



# **A Robustness Optimization of SRAM Dynamic Stability by Sensitivity-based Reachability Analysis**

**Yang Song, Sai Manoj P. D. and Hao Yu**

School of Electrical and Electronic Engineering,

Nanyang Technological University, Singapore

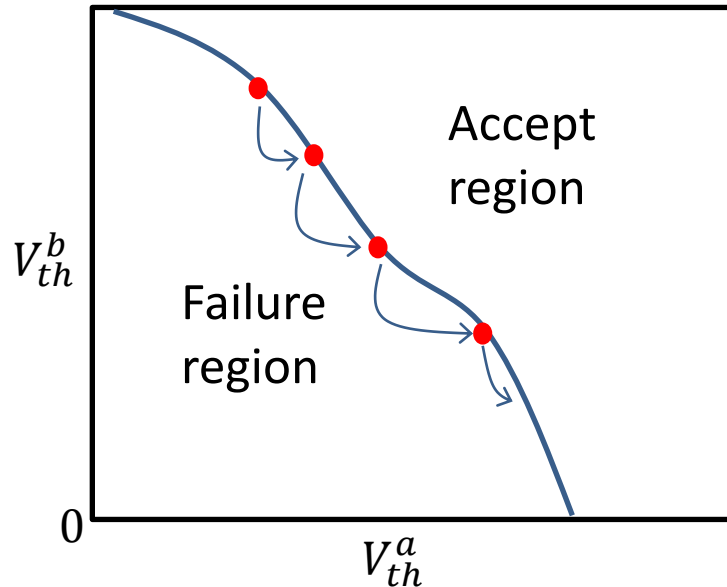
# Outline

- **SRAM Robustness Optimization Problem**
- **Reachability Analysis by Zonotope**
- **Safety Distance and Large-signal Sensitivity**
- **SRAM Reliability Optimization**
- **Experimental Results**
- **Summary**

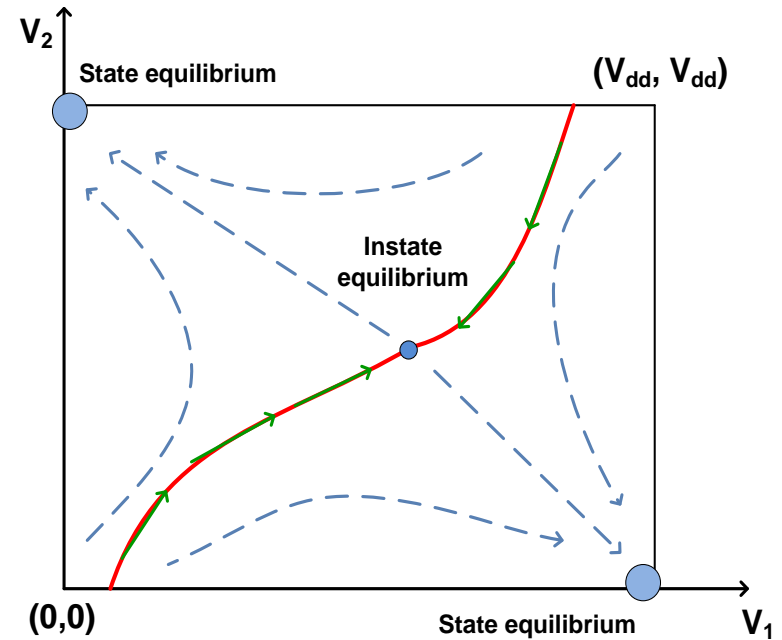
# SRAM Robustness Optimization

- **Stability verification and robustness optimization become hard for SRAM circuits**
  - Process variations, mismatch among transistors cause failures at advanced nodes
- **Static noise margin (SNM):** overestimates read failure and underestimates write failure
- **Dynamic stability margin** is adopted by deploying critical word-line pulse-width
  - How to verify and optimize?

# Previous Work of SRAM Verification



- Search for points on boundary of failure region in parameter space<sup>\*1</sup>.



- Separatrix: boundary separating two stable regions in parameter space<sup>\*2</sup>

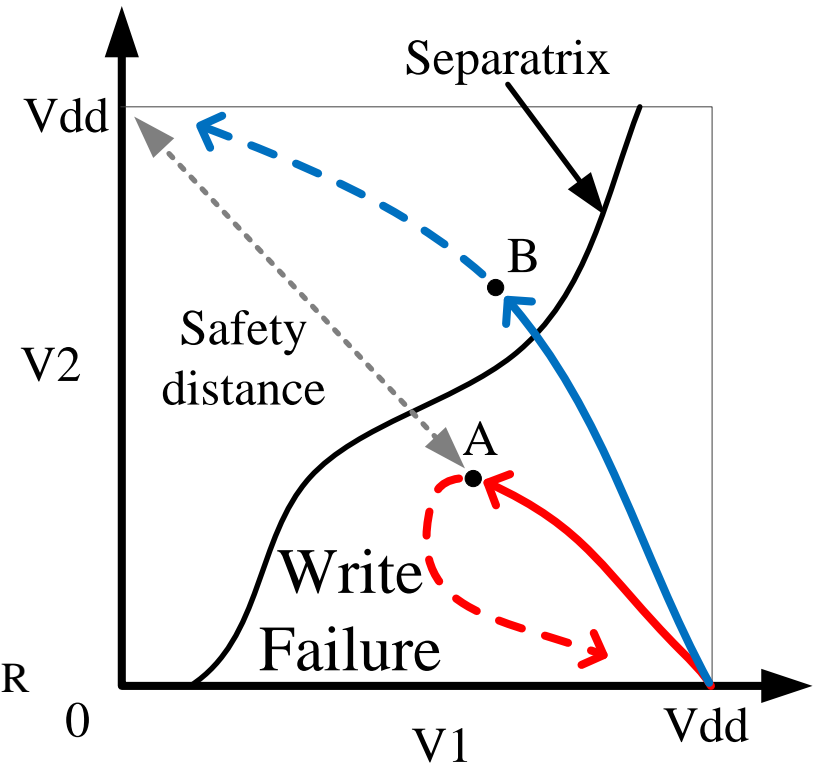
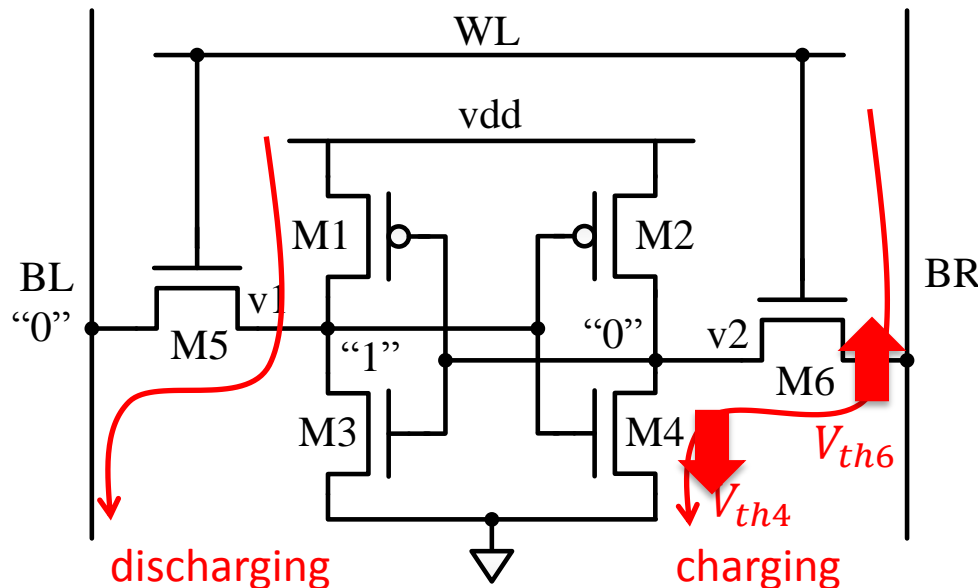
Confined in 2-D space, i.e. only two parameters considered.

