

# P-SOCrates

Parallel Software Framework for Time-Critical many-core Systems

# A Lightweight OpenMP4 Run-time for Embedded Systems

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# Parallel programming models in Real-Time Embedded Systems

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- **Why parallel programming models?**
  - Provide a high level abstraction of parallel architectures
  - Reduce the complexity of parallel programming
  - Allows exploiting the performance of many-core processors
- **Real-Time systems require more performance**
  - Composed of complex applications
  - Parallel programming models enable current many-core embedded processors to provide it
- **OpenMP, a well known parallel programming model**
  - Widely used in HPC
  - Increasingly adopted in embedded systems

# OpenMP and Real-Time Systems

- OpenMP4 tasking model allows expressing fine-grained and irregular parallelism

- Task

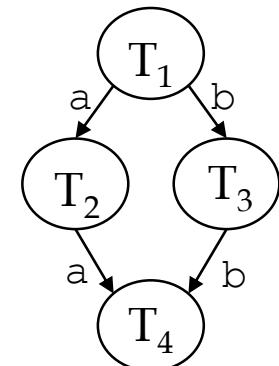
Independent parallel unit of work and its data environment

- Data dependencies

```
#pragma omp task depend(out:a,b) // T1
{ ... }
#pragma omp task depend(inout:a) // T2
{ ... }
#pragma omp task depend(inout:b) // T3
{ ... }
#pragma omp task depend(in:a,b) // T4
{ ... }
```

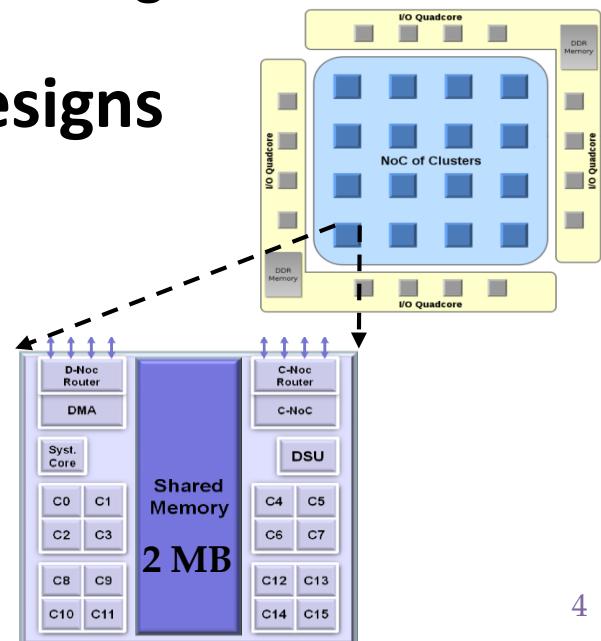
- OpenMP4 tasking model resembles the way Real-Time applications are modeled

- Task Dependency Graph (TDG) or Direct Acyclic Graph (DAG)



# OpenMP Run-time

- Current OpenMP implementations are designed for general purpose architectures
  - e.g. libgomp (GCC), nanos++ (OmpSs)
  - Require large data structures in memory (hash table) to track at run-time the dependencies among tasks
- Modern many-core embedded designs
  - e.g. Kalray MPPA
  - Rely on computing fabrics with small on-chip memories



# Memory efficient OpenMP Run-time

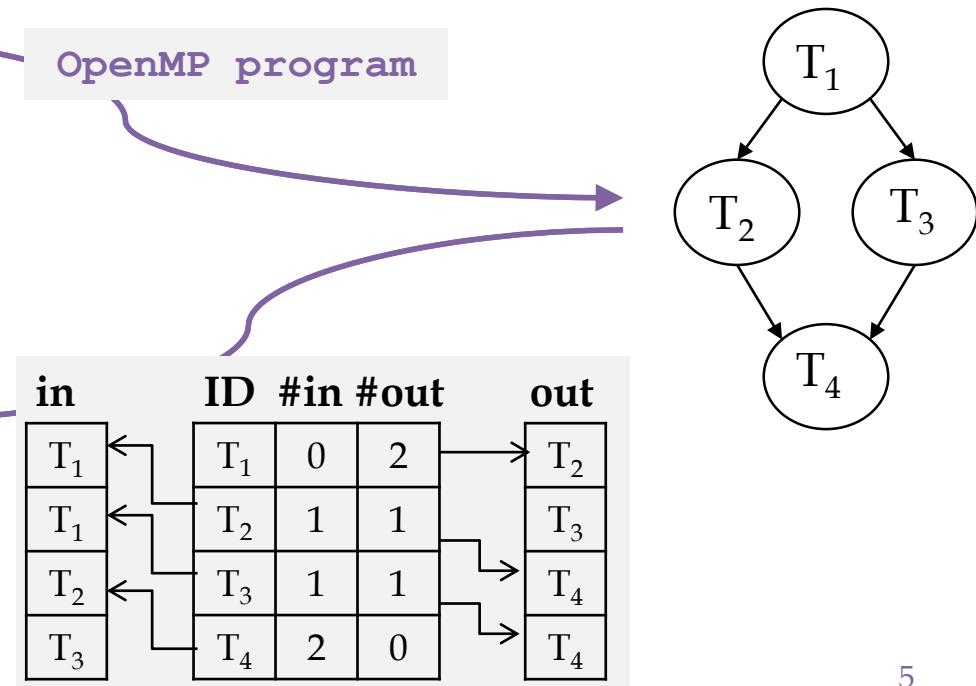
- **SOLUTION:** Derive the complete TDG at compile time and maintain it in memory at run-time
  - Although counter-intuitive, the memory consumption is reduced using more memory efficient structures

