

# A SEGMENTATION-BASED BISR SCHEME

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# Introduction (1/3)

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- SRAM memory: Determining factor in yield loss and reliability problems in modern SoC (System on Chip)
- Small geometries, Voltage scaling → Manufacturing defects and process variation
- Need for fault tolerance techniques

# Introduction (2/3)

- Conventional techniques
  - Use of spare rows and columns
  - External test equipment creates fault map
  - Faulty elements are replaced by spare ones
  - Costly and time consuming
- BISR (Built-in Self-Repair) techniques
  - Move repair process on-chip
  - Repairing circuitry intervening in the decoding operation
  - Localization of faulty cells by a BIST (Built-In Self-Test) circuitry

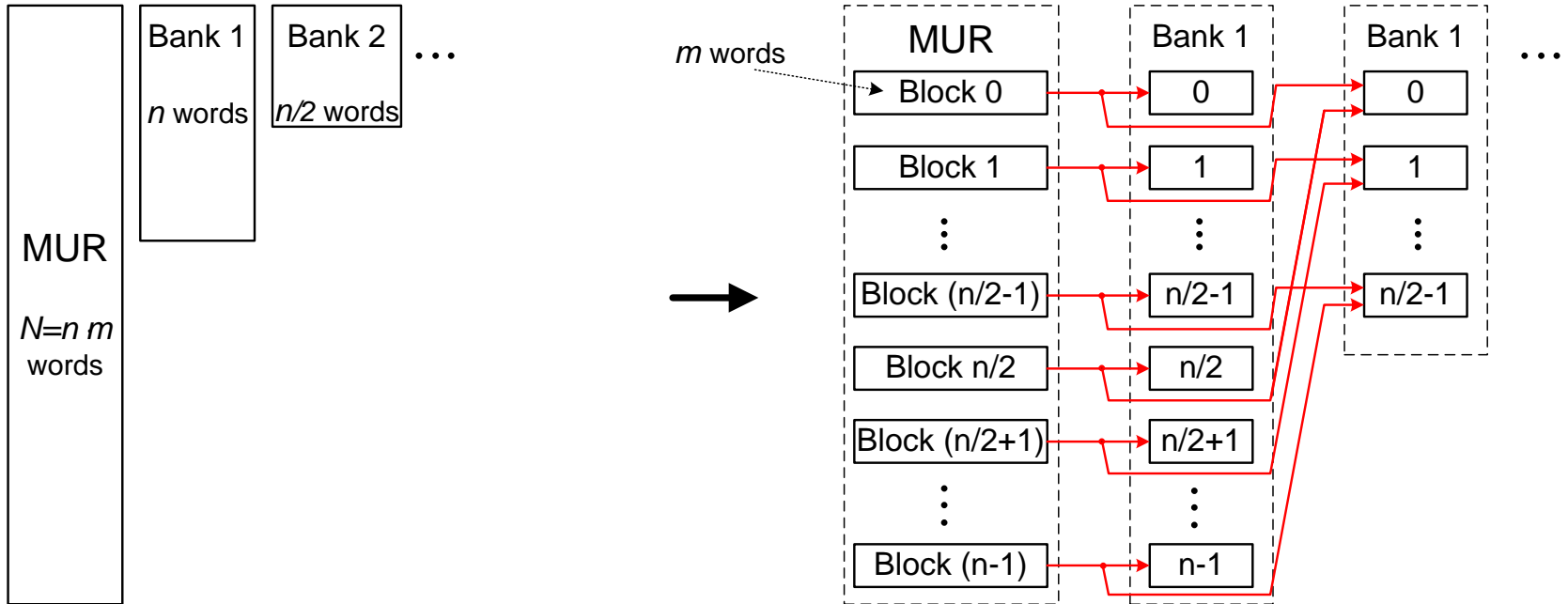
# Introduction (3/3)

- Granularity of repair affects remapping circuitry overhead and utilization of spare elements
  - ▣ Row/Column-based techniques → Simple circuitry, Not efficient allocation of spare resources
  - ▣ Block/bit-based techniques → Complex circuitry, Efficient allocation of spare resources
- Considering the tradeoff, a cache-based architecture with multiple banks was proposed

# Previous work (1/2)

- Multiple cache banks that repair faulty elements in word or bit level
  - ▣ Faulty words are directly mapped to redundant cache banks.
  - ▣ Each cache bank has half the lines of its previous one.
  - ▣ Mathematical analysis proves that for  $\lambda$  faulty words in the MUR (Memory under repair),  $\sim 100\%$  reparability can be achieved using this technique if the primary cache bank has  $n=2\lambda$  lines.
  - ▣ The bit level technique reduces the area overhead comparing to the word level one.

