



A Multilevel Analytical Placement for 3D ICs

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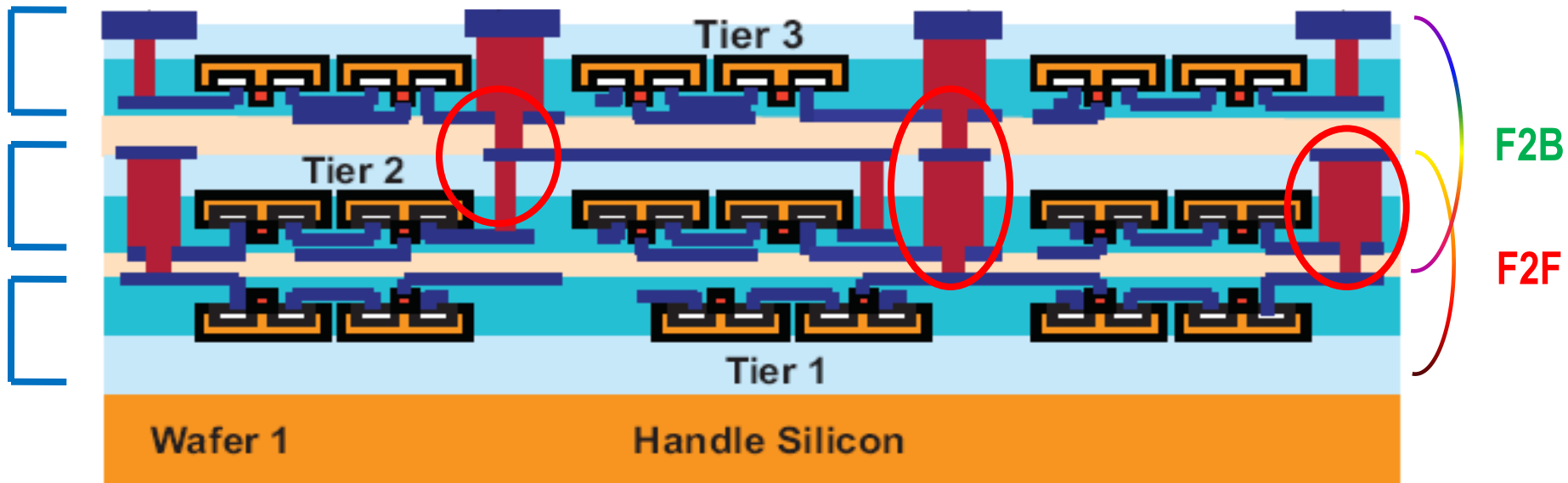
This work is partially supported by
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3D Integration

◆ Example (MIT Lincoln Lab 180nm SOI technology)

- A collection of *tiers*
- Through-silicon via (*TSV*)



Basic 3D Placement Problem

◆ Variables

- $(x_i, y_i, z_i), i=1,2,\dots,n$
- cell i is placed at (x_i, y_i) on the tier z_i

◆ Objective

- $\sum_e WL_e(x, y, z) = HPWL_{(x,y)} + \alpha_{TSV} HPWL_z$
- To minimize weighted wirelength

◆ Constraint

- no overlap between cells

Previous Works on 3D Placement

- ◆ **Force-directed method**
 - [Goplen & Sapatnekar, ICCAD'03]
- ◆ **Partitioning-based method**
 - [Goplen & Sapatnekar, DAC'07]
- ◆ **Quadratic modeling of density cost through DCT**
 - [Yan et al., Integration'09]
- ◆ **2D to 3D transformation method**
 - [Cong et al., ASPDAC'07]

Motivations

◆ 3D placement tool

- Trade-offs between wirelength and TSV
- Flexible to integrate other objective function and constraints
- High-quality and scalable

◆ To study analytical placement

Our Contributions

- ◆ **Analytical formulation with a novel density penalty function**
 - Based on multiple-tier 2D density penalty functions
 - Introduce pseudo-layers, so that minimization of penalties on tiers and pseudo tiers guarantees a legal 3D placement
- ◆ **Adaption of multilevel method**
 - Provides extra TSV reduction in addition to increasing the TSV weight
- ◆ **Improvements compared to 2D to 3D transformation**
 - (best wirelength cases) 2% shorter wirelength and 29% fewer TSV
 - (best TS via cases) 20% shorter wirelength and 50% fewer TSV

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◆ Constraint

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Weighted Wirelength

$$\blacklozenge WL_e(x, y, z) = \left(\max_{v_i, v_j \in e} |x_i - x_j| + \max_{v_i, v_j \in e} |y_i - y_j| \right) + \alpha_{TSV} \cdot \max_{v_i, v_j \in e} |z_i - z_j|$$