- **New compiler pass**

- Derives the TDG of a OpenMP program

- **New Run-Time**

- Efficiently stores and manages the TDG



# Compiler pass: Static construction of TDG

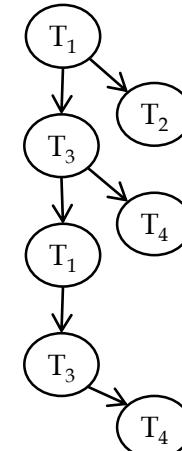
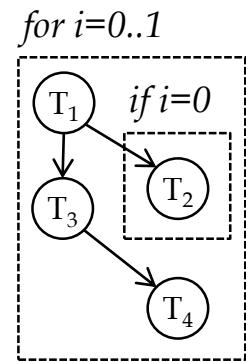
**1. The Control/Data Flow Analysis Stage generates the augmented static TDG (*asTDG*)**

- i. Parallel Control Flow Analysis
- ii. Induction-Variable Analysis
- iii. Range Analysis

```
for (i = 0; i < 2; i++) {  
    #pragma omp task ... { // T1  
        if (i==0) {  
            #pragma omp task { ... } // T2  
            #pragma omp task ... { // T3  
                #pragma omp task { ... } // T4  
            }  
        }  
    }  
}
```

**2. The Task Expansion Stage generates the expanded static TDG (*esTDG*)**

- i. Expand the control flow structures
- ii. Resolve the dependency



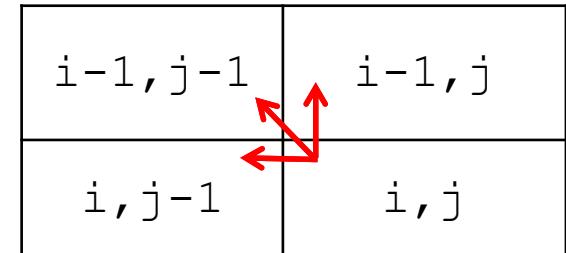
# Case Study: Matrix Processing

- **compute\_block(i, j)**

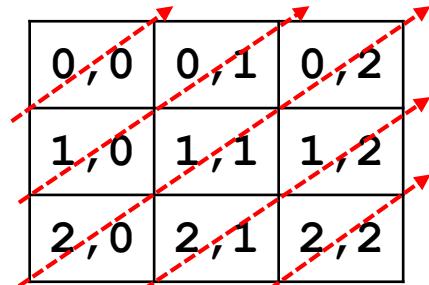
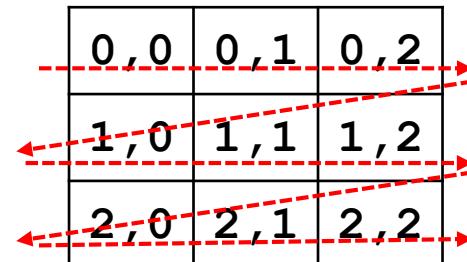
```
m[i][j] = func(m[i-1][j-1],  
                m[i-1][j],  
                m[i][j-1])
```

- Sequential version

```
for (int i=0; i<=2; i++) {  
    for (int j=0; j<=2; j++) {  
        compute_block(i,j);  
    }  
}
```