<sup>\*1</sup> W. Dong and et.al. ICCAD, 2008

<sup>\*2</sup> G M Huanag and et.al. IEEE Int. BMAS Workshop, 2007

# Write Failure Analysis by Safety Distance

- Initial state  $(v1, v2) = (vdd, 0)$
- Target state  $(v1, v2) = (0, vdd)$

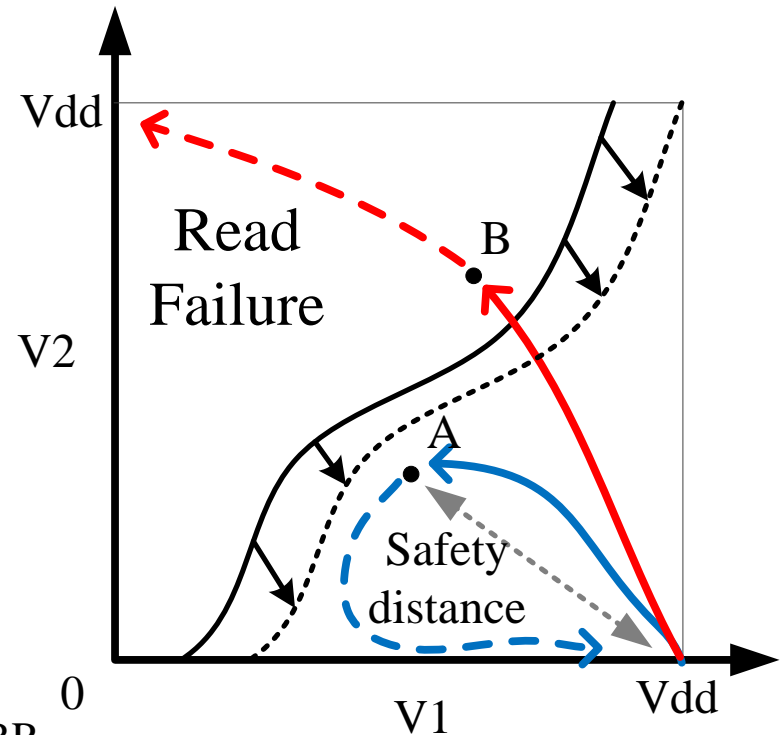
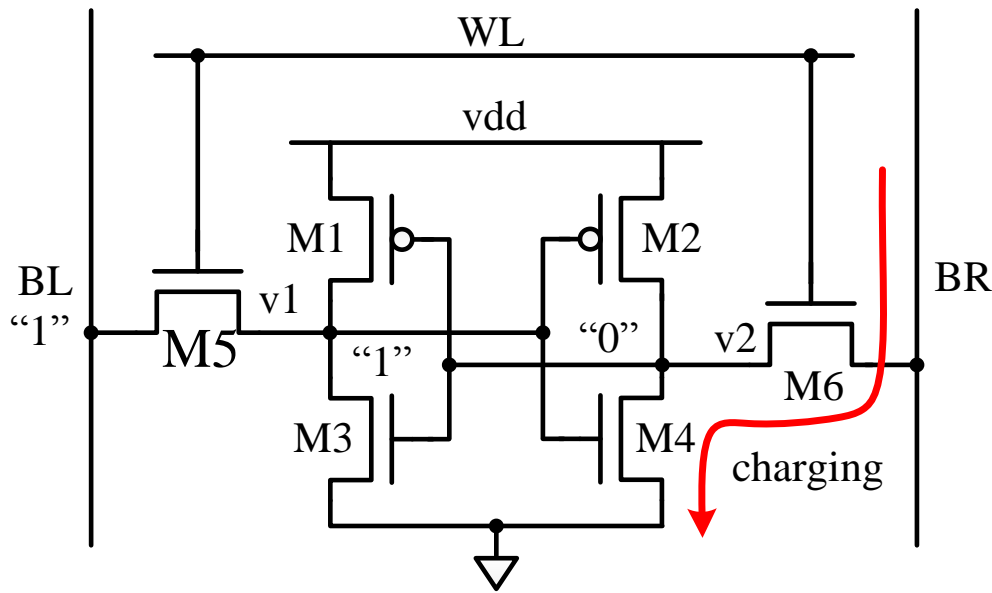


- Threshold voltage variation causes difficulty to move state point to the target state.

**Safety Distance** is the Euclidean distance in the state space between the operating and the safe state region.

# Read Failure Analysis by Safety Distance

- Initial state  $(v1, v2) = (v_{dd}, 0)$
- Target state  $(v1, v2) = (V_{dd}, 0)$
- Internal state is aimed to maintain regardless perturbation during read operation.



- Mismatch between M4 and M6
- Mismatch among M1-4

# SRAM Nonlinear Dynamics

- Nonlinear dynamics of SRAM can be defined as

$$\frac{d}{dt}q(x(t), t) + f(x(t), t) + u(t) = 0.$$

- Based on mean-value theorem,  $f(x)$  at neighborhood of the nominal point can be approximated with 2<sup>nd</sup> order residue as

$$\frac{d}{dt}q(x, t) + f(x^*, t) + u^*(t) + G(x - x^*) + \boxed{\frac{1}{2}(x - x^*)^T \cdot \frac{\partial^2 f}{\partial x^2} \big|_{x=\xi} \cdot (x - x^*)} = 0.$$