Weighted Wirelength

$$\blacklozenge WL_e(x, y, z) = \left(\max_{v_i, v_j \in e} |x_i - x_j| + \max_{v_i, v_j \in e} |y_i - y_j| \right)$$

2D HPWL

Weighted Wirelength

$$\blacklozenge WL_e(x, y, z) = \left(\max_{v_i, v_j \in e} |x_i - x_j| + \max_{v_i, v_j \in e} |y_i - y_j| \right) + \alpha_{TSV} \cdot \max_{v_i, v_j \in e} |z_i - z_j|$$

3D
Weighted
HPWL

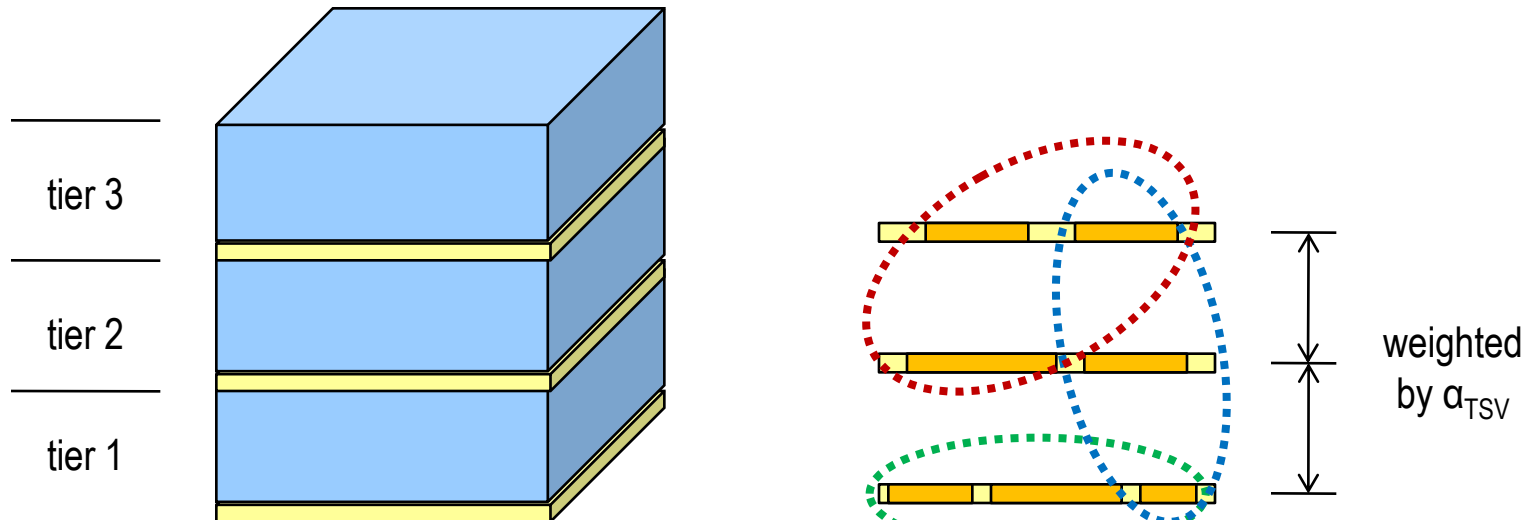
Weighted Wirelength

$$\blacklozenge WL_e(x, y, z) = \left(\max_{v_i, v_j \in e} |x_i - x_j| + \max_{v_i, v_j \in e} |y_i - y_j| \right) + \alpha_{TSV} \cdot \max_{v_i, v_j \in e} |z_i - z_j|$$

◆ Model TSV by a length of wire

■ For example [Davis et al., DTC'05]

- MIT Lincoln Lab 180 nm 3D SOI technology
- 3 μm thick TSV \approx 8 to 20 μm metal 2 wire, in terms of capacitance
- 3 μm thick TSV \approx 0.2 μm metal 2 wire, in terms of resistance