- Parallel version (Wave-front strategy)
  - Each task computes one block



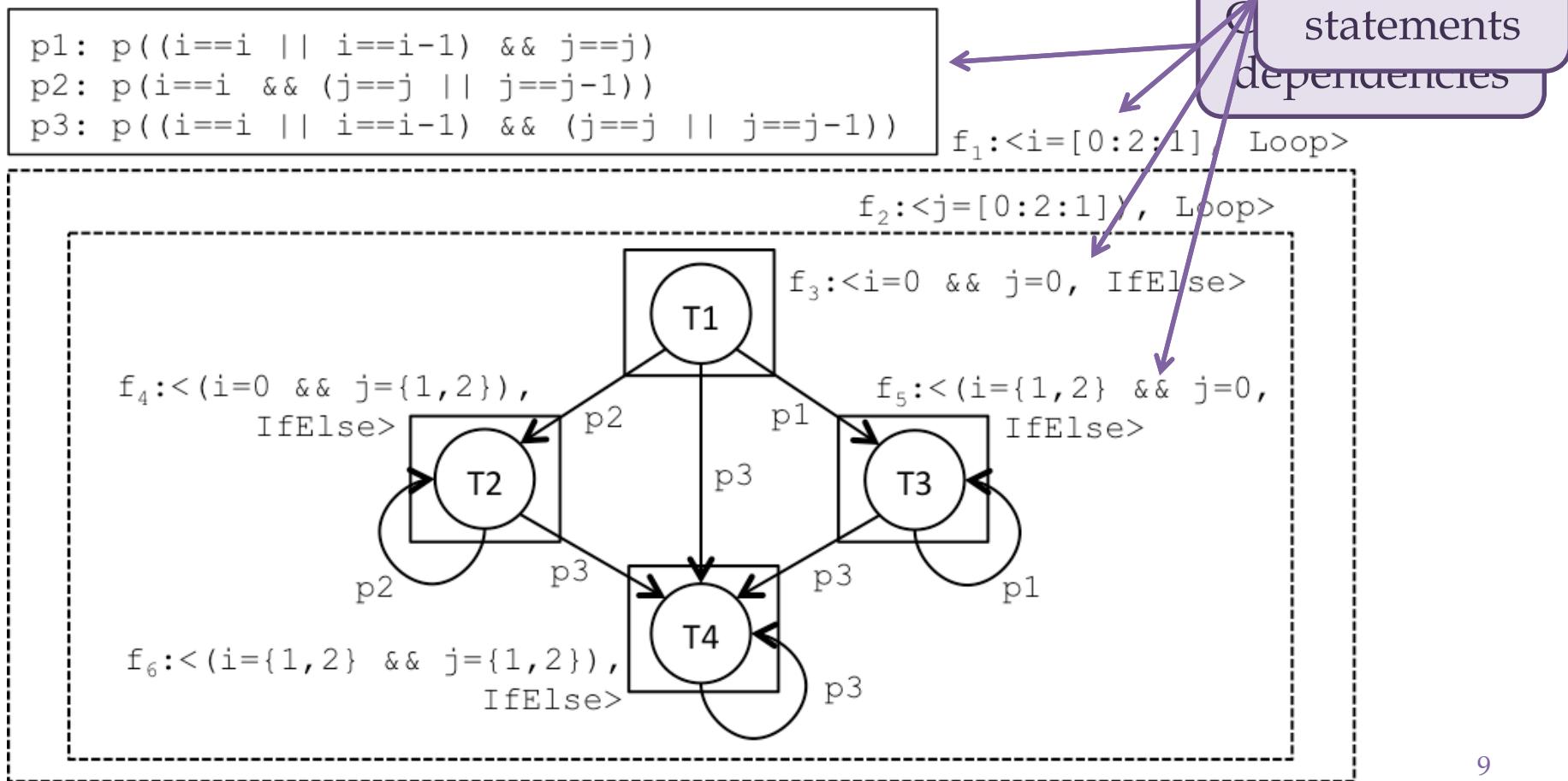
# Case Study: Matrix Processing

```
for (int i=0; i<=2; i++) {  
    for (int j=0; j<=2; j++) {  
        if (i==0 && j==0) { // Initial block  
            #pragma omp task depend (out: m[i][j])  
            compute block(i,j); // Task region T1  
        } elseif (i==0) { // Blocks in upper edge  
            #pragma omp task depend (in: m[i][j-1], out: m[i][j])  
            compute block(i,j); // Task region T2  
        } elseif (j==0) { // Blocks in left edge  
            #pragma omp task depend (in: m[i-1][j], out: m[i][j])  
            compute block(i,j); // Task region T3  
        } else { // Internal blocks  
            #pragma omp task depend (in: m[i-1][j], in: m[i][j-1],  
            in: m[i-1][j-1], out: m[i][j])  
            compute_block(i,j); // Task region T4  
        }  
    }  
}
```

0,0	0,1	0,2
1,0	1,1	1,2
2,0	2,1	2,2

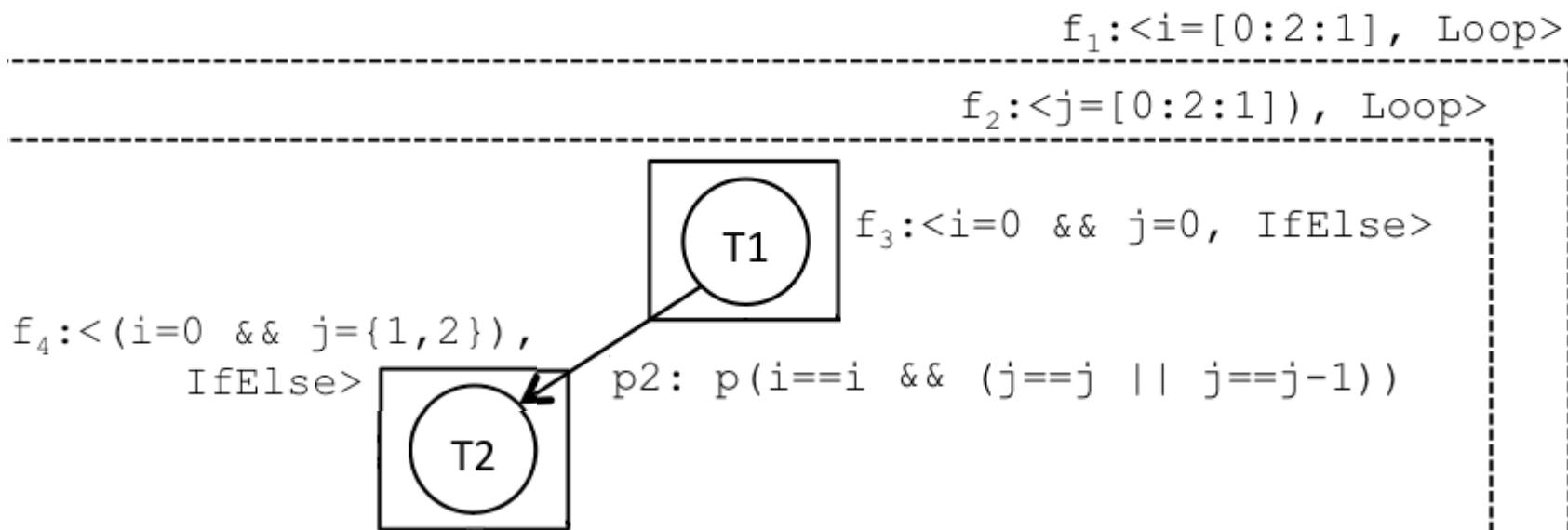
# Case study: Control/Data Flow Analysis