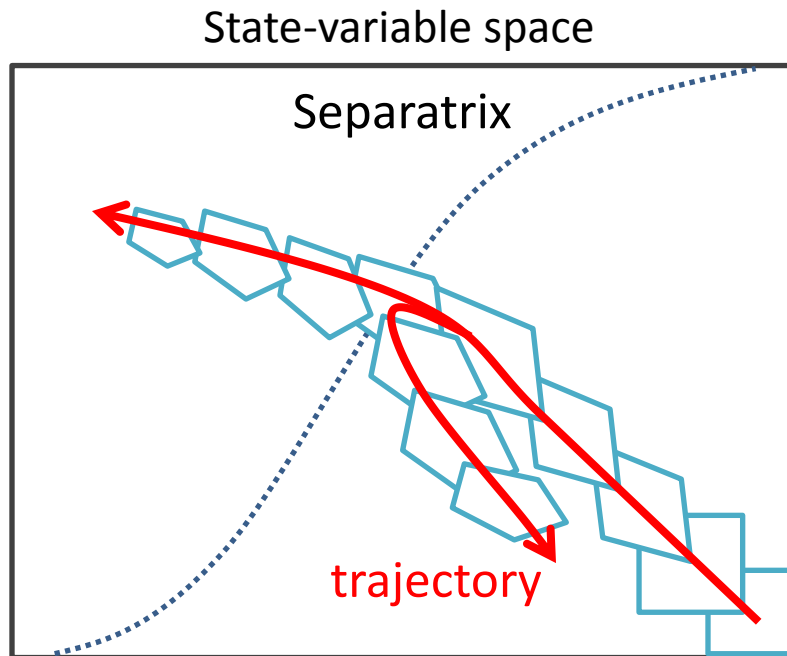
Linearization error

- Assuming  $q(x, t)$  can be decomposed

$$\begin{cases} \frac{d}{dt}q(x^*, t) + f(x^*, t) + u^*(t) = 0 & \boxed{\text{Nonlinear dynamics at nominal point}} \\ \frac{d}{dt}C\Delta x + G\Delta x + L = 0 & \boxed{\text{Linear dynamics at nominal point}} \end{cases}$$

$$C = \frac{\partial q}{\partial x} \big|_{x=x^*} \quad G = \frac{\partial f}{\partial x} \big|_{x=x^*}$$

# SRAM Verification by Reachability Analysis



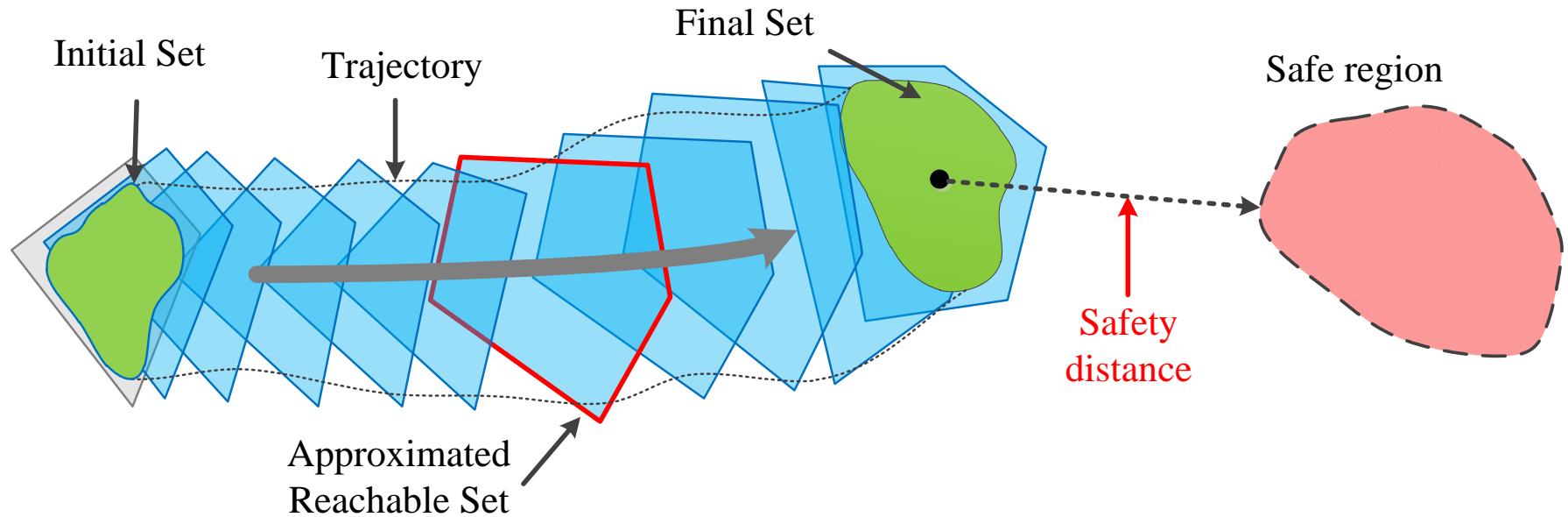
- Fast verification of SRAM nonlinear dynamics by reachability analysis
  - Variations from multiple sources considered at the same time
- For example, transconductance of multiple transistors considering variation in their widths can be added as follows

$$\Delta g_m = \frac{\partial g_m}{\partial W} \Delta W$$

$$\Delta G = \begin{pmatrix} \ddots & & & \\ & \frac{\partial g_m}{\partial W} & -\frac{\partial g_m}{\partial W} & \\ & -\frac{\partial g_m}{\partial W} & \frac{\partial g_m}{\partial W} & \\ & & & \ddots \end{pmatrix} \Delta W.$$



# Reachability Analysis: Unidirectional Zonotope

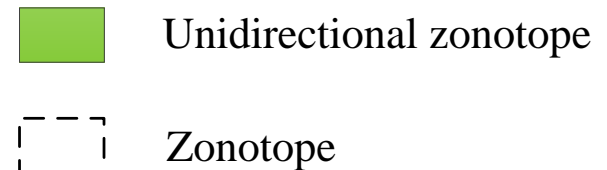
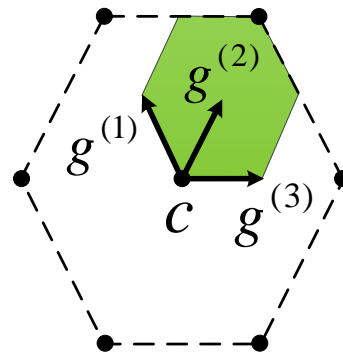


## Zonotope

*Set of points in  $n$ -dimensional polygon with generator  $g^{(i)}$*

## Unidirectional zonotope

$$z^{uni} = c + \sum_{i=1}^e \beta_i g^{(i)}, 0 \leq \beta_i \leq 1$$



# Reachability Analysis with Uncertain Parameters

$$\begin{cases} \frac{d}{dt} q(x^*, t) + f(x^*, t) + u^*(t) = 0 \\ \frac{d}{dt} C \Delta x + G \Delta x + L = 0 \end{cases}$$