# Previous work (2/2)



# Proposed BISR scheme (1/6)

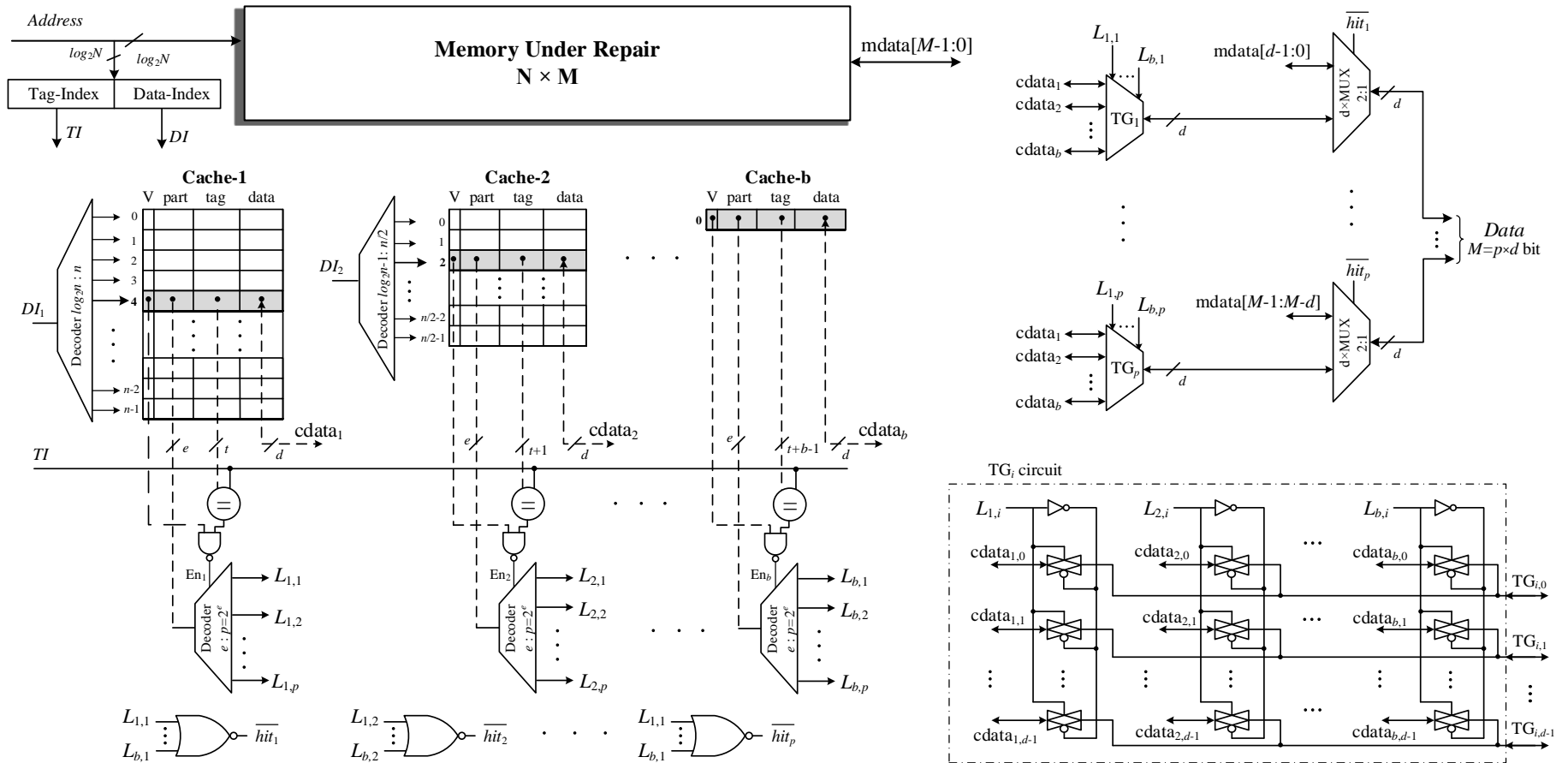
- A segmentation-based BISR scheme is proposed
  - ▣ The MUR (Memory Under Repair) word is segmented in parts and can be repaired in any segmentation level
  - ▣ A part of the address is used as an index (DI) to map the repaired word in the cache banks and another part is used as a tag (TI) to identify the exact word that is mapped
  - ▣ A special field (part) in each cache line identifies which segment of the MUR word is repaired