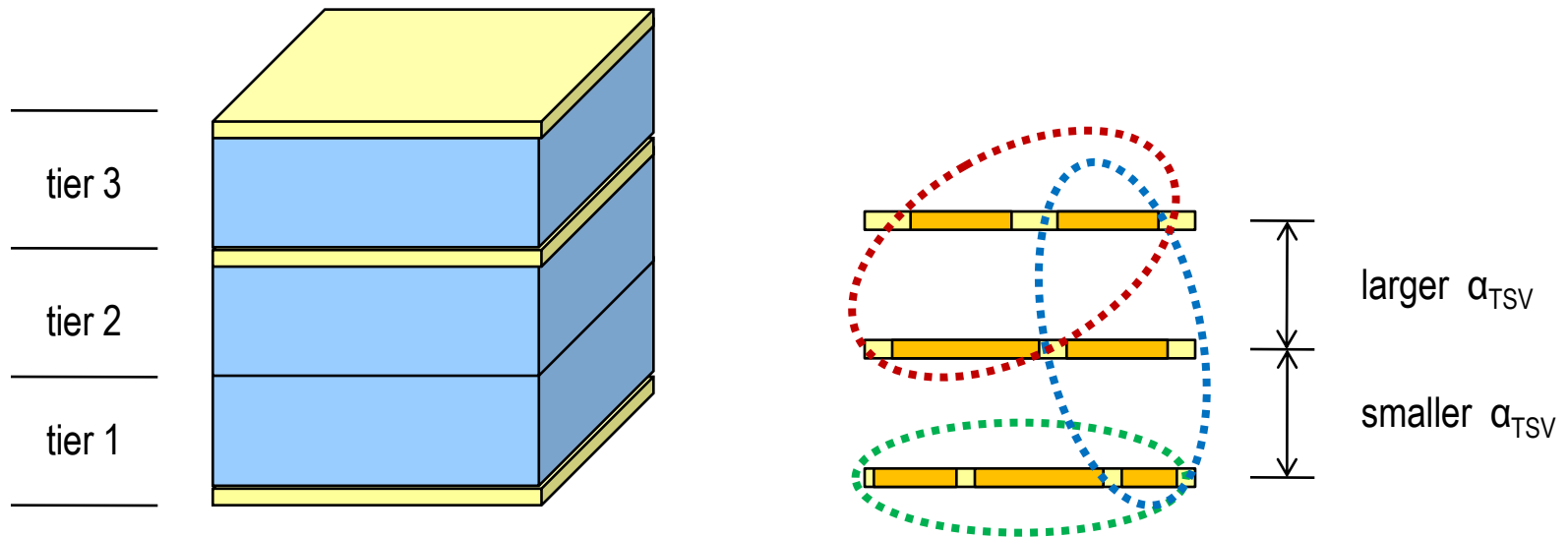


Weighted Wirelength

◆ Another case

- Tier 1 and tier 2: face-to-face
- Tier 2 and tier 3: back-to-back

◆ Different weights between tiers



Weighted Wirelength

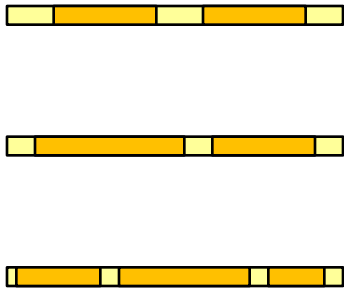
◆ Practical weighed wirelength

$$WL_e(x, y, z) = (1 + p_e) \left(\max_{v_i, v_j \in e} |x_i - x_j| + \max_{v_i, v_j \in e} |y_i - y_j| \right) \\ + (1 + q_e) \cdot \alpha_{TSV} \cdot \max_{v_i, v_j \in e} |z_i - z_j|$$

- Additional net weights p_e and q_e to model and optimize performance or temperature [Goplen & Sapatnekar, DAC'07]
 - It is a convex function w.r.t. (x, y, z)
- ◆ Such weighted wirelength is the form of objective function in the 3D placement problem formulation

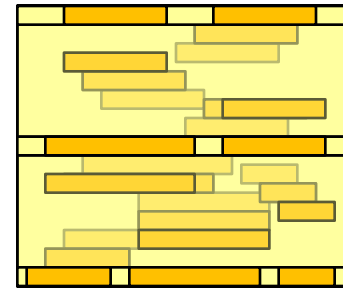
Analytical Engine

◆ Discrete tier assignment



discrete
(legalized solution)

◆ Relaxed tier assignment



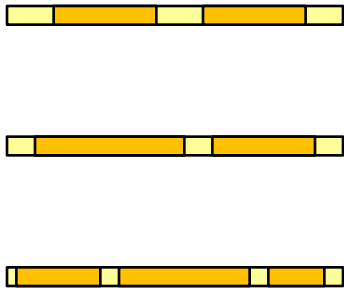
relaxed
(intermediate solution)

◆ Variables

- $(x_i, y_i, z_i), i=1, 2, \dots, n$
- cell i is placed at (x_i, y_i) on the tier z_i