- *augmented static TDG (asTDG)*



# Case study: Control/Data Flow Analysis

```
... for (int i=0; i<=2; i++) { ← f1
    for (int j=0; j<=2; j++) { ← f2
        if (i==0 && j==0) { ← f3
            #pragma omp task depend (inout: m[i][j])
            compute_block(i,j); // Task region T1
        } elseif (i==0) { ← f4 → p2
            #pragma omp task depend (in: m[i][j-1], inout: m[i][j])
            computeblock(i,j); // Task region T2
        }
    ...
}
```



# Case study: Task Expansion Stage

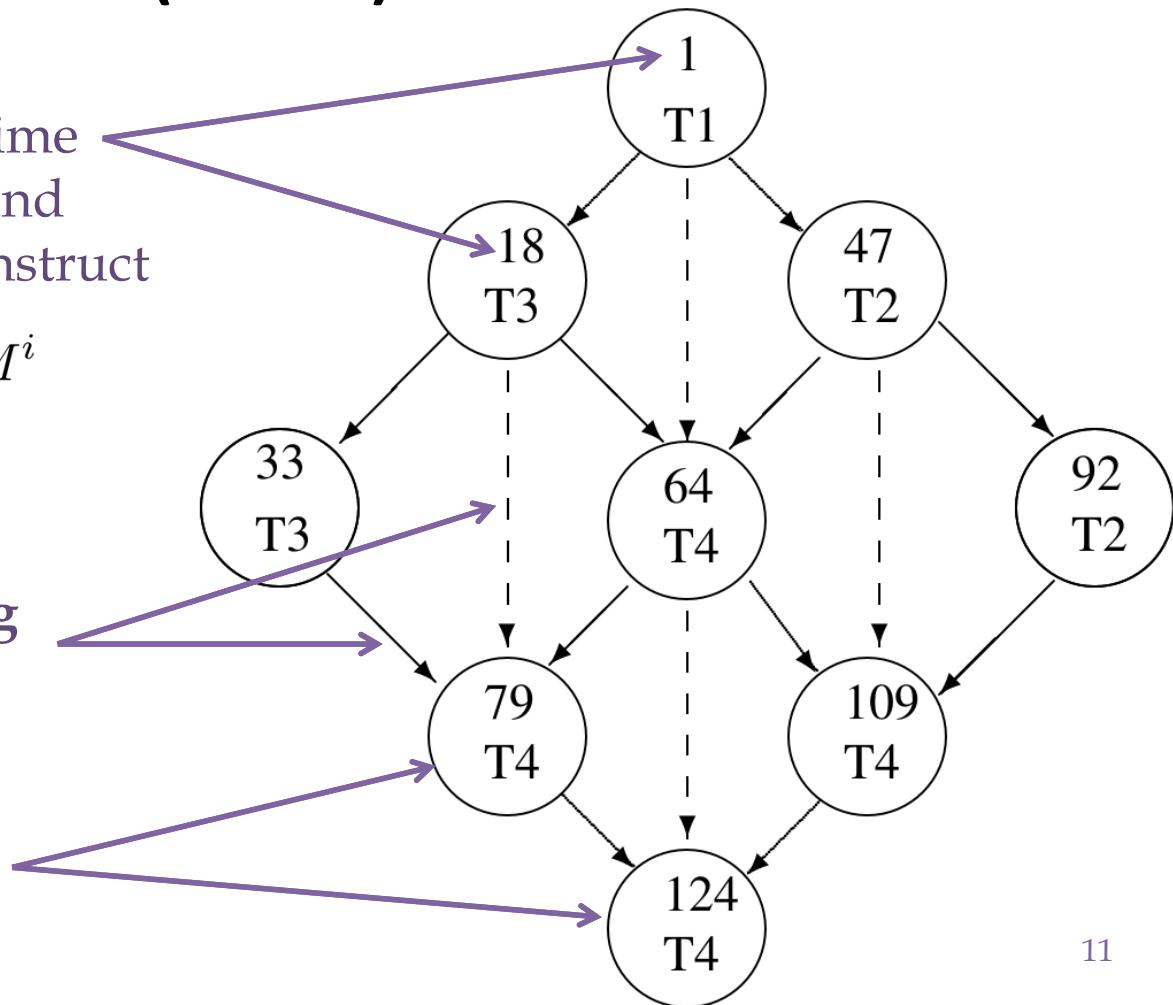
- *expanded static TDG (esTDG)*

Task ID: Allows the run-time to identify task instances and the corresponding task construct