# Proposed BISR scheme (2/6)

- Except for the cache banks there is a remapping and routing circuit
  - ▣ Identifies if parts of the requested word are stored in the cache bank circuitry and drives them to the data bus.
- Interaction with BIST
  - ▣ A BIST circuitry has previously identified all the faulty parts of the MUR and distributed them in the spare cache banks.



# Proposed BISR scheme (3/6)

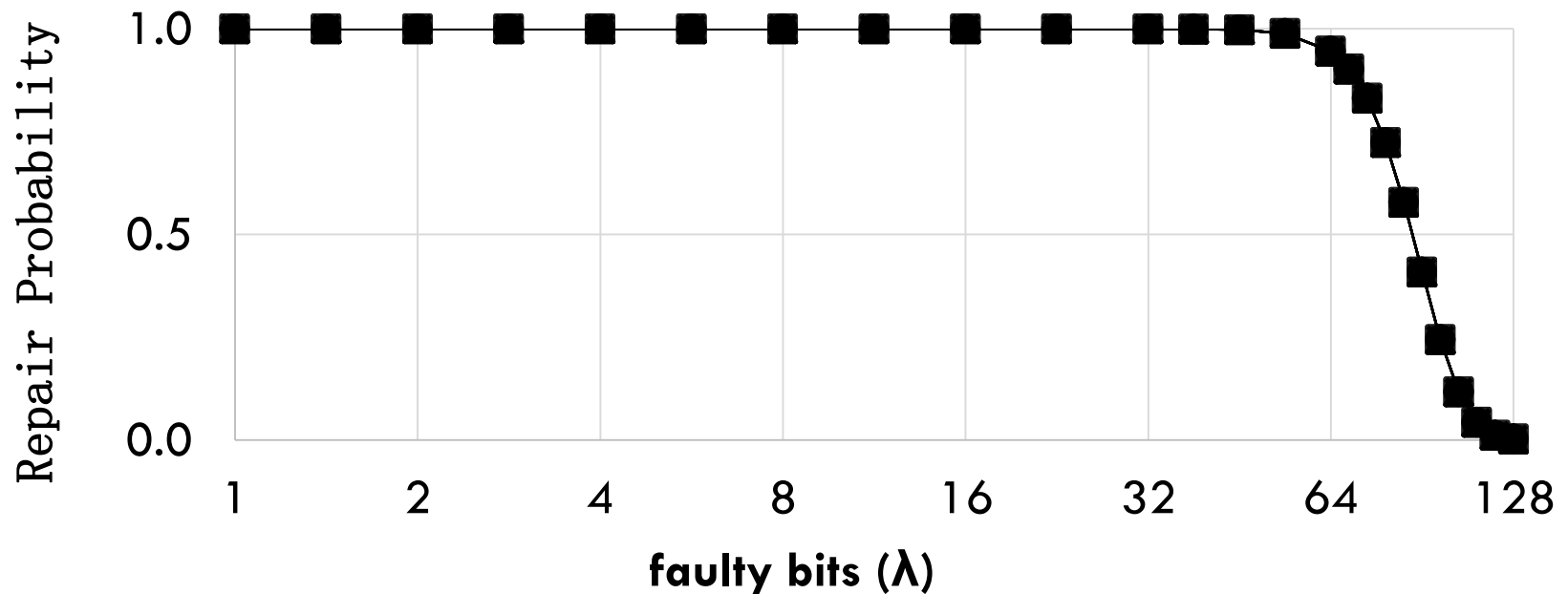


# Proposed BISR scheme (4/6)

- A mathematical analysis proved that:
  - ▣ The probability of the MUR being fully repaired by the BISR circuitry does not depend on the level of segmentation.
  - ▣ For  $\lambda$  faulty bits in the MUR, a primary bank with  $n=2\lambda$  lines is required to achieve  $\sim 100\%$  reparability independently of the segmentation level.
  - ▣ Negligible differences in the probability of repair are observed only for values of faulty bits ( $\lambda > 2n$ ) that even the non-segmented scheme cannot repair with  $\sim 100\%$  probability.