SPICE-like simulator

Backward Euler method

- Backward Euler method with discretized time-step  $h$  at  $k$ -th iteration by

$$\Delta x_k^{(i)} = A^{-1} \left( \frac{C}{h} x^{(i)}_{k-1} - L_k \right)$$

Euclidean distance

$$A = \frac{C}{h} + G$$

- Considering all parameter variations as zonotope, linear Multi-step integration for reachability analysis

$$X_k = \mathcal{A}^{-1} \left( \frac{C}{h} X_{k-1} - L_k \right)$$

$$X_k = [\Delta x_k^{(1)}, \dots, \Delta x_k^{(m)}]$$

Zonotope generator matrix

# Reachability Analysis with Uncertain Parameters

- Parameter variations can be considered by the interval matrix  $A$  which is represented by a matrix zonotope.
- Zonotope matrix represented in terms of interval-valued matrices as

$$\mathbf{A} \in \left[ A^{(0)} - \sum_i |A^{(i)}|, A^{(0)} + \sum_i |A^{(i)}| \right]$$

in which each matrix zonotope generator  $A^{(i)}$  contains the variation range of a parameter.

$$A^{(i)} = \frac{\partial A^{(0)}}{\partial W} \Delta W^{(i)} = \Delta G^{(i)}$$

- The inverse of  $\mathcal{A}$  with variations is approximated as follows

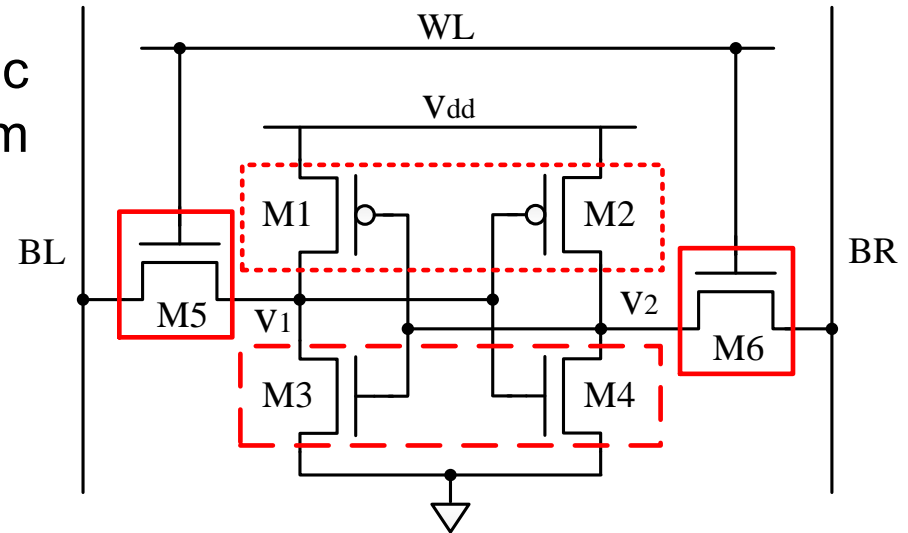
$$\mathcal{A}^{-1} = \left( (\mathcal{A}^{(0)})^{-1}, \dots, (\mathcal{A}^{(0)})^{-1} \mathcal{A}^{(m)} (\mathcal{A}^{(0)})^{-1} \right)$$

Inverse of  $\mathcal{A}^{(0)}$  is computed by LU decomposition

# SRAM Robustness Optimization Problem

- Optimization of SRAM dynamic stability is modeled as a minimum value problem.

$$\begin{aligned} & \min F(\vec{w}) \\ & S.T. W_{min} < w_i < W_{max} \end{aligned}$$



Due to symmetric structure,  
 $\vec{w} \in R^{3 \times 1}$

## Safety distance for write operation

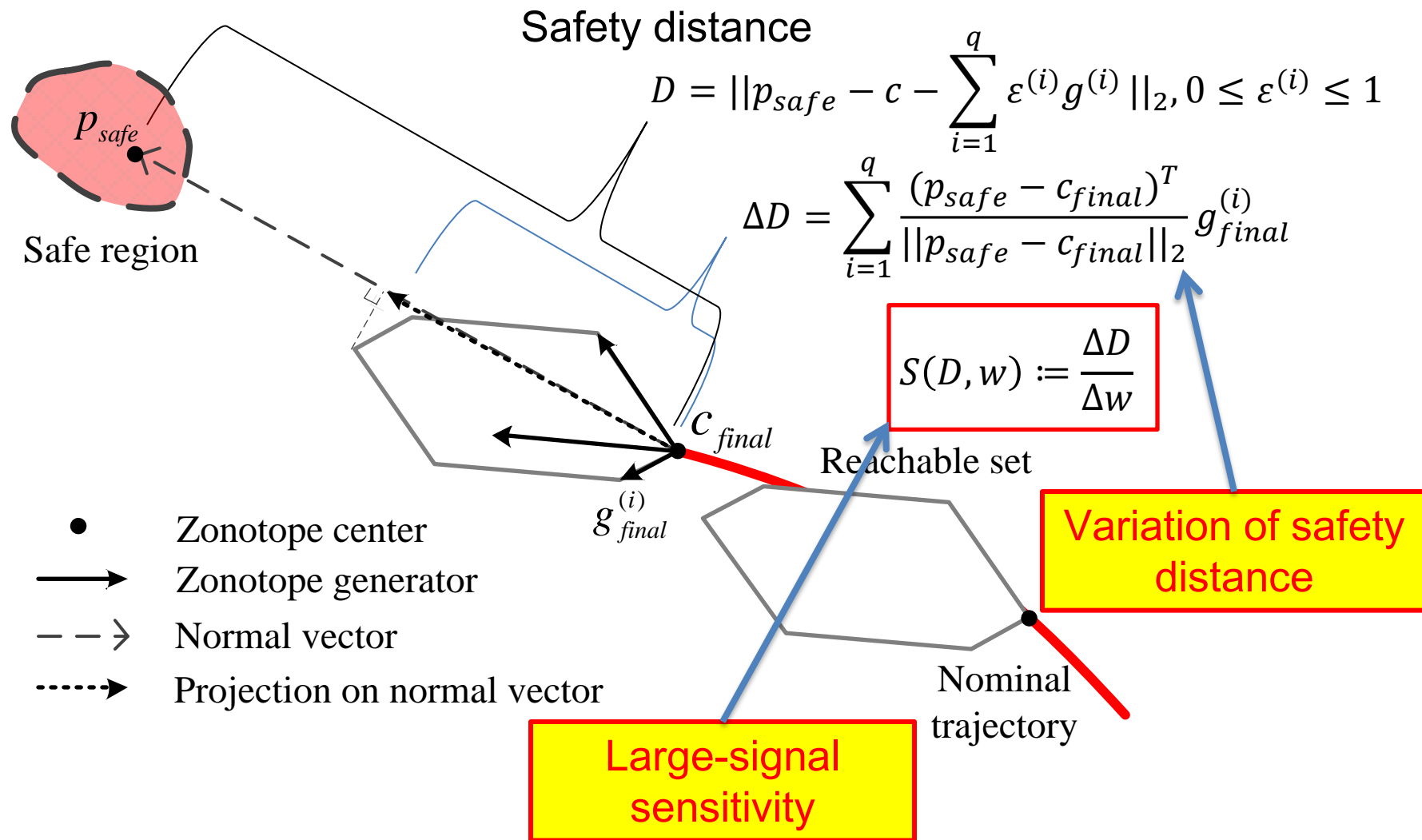
## Pulse width

operation

$$F(w) = \begin{cases} D_w(w, t_w) + D_r(w, t_r), & \text{write and read failures} \\ D_w(w, t_w), & \text{only write failure} \\ D_r(w, t_r), & \text{only read failure} \end{cases}$$