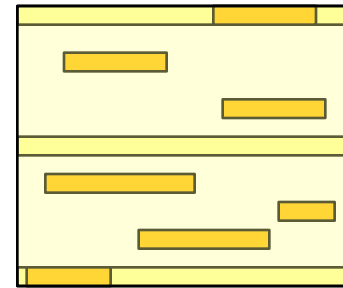
Analytical Engine

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discrete
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◆ Relaxed tier assignment



relaxed
(intermediate solution)

◆ Formulate 3D placement problem as continuous optimization

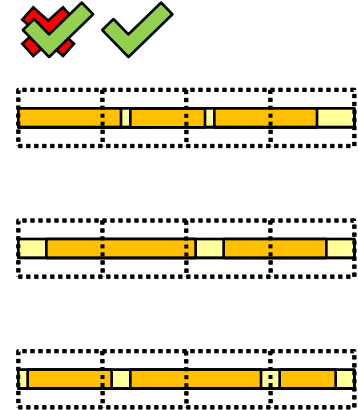
minimize $\sum_e WL_e(x, y, z)$

subject to (no overlap between cells)

Non-overlap Constraints

◆ Relaxed by area density constraints

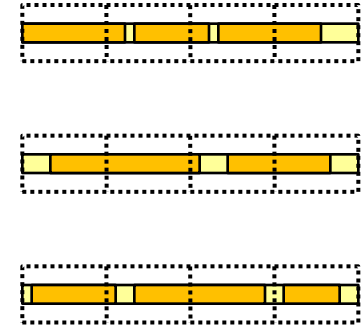
- Divide the placement region into bins
- Measure the overflow of bin area to capture cell overlaps
 - Cell overlaps in overflow bins violate density constraints
 - Cell overlaps not in overflow bins do not violate density constraints



Non-overlap Constraint

◆ Replaced by area density constraint

- Divide the placement region into bins
- Measure the overflow of bin area to capture cell overlaps



minimize $\sum_e WL_e(x, y, z)$
subject to (no overlap between cells)

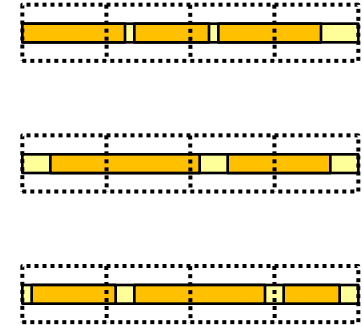


minimize $\sum_e WL_e(x, y, z)$
subject to $A_{i,j,k}(x, y, z) \leq C_{i,j,k}$
for all i, j, k

Non-overlap Constraint

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minimize $\sum_e WL_e(x, y, z)$
subject to (no overlap between cells)



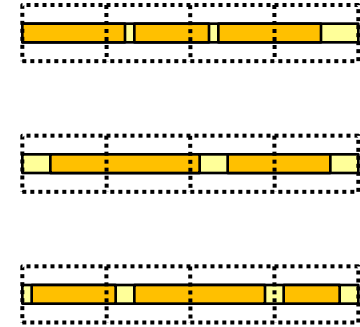
minimize $\sum_e WL_e(x, y, z)$
subject to $A_{i,j,k}(x, y, z) = C_{i,j,k}$
for all i, j, k

add **filler cells**
[Chan et al., ISPD'06]

Non-overlap Constraint

◆ Replaced by area density constraint

- Divide the placement region into bins
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minimize $\sum_e WL_e(x, y, z)$

subject to $A_{i,j,k}(x, y, z) = C_{i,j,k}$ for all i, j, k



minimize $\sum_e WL_e(x, y, z) + \frac{\mu}{2} \sum_k \sum_{i,j} (A_{i,j,k}(x, y, z) - C_{i,j,k})^2$

increase μ until overlaps are removed

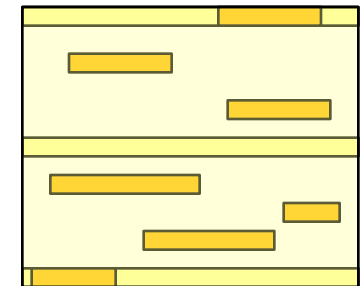
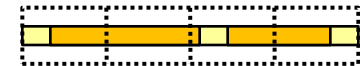
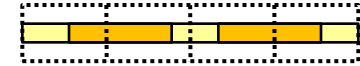
[Nam & Cong, Springer'07]
[Cong & Luo, ISPD'08]

Non-overlap Constraint

◆ Replaced by area density constraint

- Divide the placement region into bins
- Measure the overflow of bin area to capture cell overlaps