# Proposed BISR scheme (5/6)

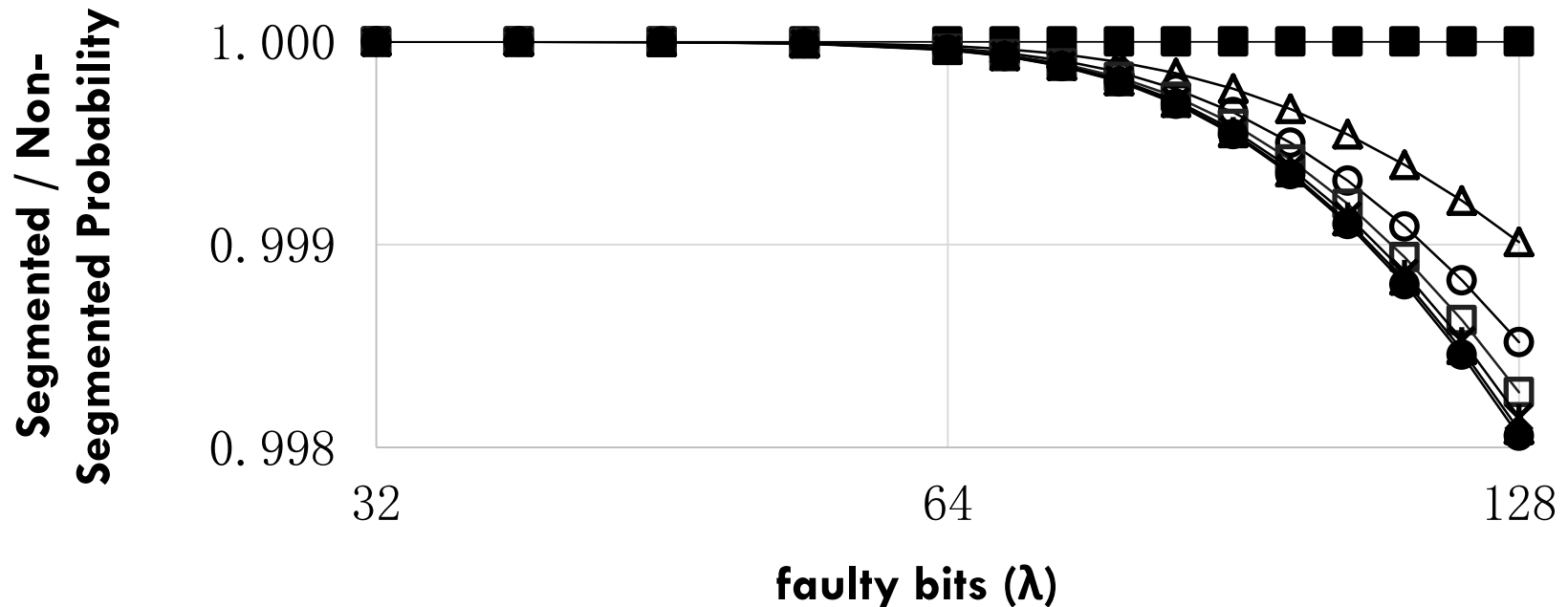
- MUR 1Mx64, primary cache bank with 64 lines



■ non-segmented    ▲ 32-bit    ○ 16-bit    □ 8-bit    ✖ 4-bit    ▲ 2-bit    ● 1-bit