$$t_{id} = sid_t + T \times \sum_{i=1}^{L_t} l_i \cdot M^i$$

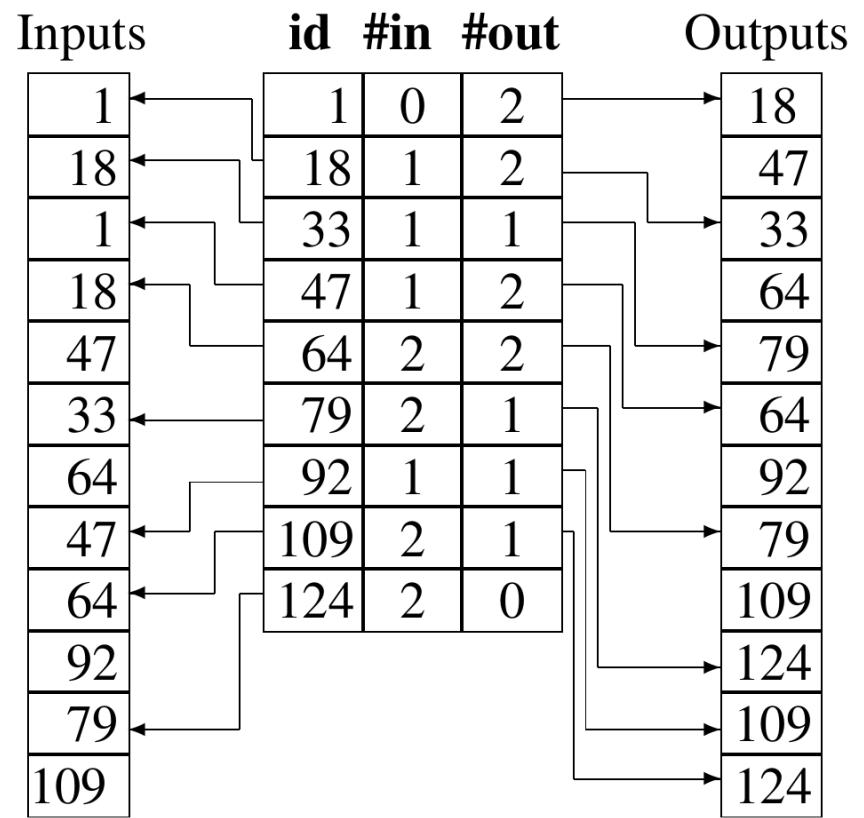
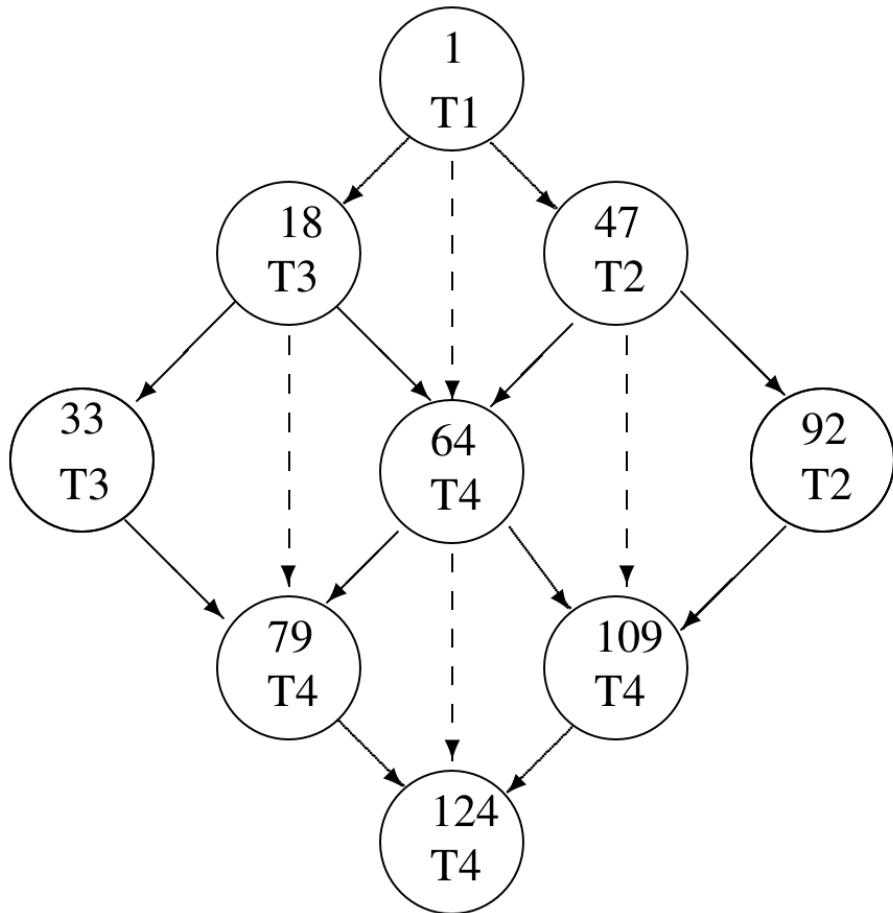
Dependencies among task instances

