#### On-Chip Power Network Optimization with Decoupling Capacitors and Controlled-ESRs

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# Outline of Optimization with Decap and Controlled-ESR

- Introduction
  - Existing works add decap to reduce noise
  - Controlled-ESR is shown to be effective to suppress the resonance
- Power network model with controlled-ESR
- Problem statement
  - Power network noise considering overshoot
  - Formulation
- Revised sensitivity computation
  - Sensitivity computation with merged adjoint network
  - Revised sensitivity computation considering voltage overshoot
- SQP based optimization
- Experimental results
- Conclusions

# **Our Contributions**



- We propose to allocate decaps and controlled-ESRs simultaneously to suppress the resonance and reduce SSN of power network.
- We consider both voltage drop and overshoot for voltage violation. Derive revised sensitivity.
- An optimization formulation with the objective function of minimizing the voltage violation area and a constraint of decap budget is presented, and solved with an efficient SQP algorithm.

# Power Network Model with Controlled-ESR





# Voltage Variation Analysis with Circuit State Equation

From KCL and KVL, we have the circuit state equation:

$$\begin{bmatrix} C & 0 \\ 0 & L \end{bmatrix} \begin{bmatrix} \dot{v} \\ \dot{i} \end{bmatrix} = \begin{bmatrix} -G & -E \\ E^T & -R \end{bmatrix} \begin{bmatrix} v \\ \dot{i} \end{bmatrix} + BU \quad (1)$$

$$C\dot{x} = Ax + Bu \qquad (2)$$

which is denoted to be:

If add extra decap riangle C and controlled-ESR riangle A, solution *x* will be updated by riangle x, so (2) becomes:

 $(C + \Delta C)(\dot{x} + \Delta \dot{x}) = (A + \Delta A)(x + \Delta x) + Bu$  (3) s:

By subtracting (2) from (3):  $(C + \Delta C)\Delta \dot{x} = (A + \Delta A)\Delta x + (\Delta Ax - \Delta C\dot{x})$  (4)

The solution of (4) is:

$$\Delta x = e^{\tilde{C}^{-1}\tilde{A}(t-t_{0})} \Delta x_{0} + \int_{t}^{t} e^{\tilde{C}^{-1}\tilde{A}(t-\tau)} \tilde{C}^{-1}\tilde{U}(\tau) d\tau$$
(5)

where:  $\tilde{C} \equiv C + \Delta C$ ,  $\tilde{A} \equiv A + \Delta A$ ,  $\tilde{U} \equiv \Delta Ax - \Delta C\dot{x}$   $e^{\tilde{A}} \equiv I + \tilde{A} + \frac{A^2}{2!} + \frac{A^3}{3!} + \dots$ 

# Effect of Controlled-ESR on reducing the noise



# Power Network Noise Considering Overshoot





# **Problem Formulation**

- Objective function:
  - Min  $\sum_{j=1}^{N} g_j$
- Constraints:
  - (1) Voltage response satisfies the circuit equation with given stimulus;
  - (2) Total decap budget:  $\sum_{i=1}^{M} c_i \leq Q$
  - (3) Space constraint for each decap location:  $0 \le c_i \le c_{\max i}$
  - (4) Space constraint for each controlled-ESR location:

 $0 \leq CtrlESR_i \leq CtrlESR_{\max i}$ 

# Sensitivity Computation with Merged Adjoint Network

The sensitivity  $s_{ij}$  is defined to be the contribution of decap added at node *i* to remove violation at node *j*:

The merged adjoint sensitivity is defined to be the contribution of decap added at node *i* to remove the violation for all nodes.

The merged adjoint network has a current source  $u(t-t_s)-u(t-t_e)$ applied at every node *j* 

Merged adjoint sensitivity is calculated with

$$s_i = \sum_{j=1}^N s_{ij} = \int_0^T (\tilde{v}_{i,all}(T-t)) \times \dot{v}_i(t) dt, (i = 1, 2, ..., M)$$



 $s_{ij} = \frac{\partial g_j}{\partial c_i}$ 

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#### **Revised Sensitivity Computation Considering Overshoot**

We denote the port currents and voltages by vectors  $I_p$  and  $V_p$ . Denote the nonsource branch currents and voltages by vectors  $I_b$  and  $V_b$ . From Tellegen's theorem, we have

We set all voltage sources in the adjoint network to zero and apply a current source for each violation node:

 $\int_{0}^{T} \left[ -\hat{i}_{p}(\tau) \Delta v_{p}(t) + \hat{v}_{p}(\tau) \Delta i_{p}(t) \right]_{\tau=T-t}^{\dagger} dt$  $- \int_{0}^{T} \left[ \hat{i}_{p}(\tau) \Delta v_{p}(t) + \hat{v}_{p}(\tau) \Delta i_{p}(t) \right]_{\tau=T-t} dt$ 

$$= \int_{0} [\hat{i}_{b}(\tau) \Delta v_{b}(t) + \hat{v}_{b}(\tau) \Delta i_{b}(t)]_{\tau=T-t} dt$$

$$\Delta g = \int_{0}^{T} \left\{ -\sum_{k=1}^{N_{v}} D_{k} [u(t-t_{sk}) - u(t-t_{ek})] \right\}_{\tau=T-t}$$