◆ Area projection to obtain bin densities from intermediate solution

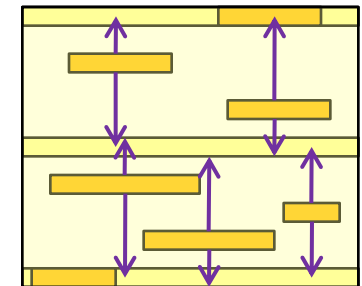
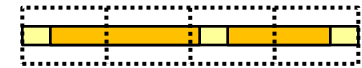
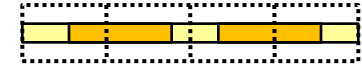


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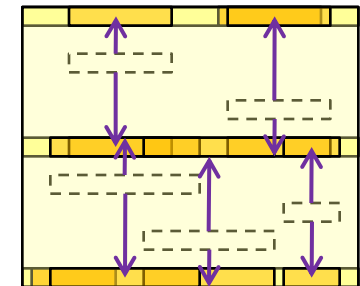
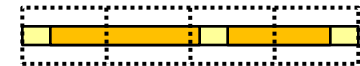
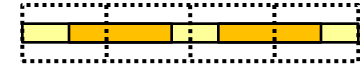


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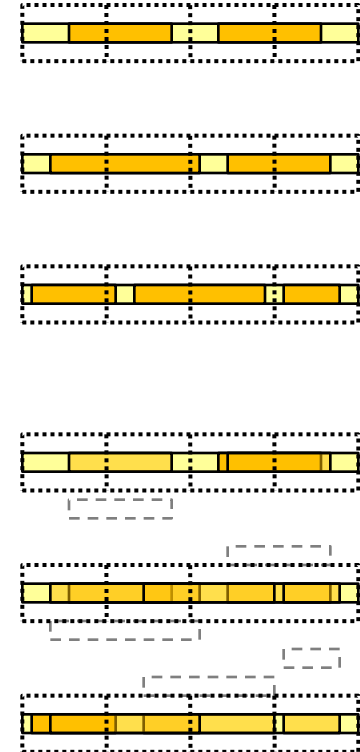


Non-overlap Constraint

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◆ Area projection to obtain bin densities from intermediate solution



Area Projection

◆ Bell-shaped function to project area

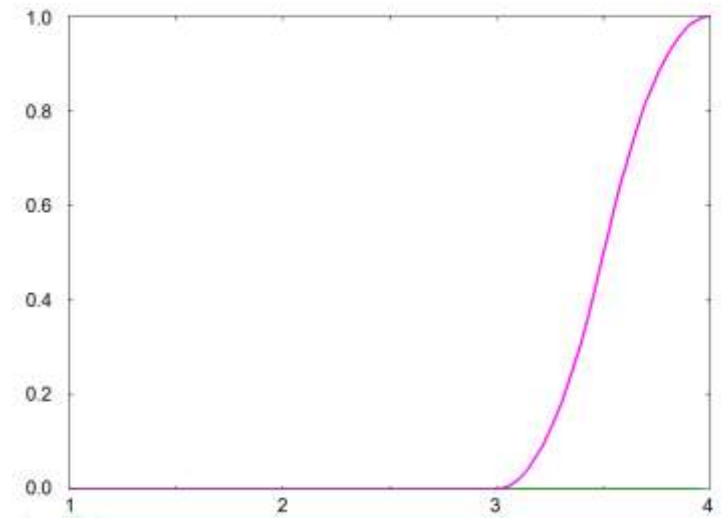
$$\eta(k, z) = \begin{cases} 1 - 2(z - k)^2 & |z - k| \leq 1/2 \\ 2(|z - k| - 1)^2 & 1/2 < |z - k| \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

$\eta(k, z)$ - The projection ratio
from “tier z” to tier k

$\eta(1, z)$ $\eta(2, z)$ $\eta(3, z)$ $\eta(4, z)$

$$A_{i, j, k}(x, y, z)$$

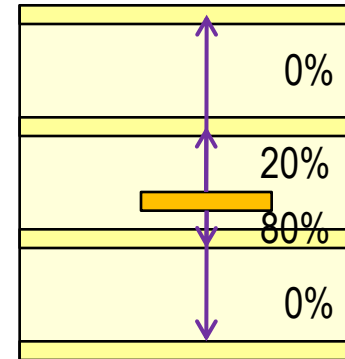
$$= \sum_{v \in V} A_{i, j}(x_v, y_v) \cdot \eta(k, z_v)$$