## Safety distance for read operation

# Large-signal Sensitivity of Safety Distance



# Reliability Optimization with Sensitivity of Safety Distance

- Based on the calculated sensitivity, optimization is performed
- Increment of parameter vector in direction of optimization is

$$\Delta w_k = \beta_k \underline{\rho_k} \quad \text{the gradient of obj. function}$$

- Suppose gradient is constant in the state-variable space:

$$F(w_k, t) + \Delta w_{k+1}^T \rho_k = 0$$

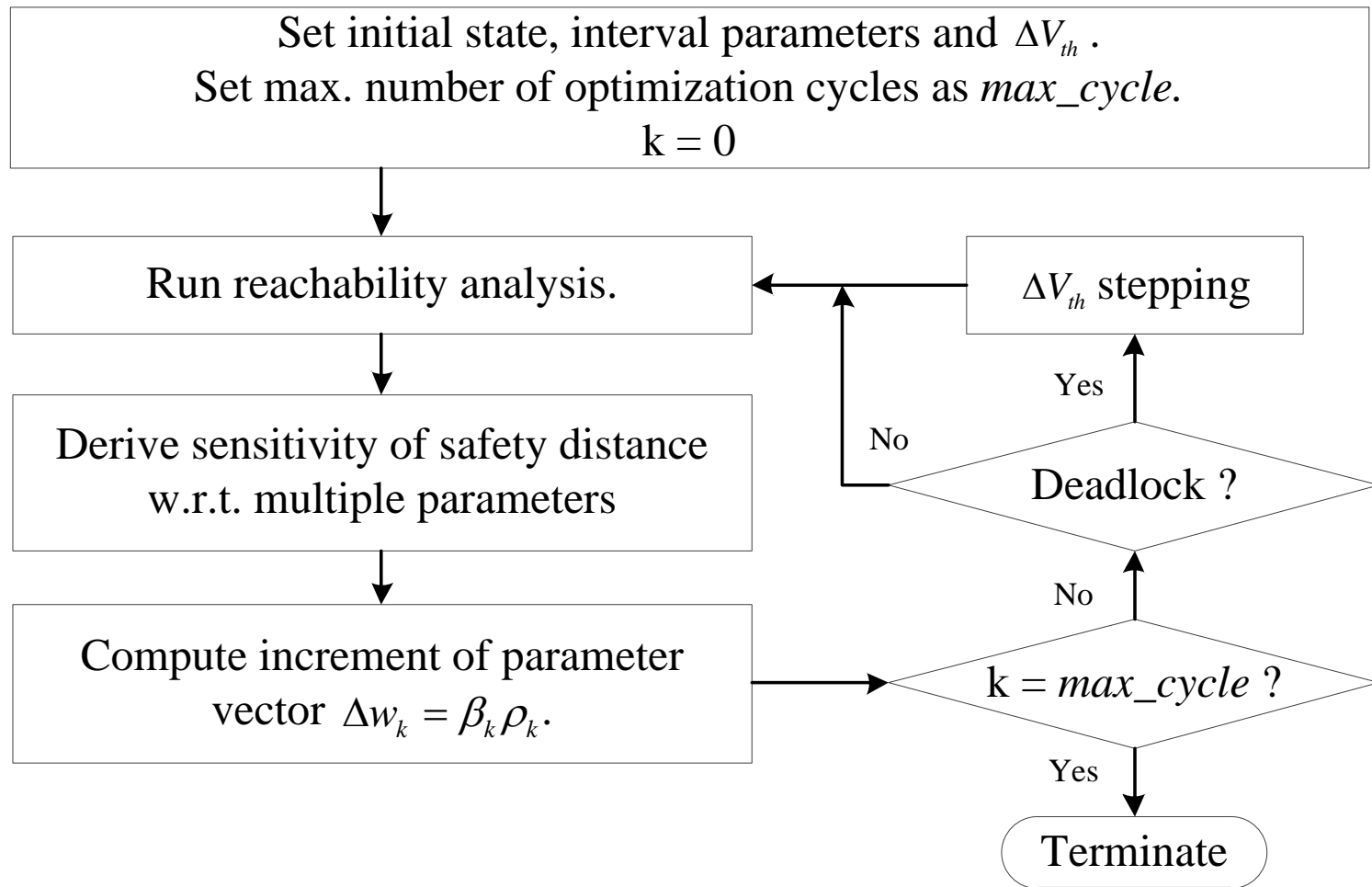
$$\beta_{k+1} = -\frac{F(w_k, t)}{\rho_k^T \rho_k}$$

- Virtually gradient decreases as safety distance becomes smaller. In other words, gradient should be smaller in the next search step.

$$\beta_{k+1} = -\gamma \frac{F(w_k, t)}{\rho_k^T \rho_k}, \quad 0 < \gamma < 1$$

Use empirical factor  $\gamma$  to modulate step size.