# Proposed BISR scheme (6/6)

□ MUR 1Mx64, primary cache bank with 64 lines



■ non-segmented ▲ 32-bit ○ 16-bit □ 8-bit \* 4-bit ▲ 2-bit ● 1-bit

# Exploration of optimal segmentation (1/7)

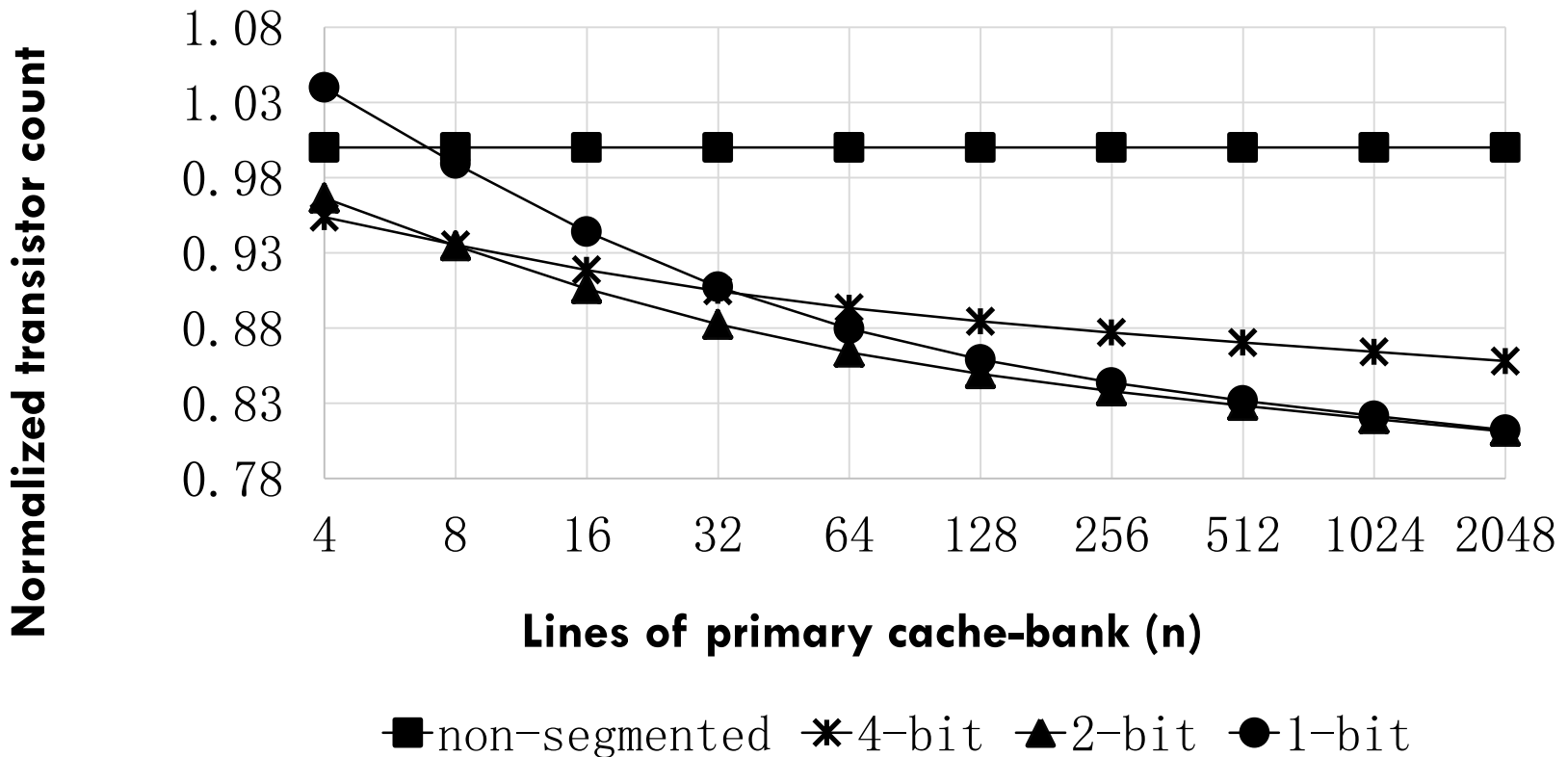
- The level of segmentation does not affect the  $\sim 100\%$  reparability.
- The basic criteria to find the optimal segmentation is the area occupied (transistor count) by the BISR circuitry.
  - ▣ Segmenting in bit-level seems an obvious solution but the additional remapping and routing circuitry becomes significantly larger.
  - ▣ The area occupied by the BISR circuitry for each level of segmentation was computed using a unit gate model.