Task instances executed at run-time



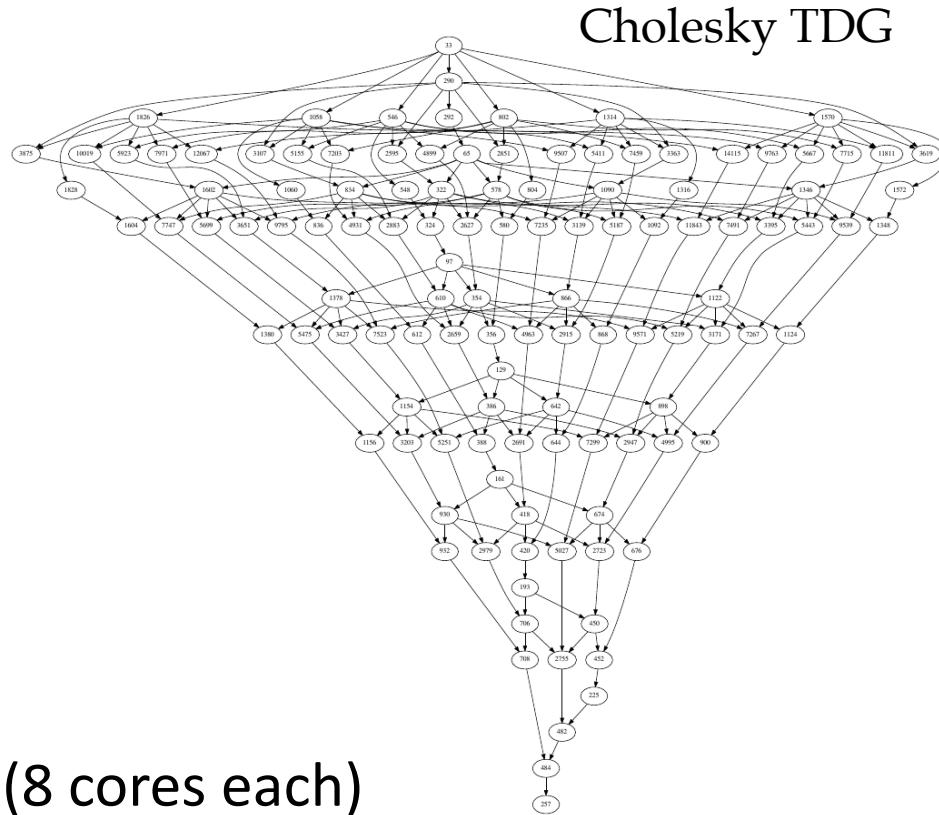
# OpenMP Run-Time

- Representation of the *esTDG*: sparse matrix



# Evaluation: Experimental Setup

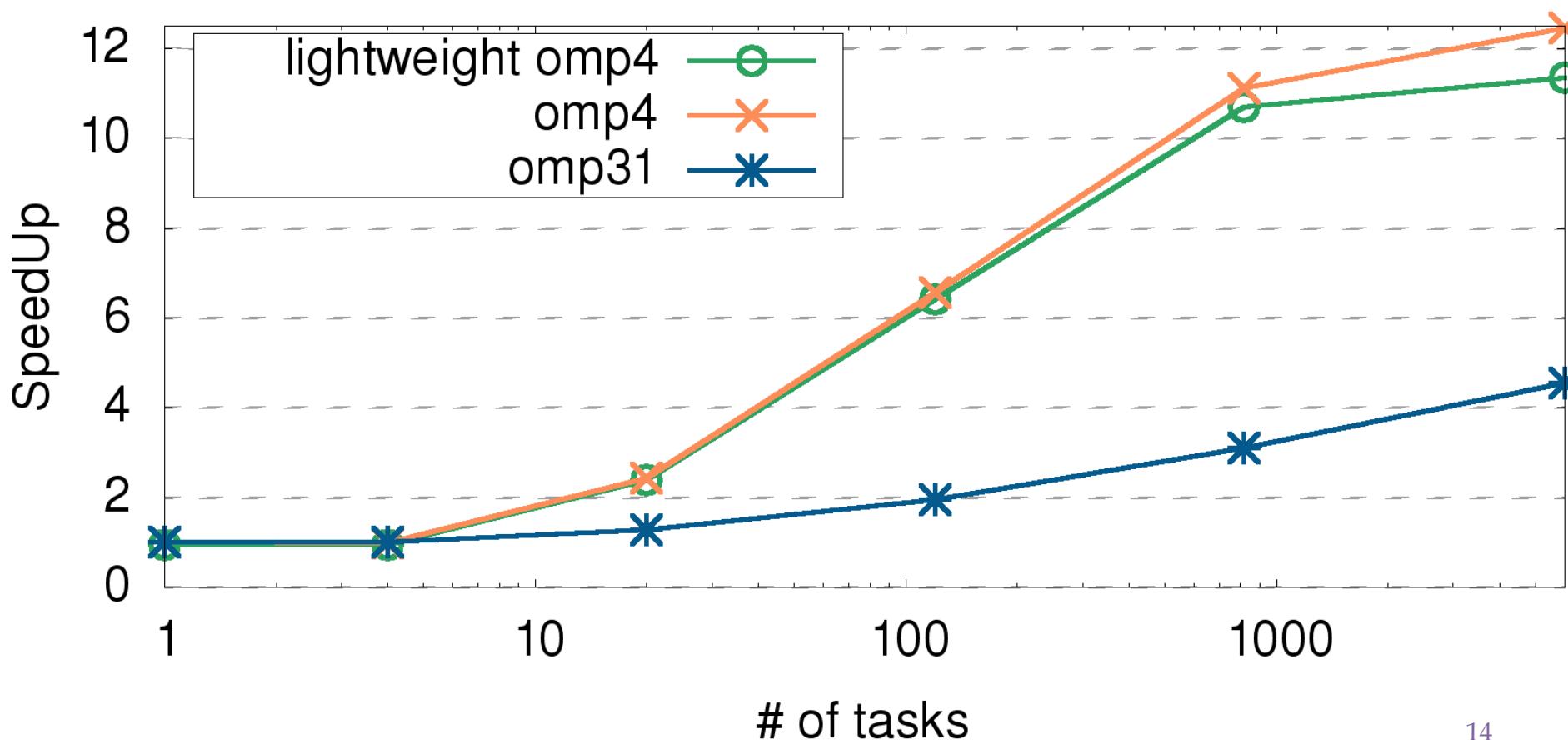
- **OpenMP framework**
    - New compiler pass
      - Mercurium
    - Lightweight Run-Time
      - GNU libgomp (GCC 4.7.2)
  - **Application**
    - Cholesky Factorization
  - **Platforms**
    - 2 Intel Xeon CPUs E5-2670
    - MPPA processor (256 cores  
2 MB per cluster)