# SRAM Robustness Optimization Flow



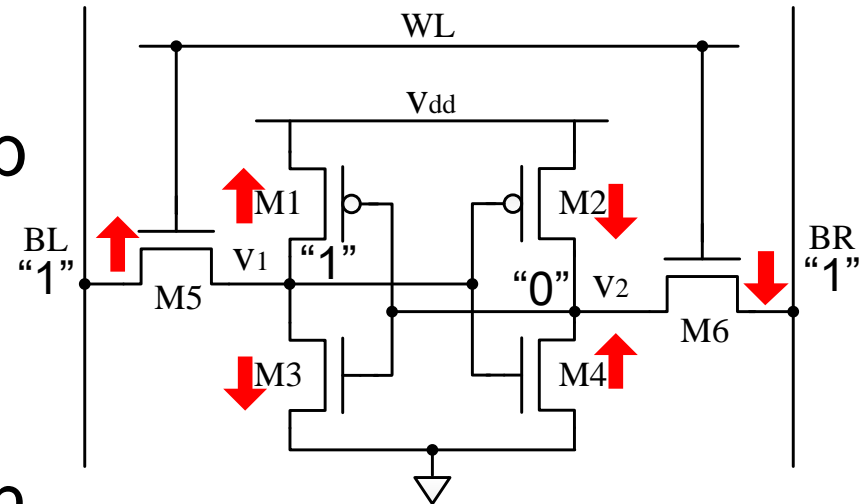
# Experimental Results

- Implemented in Matlab Platform

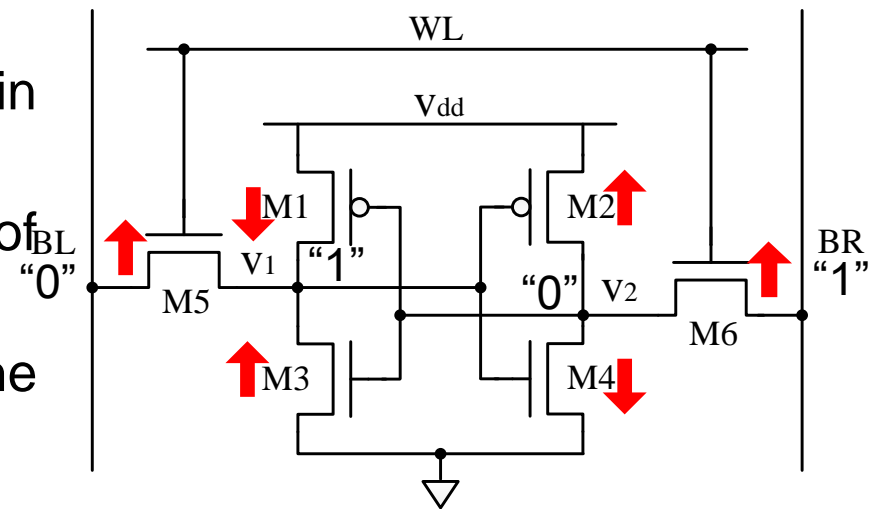
- Core i5 3.2GHz processor
- 8GB memory

- Preset simulation parameters

- Transistor width varies within  $[100, 600]nm$
- Relative standard deviation of  $V_{th} = 10\%$ .
- Optimization is performed for the most adverse situations.