# Exploration of optimal segmentation (2/7)

- The area of the BISR circuitry is affected by the:
  - Size of the MUR ( $N$  lines,  $M$ -bit words)
    - An exhaustive exploration about the effect of the MUR lines ( $N$ ) was conducted and the impact proved to be insignificant → The number of MUR lines is set to  $N=2^{20}$
    - The most usual memory word lengths (8, 16, 32 and 64-bit) are used in the exploration
  - Lines of primary cache bank ( $n$ )
    - The exploration was conducted for a range of lines of the primary cache bank from 4 to 2048
- All the possible segmentations were explored

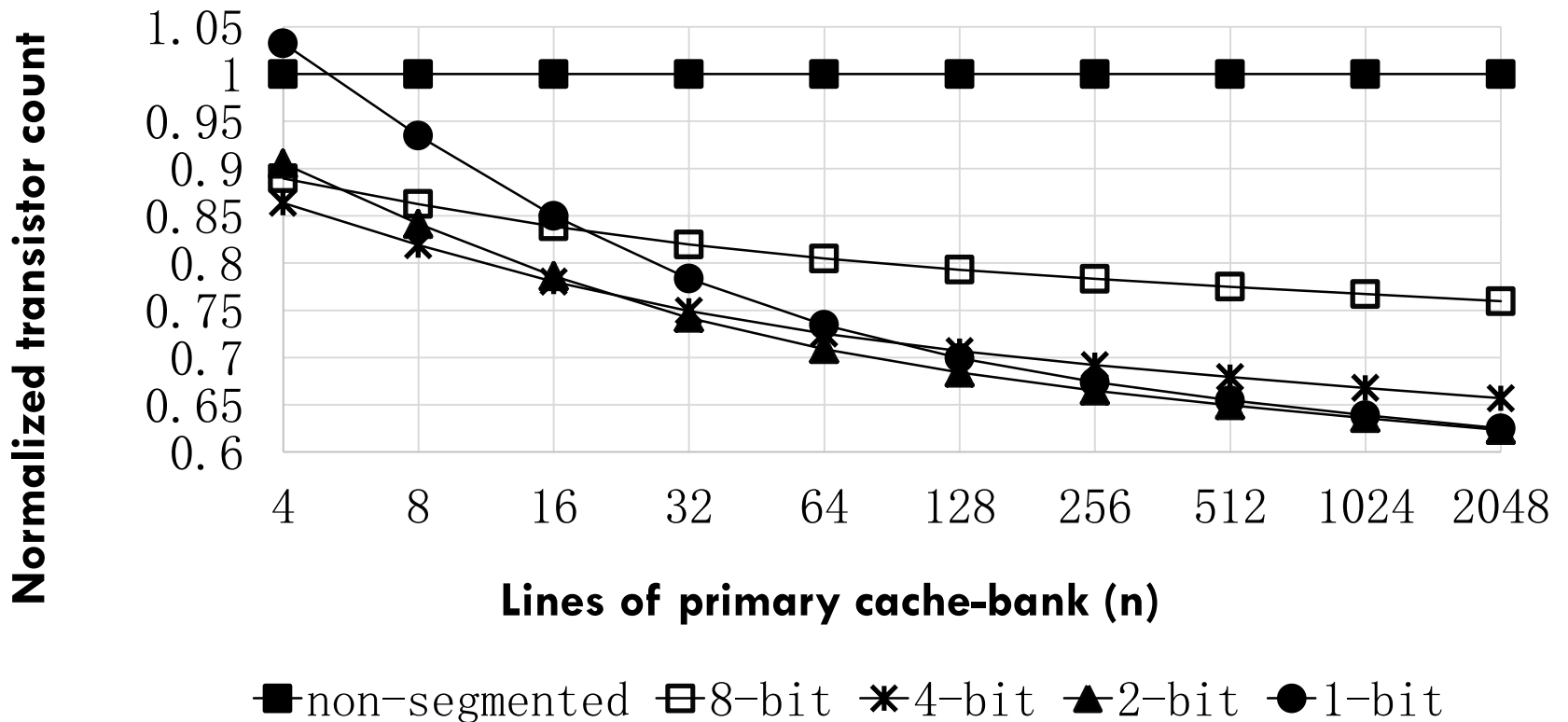
# Exploration of optimal segmentation (3/7)