# Evaluation: Performance speed-up

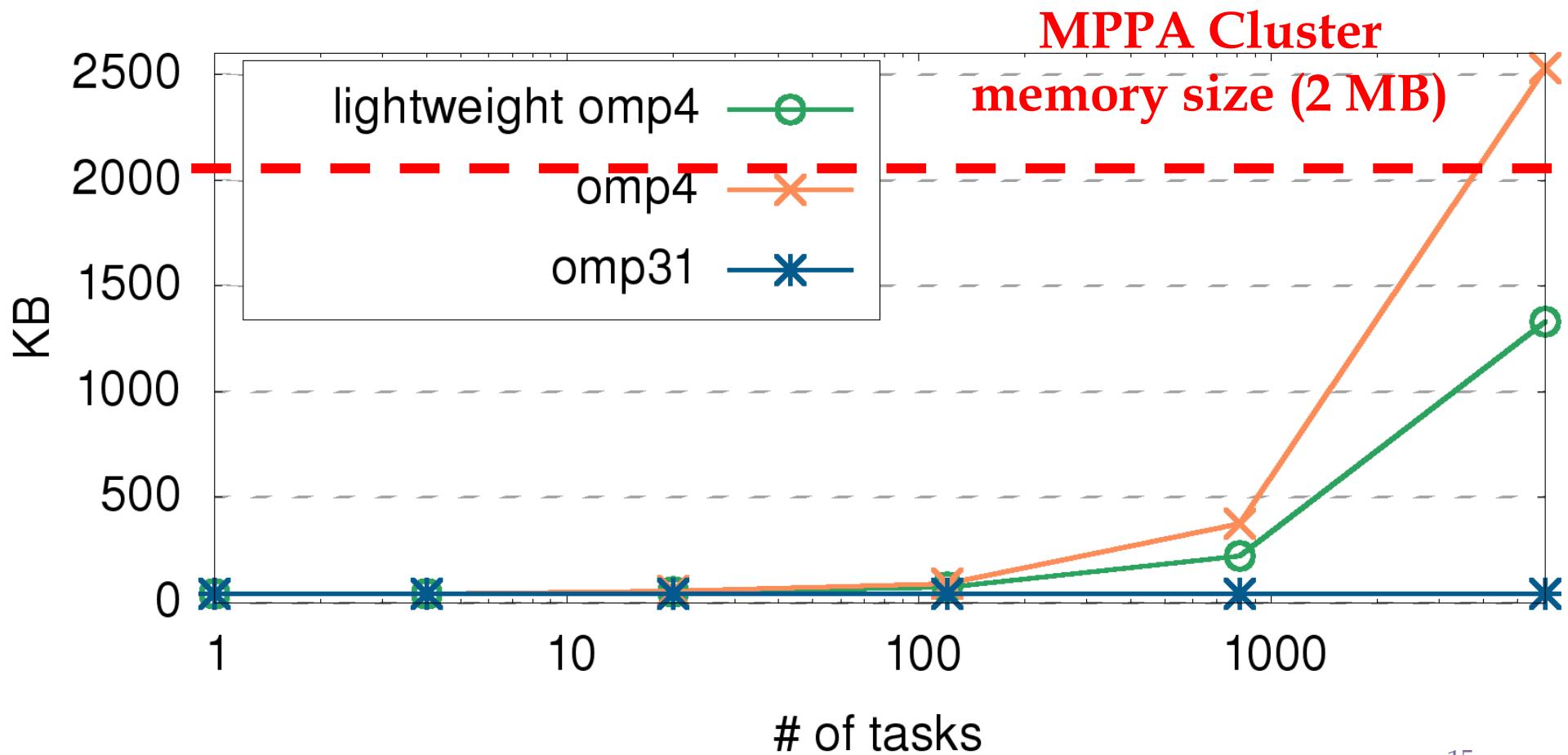
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- 2 Intel Xeon CPUs (16 cores)