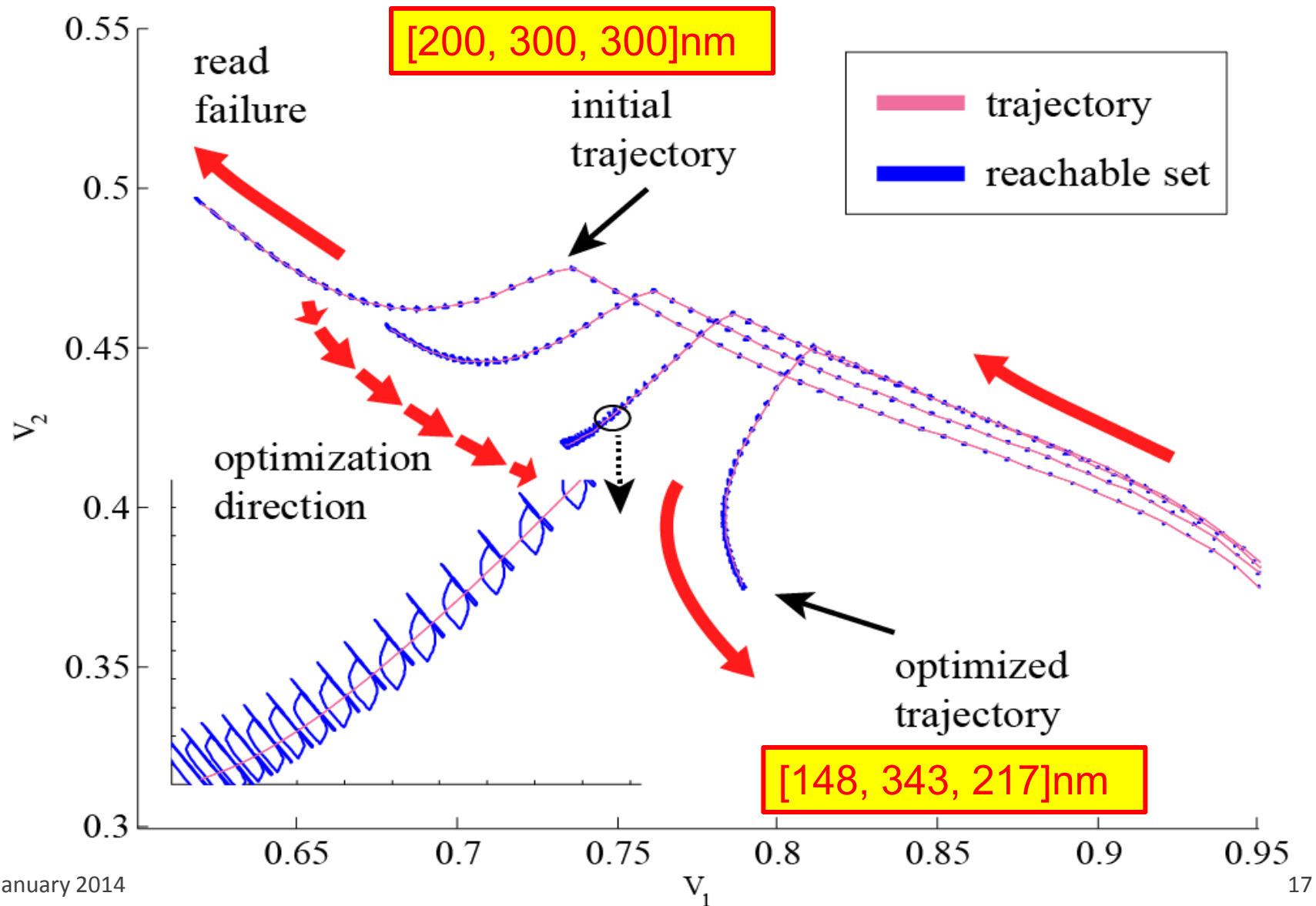
Threshold variations for read operation



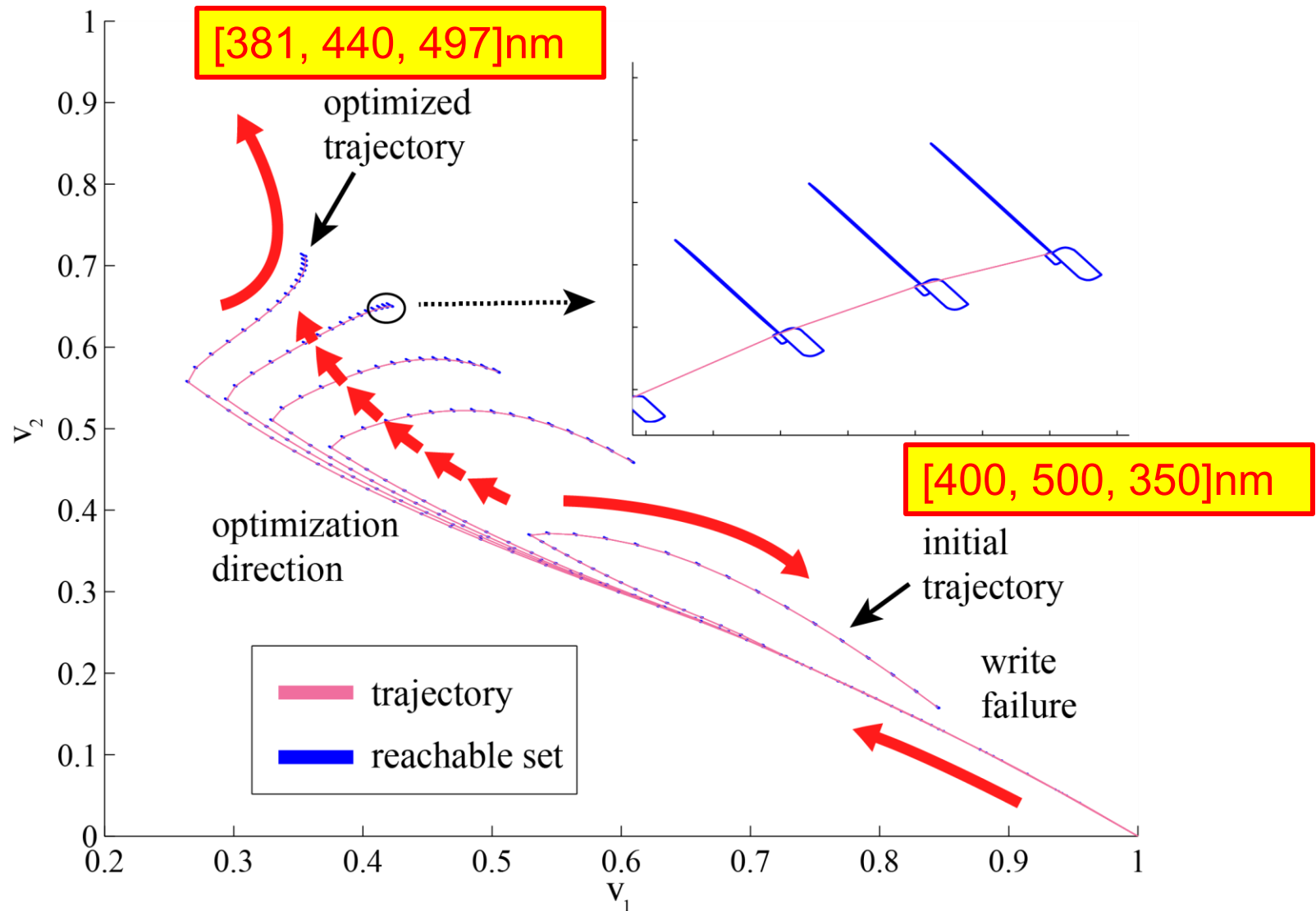
Threshold variations for write operation