Area Projection

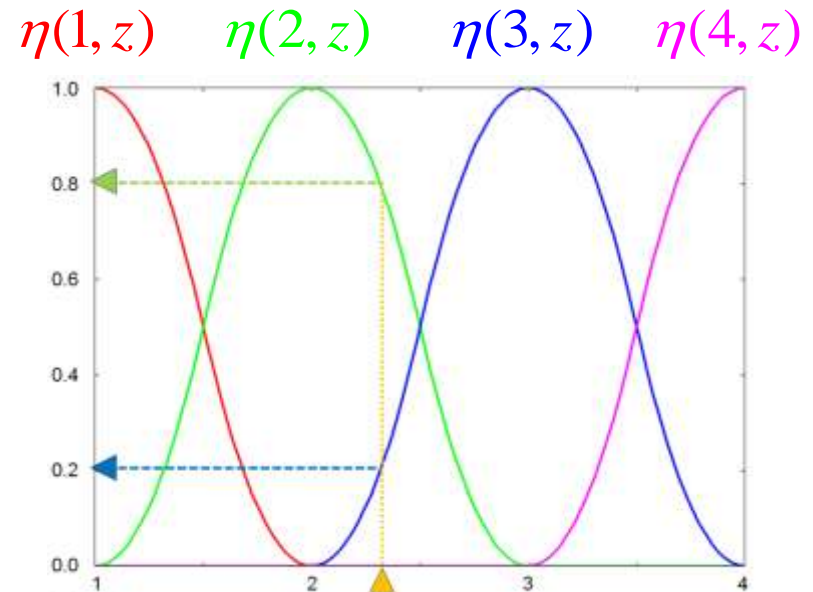
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◆ An Example

- Intermediate placement of a cell at “tier 2.316”
- Projects 0% area to tier 1
- Projects 80% area to tier 2
- Projects 20% area to tier 3
- Projects 0% area to tier 4



Area Projection

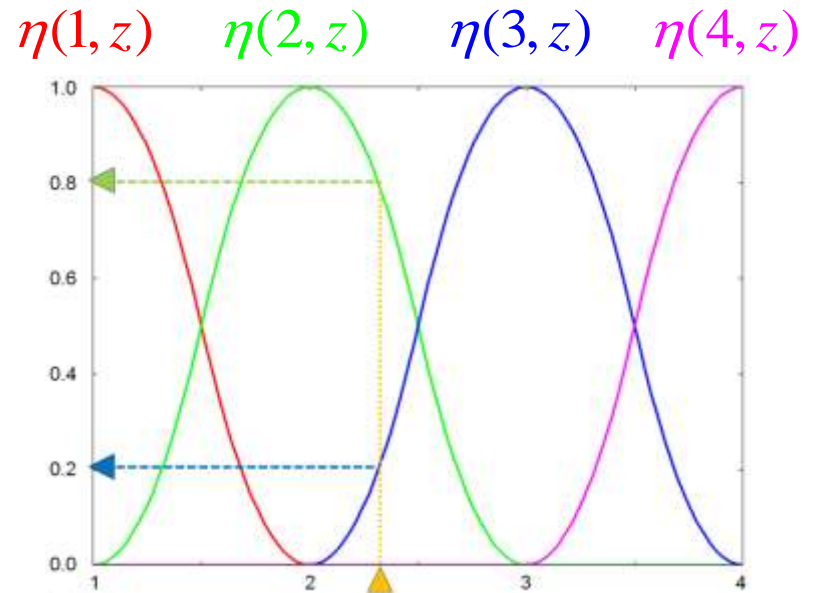
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$\eta(k, z)$ - The projection ratio from “tier z” to tier k