# Evaluation: Memory usage

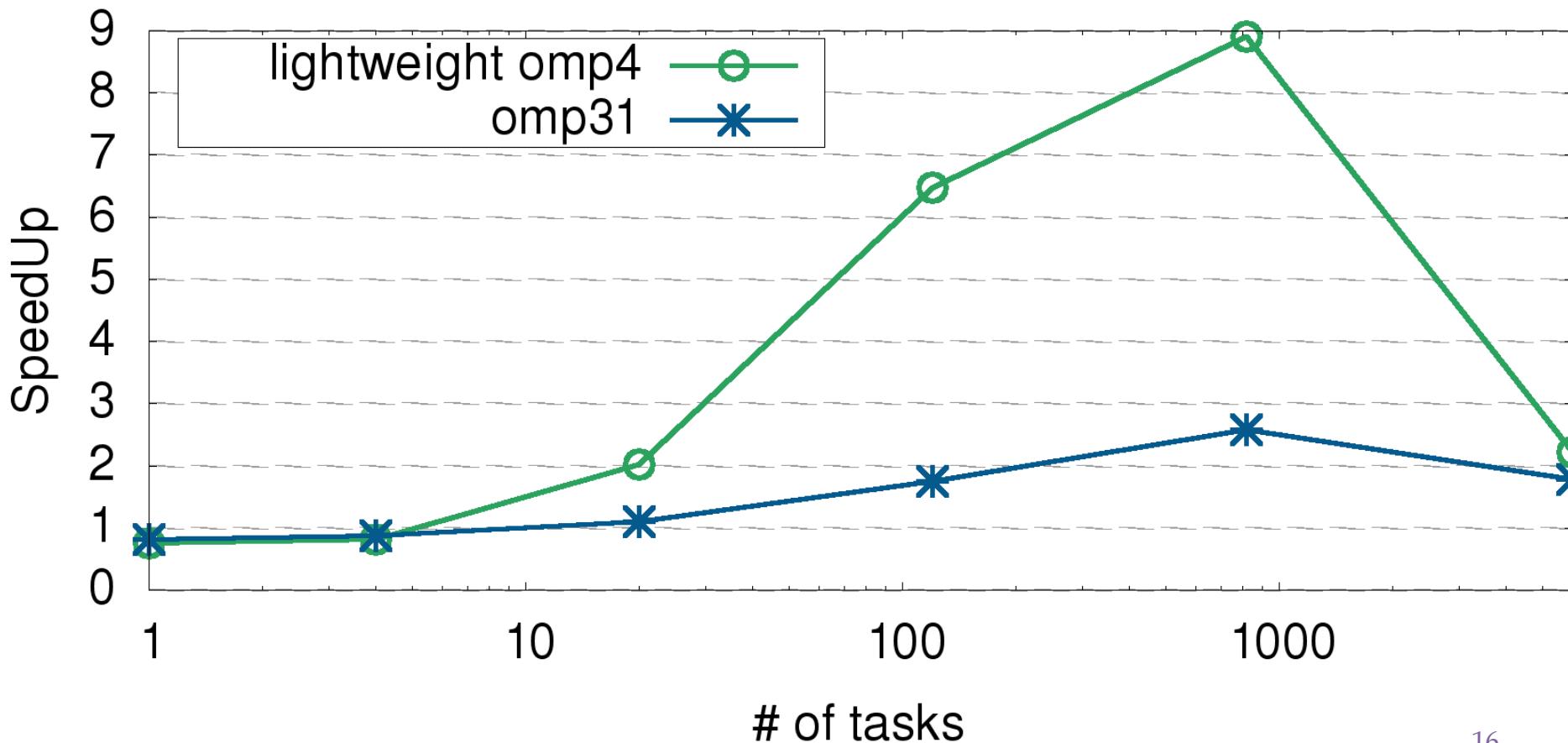
- 2 Intel Xeon CPUs (16 cores)



# Evaluation: Performance speed-up

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- MPPA (1 cluster, 16 cores)



# Conclusions

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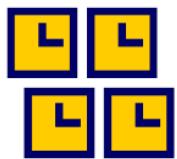
- **Parallel programming models are vital to exploit the parallel capabilities of many-core processors**
  - OpenMP is supported by most processors
- **Current OpenMP run-time implementations use large data structures**
  - Many-core processors rely on small on-chip memories
- **Our run-time handles the *static TDG***
  - New compiler pass derives it
  - Memory efficient data structure maintains it
- **Our approach provides similar speed-up of current run-times while reducing the memory consumption**

# Acknowledgments

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- EU project P-SOCRATES (FP7- ICT-2013-10)
- Spanish Ministry of Science and Innovation grant TIN2012-34557.



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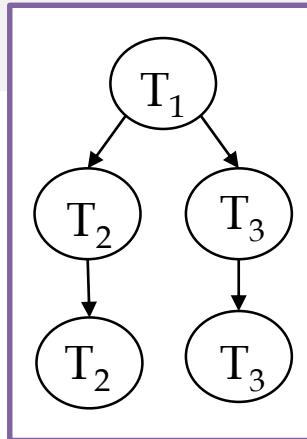
# Missing Information

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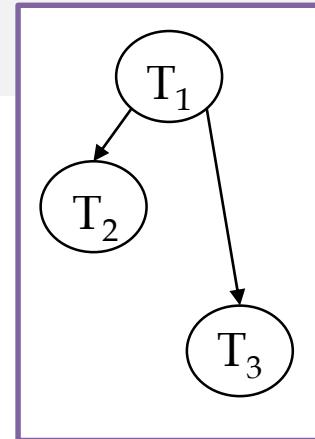
- **When an if-else statement cannot be evaluated**
  - All related tasks are instantiated
- **When the loop boundaries are unknown**
  - Disable parallelism across iterations by inserting a barrier at the end of the loop
- **When the dependency cannot be evaluated**
  - Dependency is always kept, forcing the involved tasks to be serialized.
- **The situations described above will result in a bigger esTDG or in a performance loss, although guarantee a correct esTDG.**

# Missing Information

```
#pragma omp task depend(out:b,c)
// T1
for (i= 0; i < 2; i++) {
    if(i == unknownCondition()) {
        #pragma omp task
            depend(inout:b)
        // T2
    } else {
        #pragma omp task
            depend(inout:c)
        // T3
    }
}
```



```
#pragma omp task depend(out:b,c)
// T1
for (i=0; i < 2; i++) {
    if(i == 0) {
        #pragma omp task
            depend(inout:b)
        // T2
    } else {
        #pragma omp task
            depend(inout:c)
        // T3
    }
}
```



# Compiler complexity

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- **Control/Data flow analysis stage**
  - i. Control Flow Analysis → Cyclomatic Complexity [1]
  - ii. Induction-Variable Analysis
  - iii. Range Analysis
- **Task expansion stage** → Quadratic on the number of instantiated tasks.

[1] T. McCabe. A complexity measure. *IEEE Transactions of Software Engineering*, 1976.

[2] R. E. Rodrigues, V. H. Sperle Campos, F. M. Quinto Pereira. A fast and low-overhead technique to secure programs against integer overflows. In CGO, 2013.