□ MUR word length = 8 bits



# Exploration of optimal segmentation (4/7)

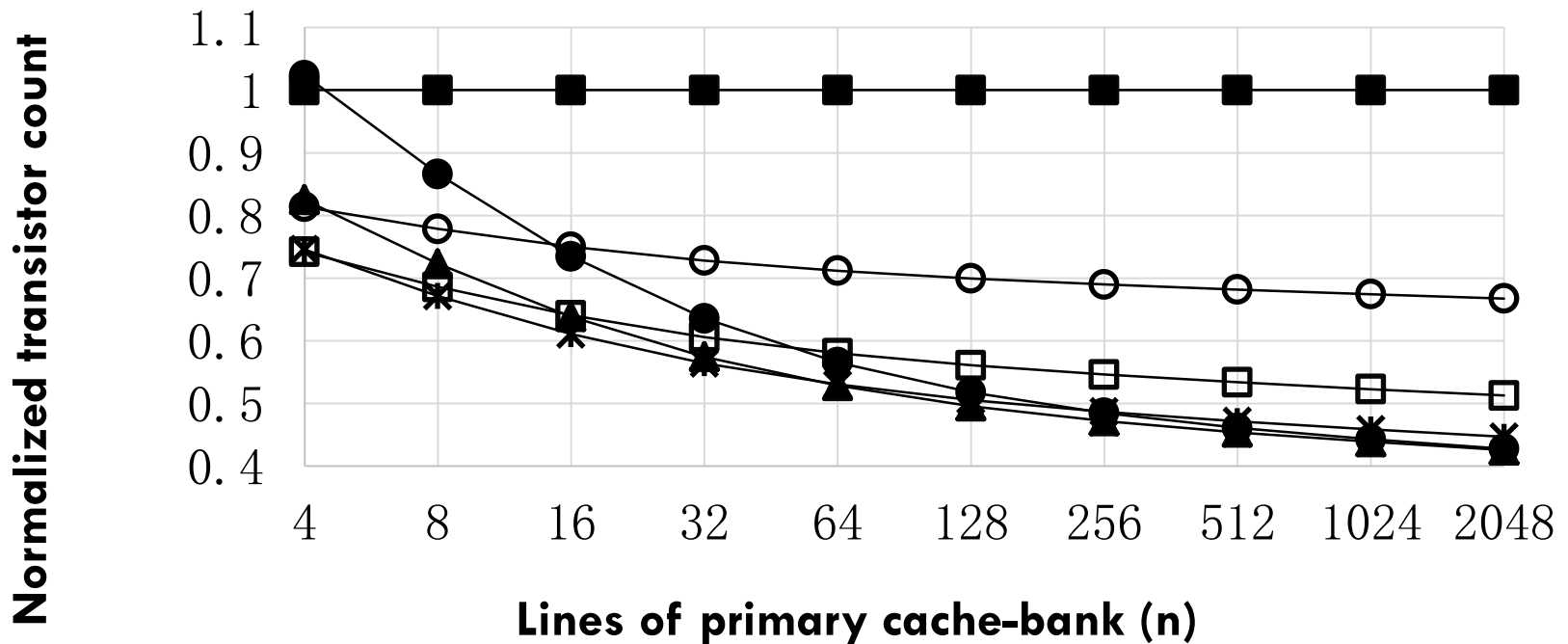
□ MUR word length = 16 bits





# Exploration of optimal segmentation (5/7)

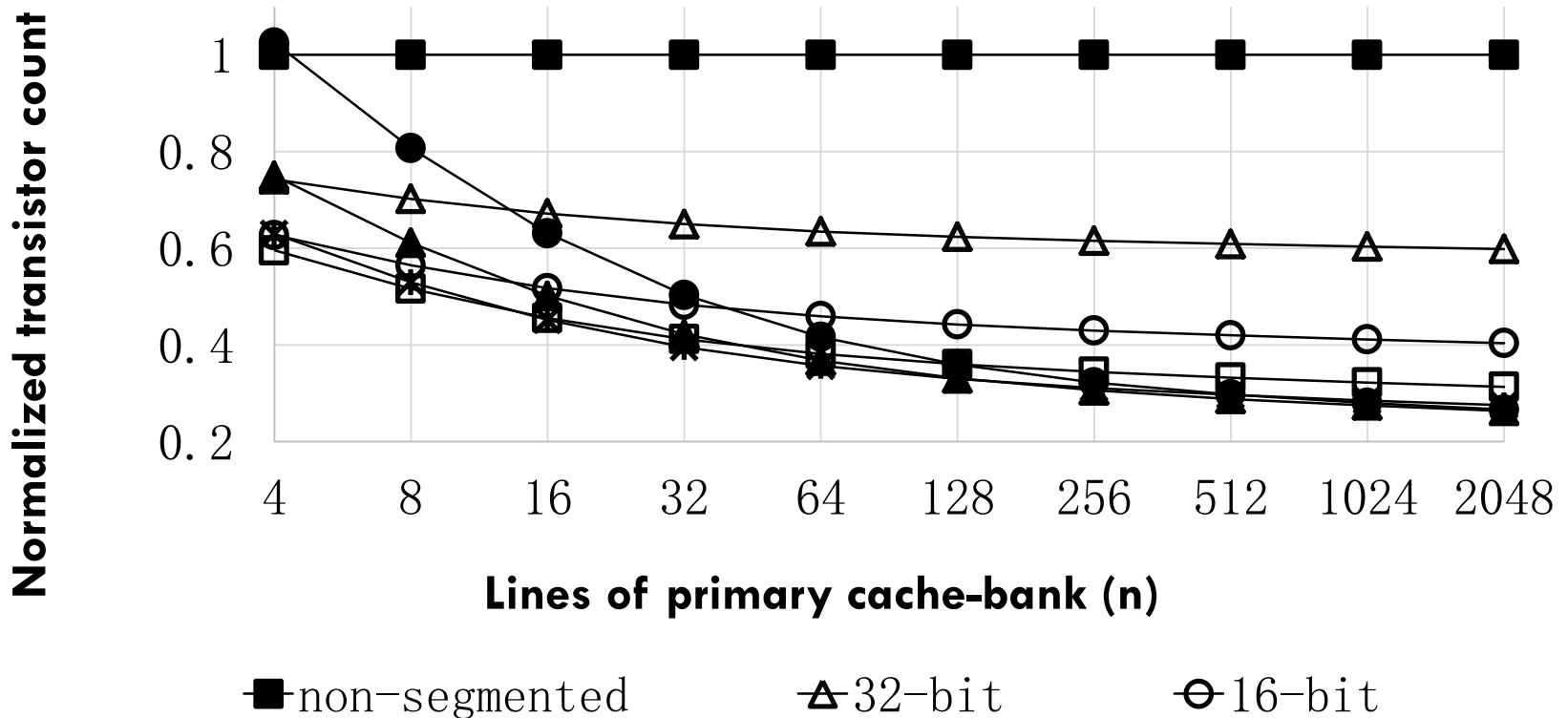
□ MUR word length = 32 bits



■ non-segmented ○ 16-bit □ 8-bit \* 4-bit ▲ 2-bit ● 1-bit

# Exploration of optimal segmentation (6/7)

□ MUR word length = 64 bits



# Exploration of optimal segmentation (7/7)

- Overall observation of the results
  - ▣ The non-segmented scheme is the one with the highest area overhead and it must be avoided.
  - ▣ The 1-bit segmentation, although it might seem as the obvious solution, never proves to be the best option.
  - ▣ When the MUR has a high fault rate, the 2-bit segmentation seems to be the optimal choice.
  - ▣ When the MUR fault rate becomes smaller and the word length increases, segmentation in bigger groups (4-bit, 8-bit) should be preferred.

# Conclusion

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- A BISR scheme with parametric repair level is proposed
- The proposed scheme can operate for all the possible segmentations of the MUR word
- According to a mathematical analysis the reparability is not affected by the segmentation level
- In terms of transistor count the non-segmented scheme proves to have the highest area overhead while the 2-bit segmentation proves to be the optimal for high fault rates of the MUR

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# Thank You!

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□ Questions?