◆ An Example

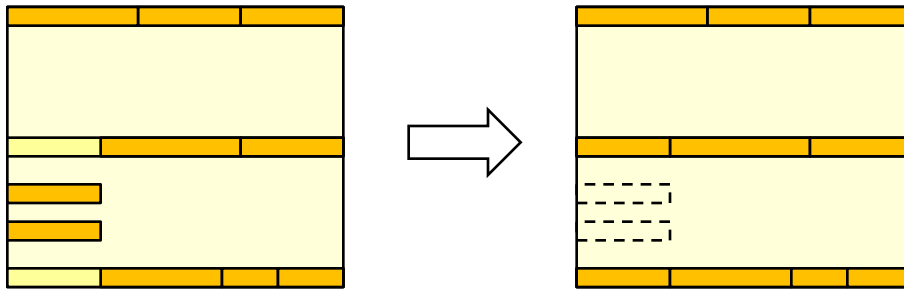
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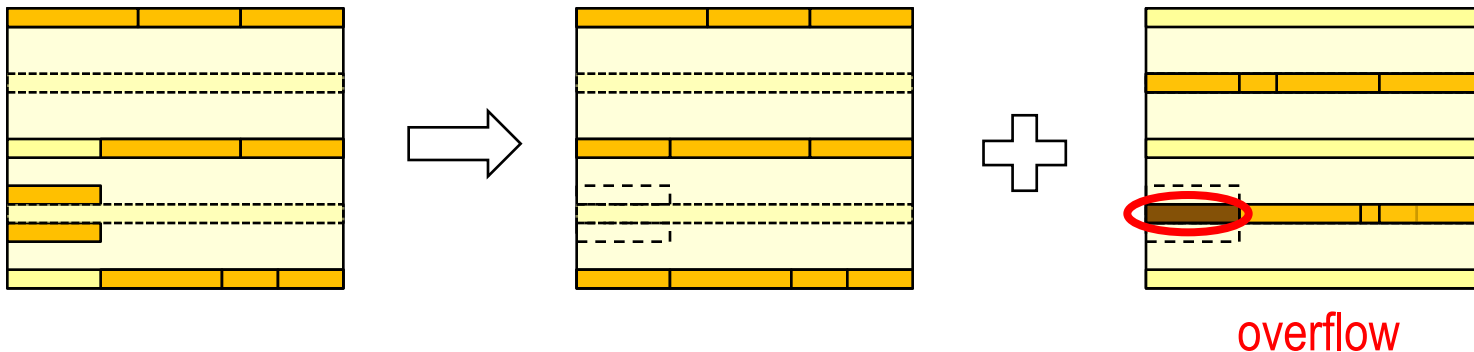
Equivalence to Non-overlap Constraint

◆ Area projection to tiers is not enough

- Counter example: projected area failed to capture illegality



◆ Solution: area projection on pseudo-tiers



Equivalence to Non-overlap Constraint

◆ Theorem: (x,y,z) satisfy the constraints

$$\begin{cases} A_{i,j,k}(x, y, z) = C_{i,j,k} \\ A'_{i,j,k}(x, y, z) = C'_{i,j,k} \end{cases} \quad \text{for all } i, j, k$$

if.f. (x,y,z) is a legal placement (no overlaps)

** after adding filler cells

Equivalence to Non-overlap Constraint

◆ **Theorem: (x,y,z) is a minimizer of the function:**

$$\frac{\mu}{2} \sum_k \sum_{i,j} (A_{i,j,k}(x, y, z) - C_{i,j,k})^2$$
$$+ \frac{\mu}{2} \sum_k \sum_{i,j} (A'_{i,j,k}(x, y, z) - C'_{i,j,k})^2$$

if.f. (x,y,z) is a legal placement (no overlaps)

**** after adding filler cells**

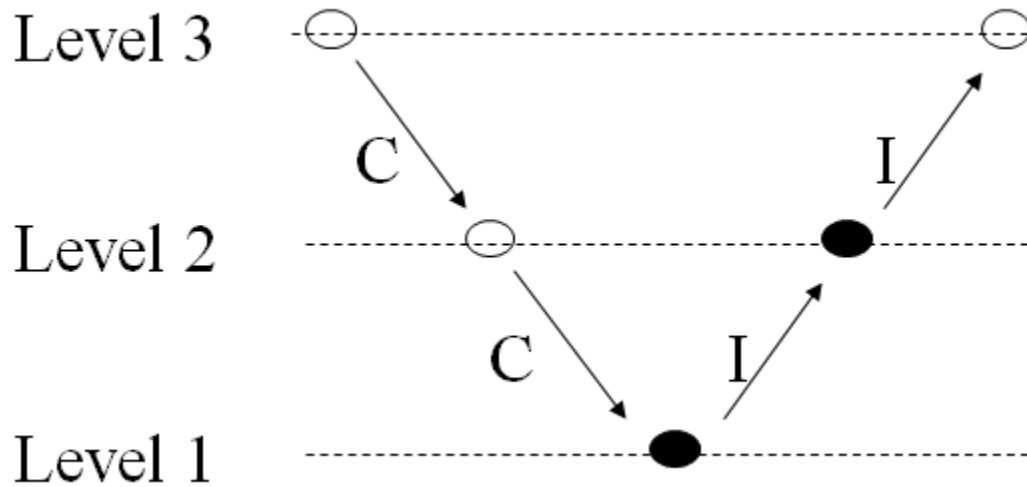
Analytical Engine

◆ minimize
$$\sum_e WL_e(x, y, z) + \frac{\mu}{2} \sum_k \sum_{i,j} (A_{i,j,k}(x, y, z) - C_{i,j,k})^2 + \frac{\mu}{2} \sum_k \sum_{i,j} (A'_{i,j,k}(x, y, z) - C'_{i,j,k})^2$$

increase μ until overlaps are removed

- $A_{i,j,k}(x, y, z)$: area projected in bin (i,j) of tier k
- $C_{i,j,k}$: area capacitance on tier k
- $A'_{i,j,k}(x, y, z)$: area projected in bin (i,j) of pseudo-tier k
- $C'_{i,j,k}$: area capacitance on pseudo-tier k