Left hand:

Right hand:

$$s_{C} = \frac{\Delta g}{\Delta C} = \int_{0}^{T} -[\hat{v}_{c}(\tau)\dot{v}_{c}(t)]_{\tau=T-t}dt \qquad s_{R} = \frac{\Delta g}{\Delta R} = \int_{0}^{T} [\hat{i}_{R}(\tau)\dot{i}_{R}(t)]_{\tau=T-t}dt$$

 $\mathbf{M}$ 



# **SQP Based Optimization**

#### Algorithm for the SQP based optimization:

1. Select the intrinsic capacitance and controlled-ESR to be the initial solution  $X^{(0)}$ .

2. Simulate the power network circuit, and compute the sensitivity as gradient using the revised method.

3. Use the gradient to approximate the problem with a linearly constrained QP subproblem at  $X^{(t)}$ .

- 4. Solve for the step size  $d^{(t)}$  to move.
- 5. If meet with termination condition, stop;

Else, let  $X^{(t+1)} = X^{(t)} + d^{(t)}$ .

6. Increase *t* and return to step 2.

## **A Simple Case**



- Initial values:
  - R = 1 ohm and L=1 nH. Decap=0.01 nF, controlled-ESR = 1.0e-4 ohm.
  - *Vdd* is 1V, and the allowable voltage drop is 0.05V.
- Constraints:
  - Maximum allowable decap at each node to be 0.1 nF,
  - Total decap should not exceed 0.2 nF,
  - Maximum allowable controlled-ESR at each node is 0.2 Ohm
- Without optimization: The overall noise is 193.7 V\*ps.
- Optimize with decap only:
  - Decap at each node are: 0.1 nF, 0.09 nF, and 0.01 nF.
  - The noise after optimization is 6.3 V\*ps.
- Optimize with both decap and controlled-ESR:
  - Controlled-ESR values at each node are: 0.2 Ohm, 2.77e-2 Ohm, and 1.0e-4 Ohm.
  - The noise is further reduced to be 5.3 V\*ps.
  - The controlled-ESR improves the noise by 15.9%.

# **Experimental Results**



#### Table I. Effect of considering voltage overshoot

Circuit	# Node	Consider voltage drop only		Consider both vo	ltage drop and overshoot	Noise underestimation due
		Noise (V*ps)	# Violation node	Noise (V*ps)	# Violation node	to neglecting overshoot
CKT1	858	306.7	46	324.8	46	5.6%
CKT2	1794	7406.3	325	8127.8	347	8.9%
CKT3	2006	5111.3	309	5324.9	309	4.0%
CKT4	3634	9770.1	268	10049.6	268	2.8%
CKT5	8330	5608.1	2470	5829.1	2470	4.0%
CKT6	14852	31420.8	2243	32477.3	2243	3.4%

• The noise is the voltage violation area and the number of violation nodes.

- Total noise is on average underestimated by 4.8% due to neglecting the voltage overshoot.
- The number of violation nodes is almost the same for both cases.

# **Experimental Results**



Table II. Comparison among three methods for the minimization of power network noise

	Evenly allocate the decaps		Allocate decaps only with		Allocate both decaps and controlled-ESRs with			
Circuit			the SQP-based method		the SQP-based method			
	Noise	# Violation	Noise	# Violation	Noise	# Violation	CPU time	Noise reduction compared
	(V*ps)	node	(V*ps)	node	(V*ps)	node	(s)	to allocating decaps only
CKT1	229.5	20	113.4	23	82.1	16	26.2	27.6%
CKT2	6137.1	156	2538.0	104	2023.4	47	172.8	20.3%
CKT3	4597.9	141	2308.3	88	2077.2	78	116.7	10.0%
CKT4	8939.0	235	2212.5	96	1527.0	47	141.6	30.8%
CKT5	5352.3	1245	1694.3	617	1073.0	333	1195.2	36.7%
CKT6	26916.9	1191	6538.1	390	4853.6	204	2564.1	25.8%

• The noise (column 2, 4, 6) and the number of violation nodes (column 3, 5, 7) are reduced.

• The improvement brought by considering the controlled-ESRs is 25% on average.

•With the third method, the average allocated controlled-ESR ranges from 0.038 Ohm to 0.083 Ohm for different cases.

# Voltage Waveforms with Different Optimizations





# Relationship between Decap Budget and Noise



Larger decap budget leads to smaller noise

Tradeoff between the noise reduction and the decap investment





 Optimize power network with both decap and controlled-ESR.

- Revised sensitivity computation considering voltage overshoot.
- SQP based optimization



# Thank You! Q & A