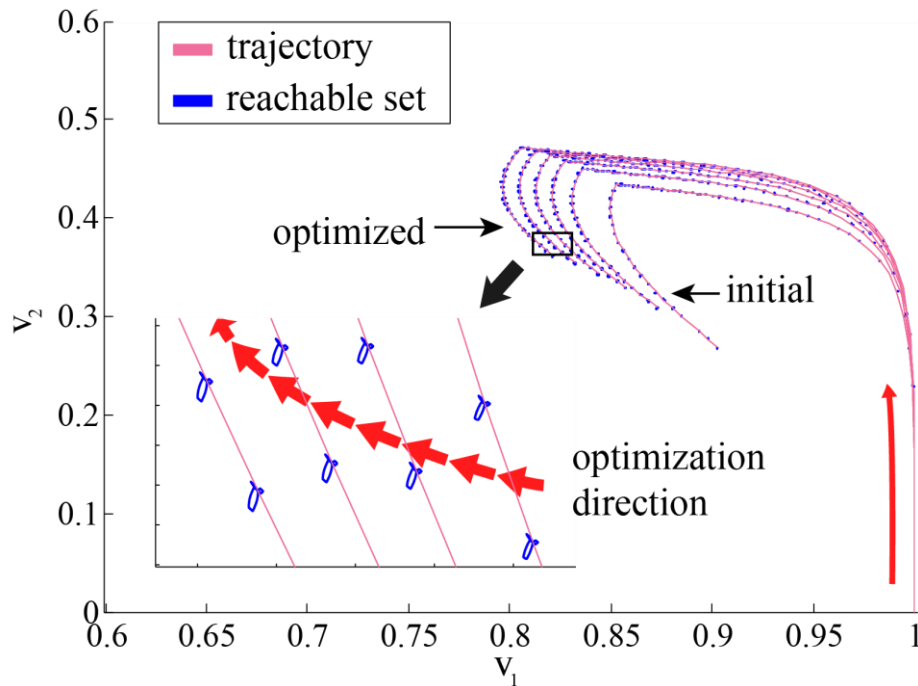
# Optimization of Read Failure



# Optimization of Write Failure

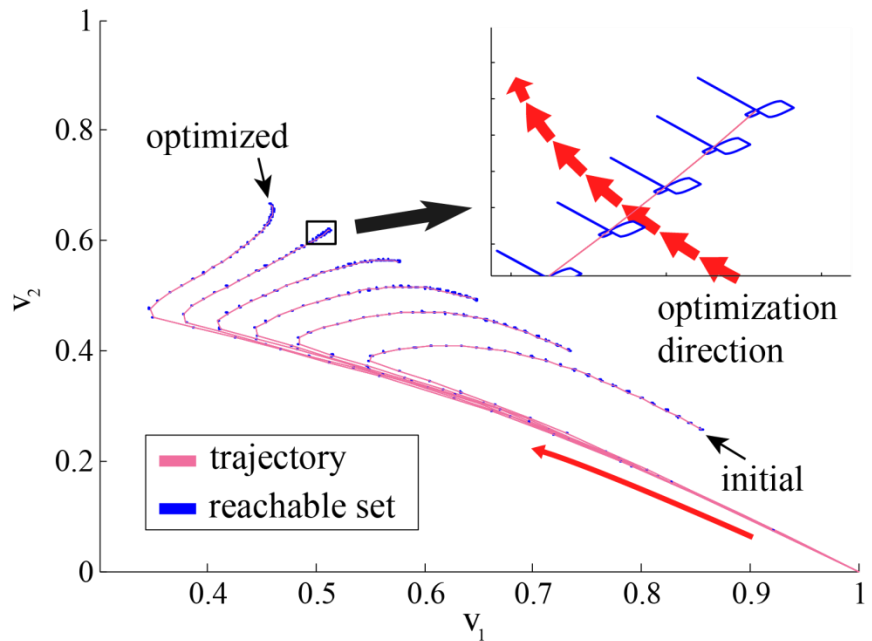


# Optimization of Read + Write Failure

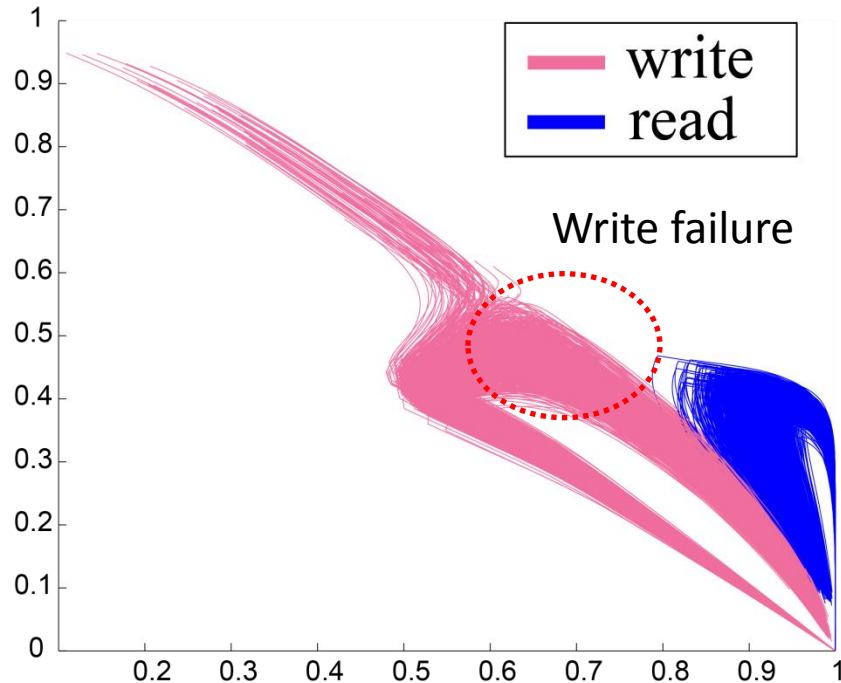


- Transistor widths :  
 $[W_1, W_3, W_5] = [200, 400, 400] \text{ nm}$
- Read pulse width is 9ns.
- Write pulse width is 0.024ns.

- Optimization result:  
 $[W_1, W_3, W_5] = [192, 330, 586] \text{ nm}$



# Yield Before and After Optimization



- Verify yield rate before and after optimization by Monte Carlo with 1000 samples.

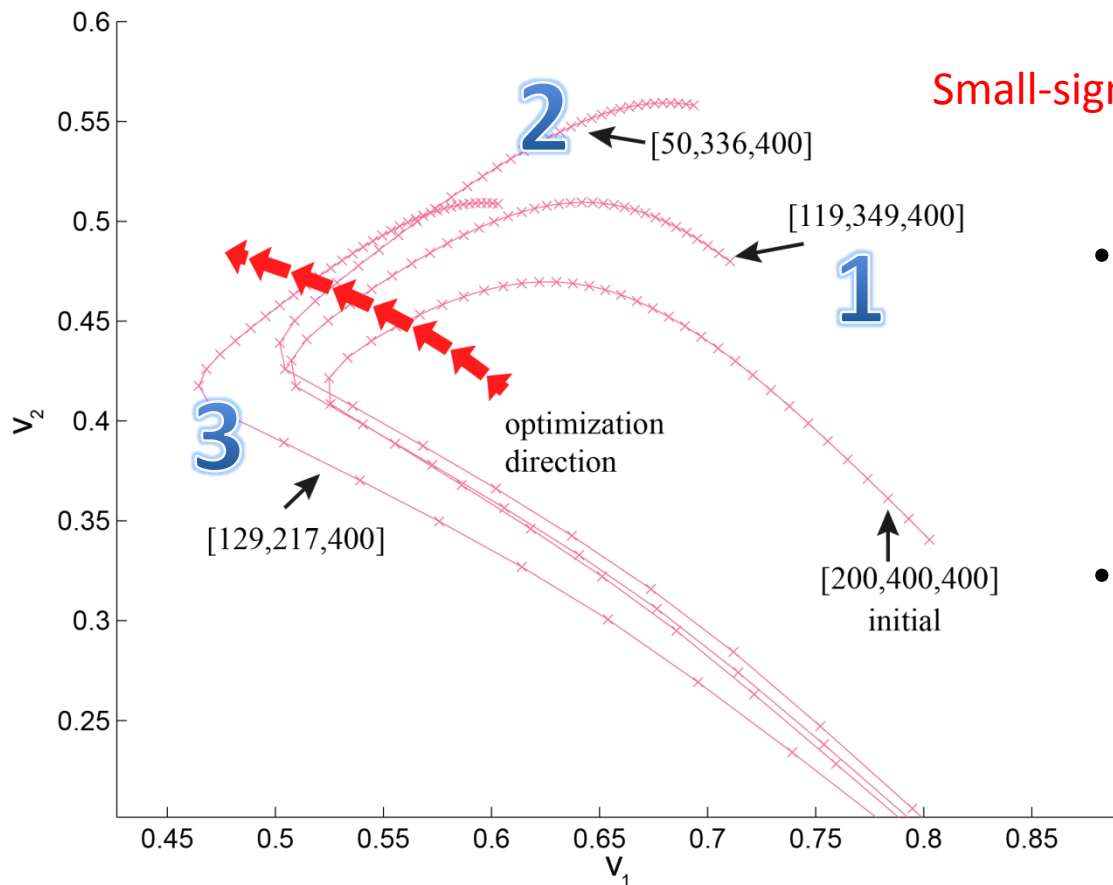
$$Yield\ rate \equiv 1 - \frac{N_{failure}}{N_{total}}$$

- Yield rate is improved from 6.8% to 99.957%.



# Optimization with Small-signal Sensitivity

$$s = \frac{\partial x_k}{\partial w} = - \left( \frac{C}{h} + G \right)^{-1} \frac{\partial G}{\partial w} \left( \frac{C}{h} + G \right)^{-1} \left( \frac{C}{h} x_{k-1} + u_k \right)$$



- The new routine fails to find a feasible solution and results in negative width after 3 iterations.
- The width M5 fails to be tuned (stays at 400nm).

# Runtime Comparison

Iteration	Transistor widths (nm)	Sensitivity based RA (s)	MC (s)	Speedup
1	[185, 371, 451]	9.37	5953.23	635.35x
2	[177, 359, 485]	9.69	5876.12	606.41X
3	[173, 349, 515]	9.53	5901.64	619.27X
4	[171, 340, 545]	9.34	5932.87	635.21x
5	[181, 329, 574]	9.58	5951.07	618.11x
6	[192, 330, 586]	9.51	5911.91	621.65x

# Summary

- **Formulated SRAM dynamic stability verification and optimization problem**
- **Proposed large-signal sensitivity of safety distance in the state space by reachability analysis**
- **Significantly improved SRAM yield rate in presence of parameter variations**

# Thank You!



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