Multilevel Framework



- Level at which analytical engine is applied
- C Coarsening
- I Interpolation

Experimental Results (1/2)

◆ Comparison of trade-off curves (ibm13)

- 19% shorter WL

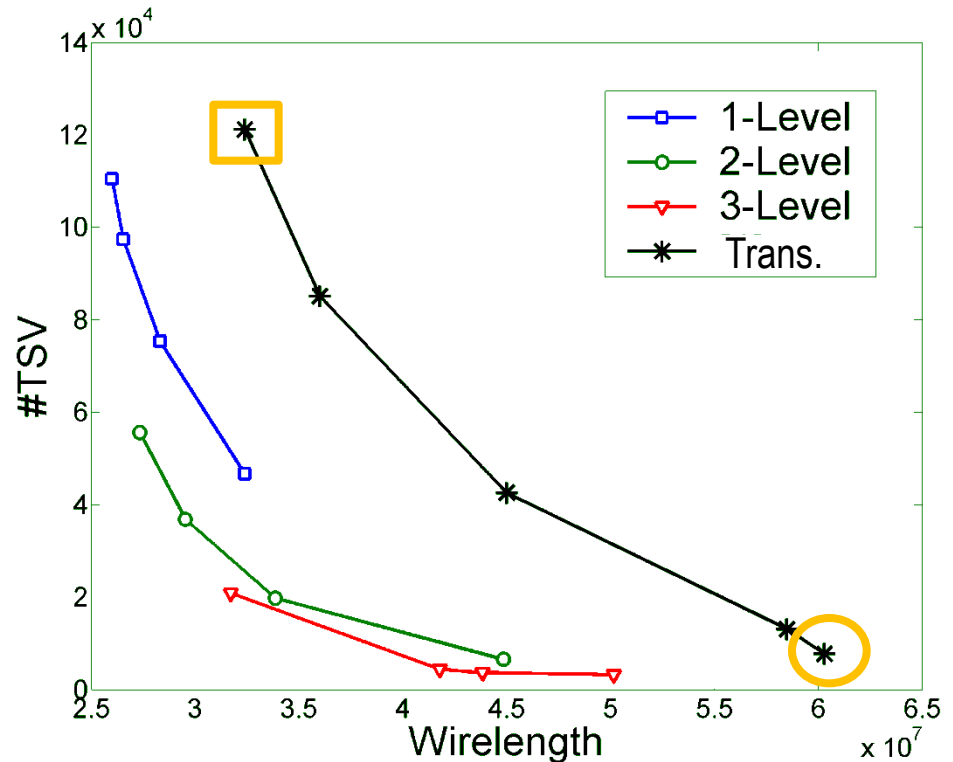
- 9% fewer TSV

- than 

- 15% shorter WL

- 43% fewer TSV

- than 



(consistent behavior on other circuits)

Experimental Results (2/2)

◆ The ability to reduce the TSV number

Circuit	3-Level Placement			4-way Mincut	
	GP WL (x 10 ⁷)	DP WL (x 10 ⁷)	#TSV (x 10 ³)	cutsizes (x 10 ³)	#TSV (x 10 ³)
ibm01	0.39	0.39	0.92	0.35	0.42
ibm03	0.92	0.91	2.10	1.28	2.02
ibm04	1.36	1.31	2.01	1.41	1.89
ibm06	1.67	1.62	2.60	1.63	2.63
ibm07	2.79	2.70	2.72	2.13	2.97
ibm08	2.99	2.89	2.83	2.02	2.60
ibm09	2.36	2.29	2.47	1.35	1.90
ibm13	5.02	4.89	3.20	1.62	2.21
ibm15	12.05	11.40	8.27	4.20	6.19
ibm18	18.36	17.37	9.82	2.95	4.68
geo-mean	2.66	2.58	2.95	1.61	2.29

Summary

◆ Non-overlap constraints

- Handled by a novel area projection method
- Pseudo-tiers added for equivalence to non-overlap constraints

◆ Multilevel framework

- Effective to reduce TS via number

◆ Trade-offs between WL and #TSV

- **12% shorter WL and 29% fewer TSV**
 - Compared to the 2D to 3D transformation method with best WL
- **20% shorter WL and 50% fewer TSV**
 - Compared to the 2D to 3D transformation method with best TSV



Thank you!