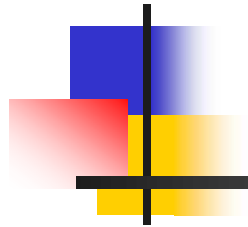


FastPlace 2.0: An Efficient Analytical Placer for Mixed-Mode Designs



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Mixed-Mode Placement

- Design style consisting of a combination of **macro blocks and standard cells**
- Varied sizes of placeable components complicates the placement step
- Traditionally, divided into two stages: floorplanning or block/module placement and cell placement.
- Designs today can have thousands of macro blocks along with millions of standard cells.
- Therefore, need efficient techniques to simultaneously handle this combination of placeable objects.

standard
cells

macro
block



Previous Work: FastPlace 2.0

- Natarajan Viswanathan and Chris C.-N. Chu.
FastPlace: Efficient Analytical Placement using Cell Shifting, Iterative Local Refinement and a Hybrid Net Model.
In Proc. International Symposium on Physical Design, pages 26-33, 2004
- Natarajan Viswanathan and Chris C.-N. Chu.
FastPlace: Efficient Analytical Placement using Cell Shifting, Iterative Local Refinement and a Hybrid Net Model.
IEEE Transactions Computer-Aided Design, 24(5): 722-733, 2005
 - Standard cell placement
 - Wirelength minimization
 - Flat placement
 - 13x, 102x and 20x faster than Capo, Dragon and Gordian-Domino
 - Comparable in wirelength

Extend the Standard-Cell placement technique to handle
Mixed-Mode designs



Overview of FastPlace 2.0

Stage 1: Global Placement

1. Hybrid Net Model
2. Cell Shifting for mixed-mode designs
3. Iterative Local Refinement

Techniques in
FastPlace 1.0

Stage 2: Legalization

1. Legalize and fix movable macros
2. Legalize standard cells

Stage 3: Detailed Placement

1. Global Swap
2. Vertical Swap
3. Local Re-ordering
4. Single-segment Clustering



Global Placement in FastPlace

➤ Framework:

repeat

Solve the convex quadratic program ①

Reduce wirelength by iterative heuristic ②

Spread the cells ③

until the cells are evenly distributed ④

➤ Special features of FastPlace:

■ Hybrid Net Model

- Speed up solving of convex QP ①

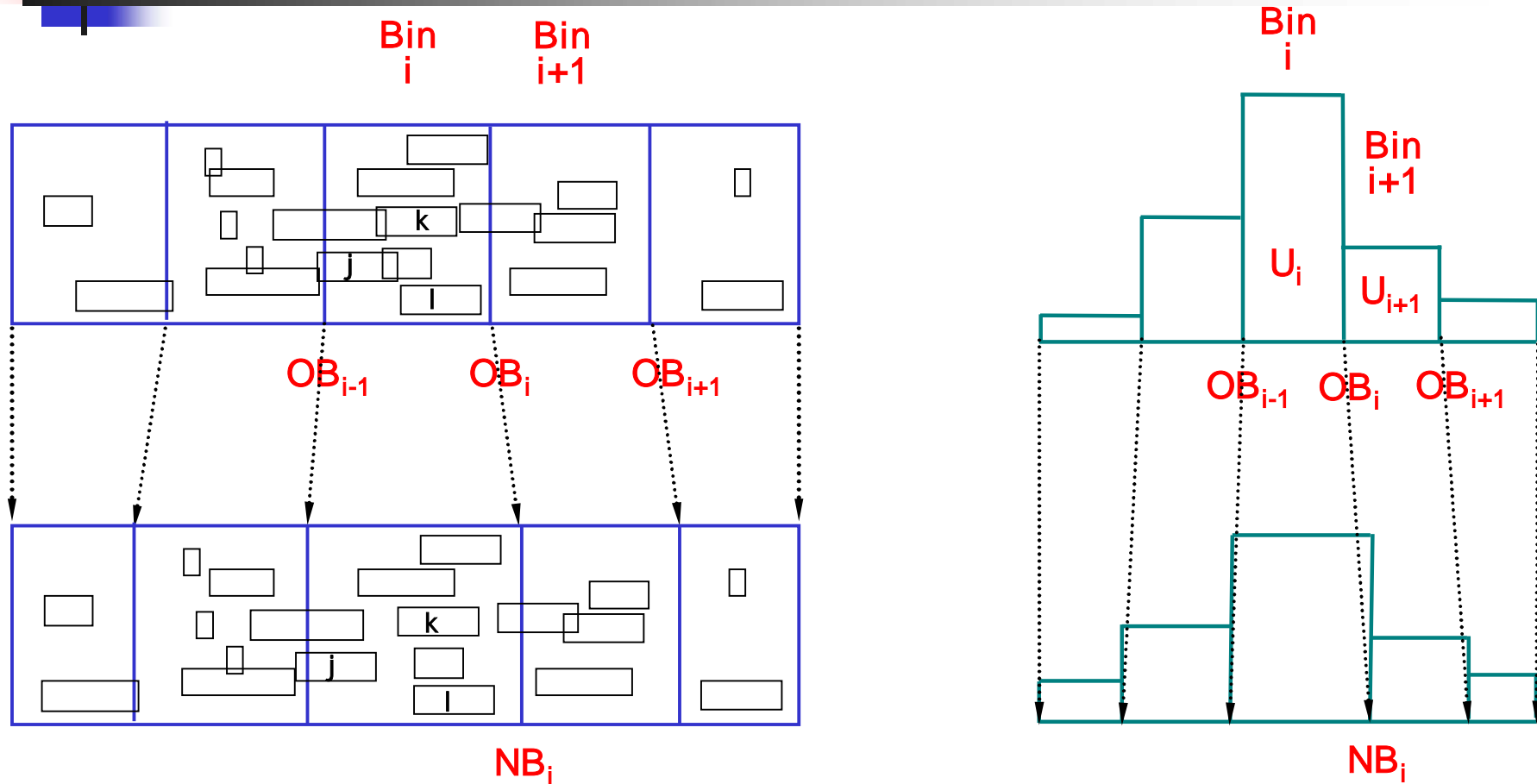
■ Cell Shifting

- Easy-to-compute technique ③
- Enable fast convergence ④

■ Iterative Local Refinement

- Minimize wirelength based on linear objective ②

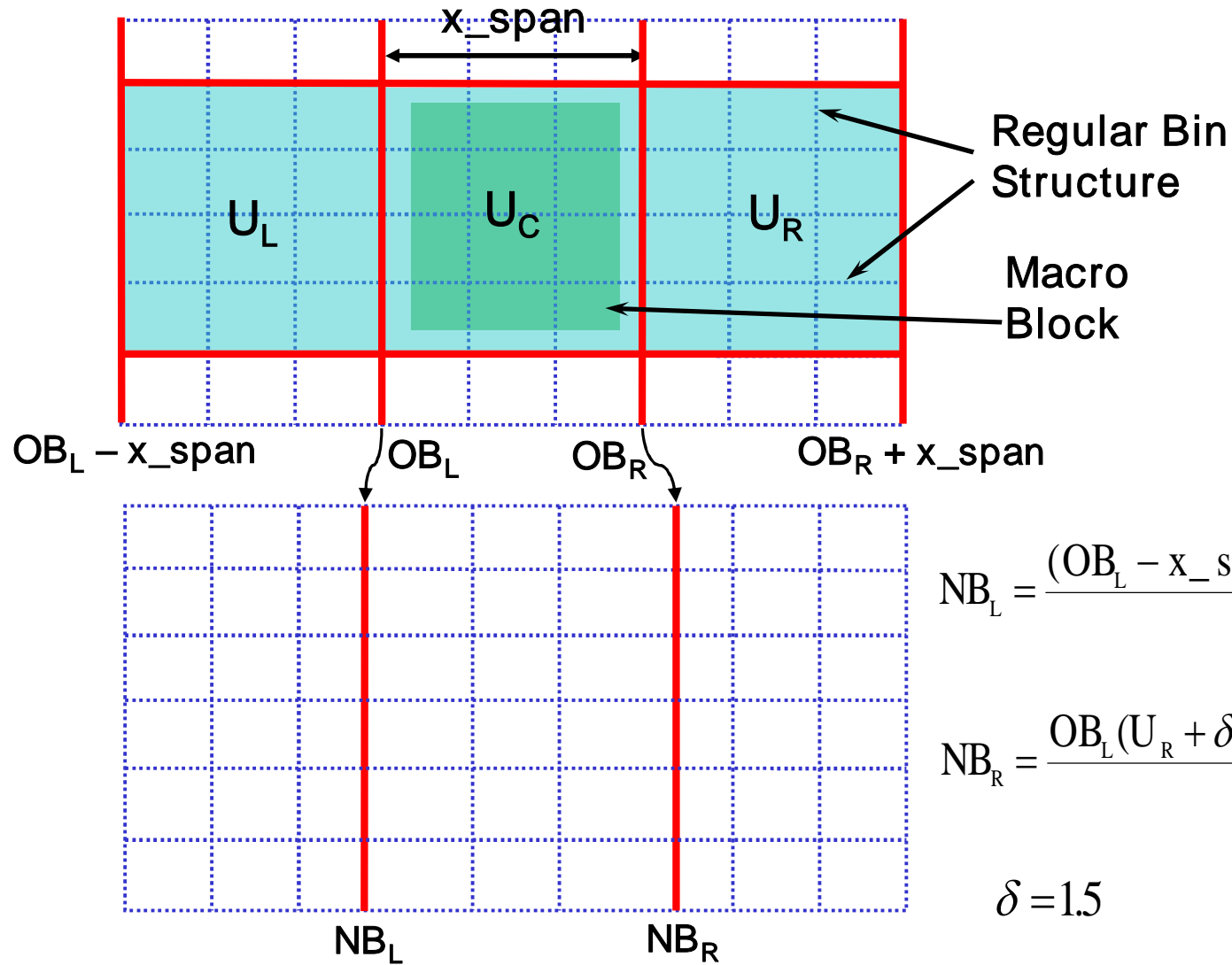
Cell Shifting for Standard Cells



$$NB_i = \frac{OB_{i-1}(U_{i+1} + \delta) + OB_{i+1}(U_i + \delta)}{(U_{i+1} + \delta) + (U_i + \delta)}$$

where $\delta = 1.5$ to prevent cross-over of bin boundaries in the unequal bin structure

Cell Shifting for macros



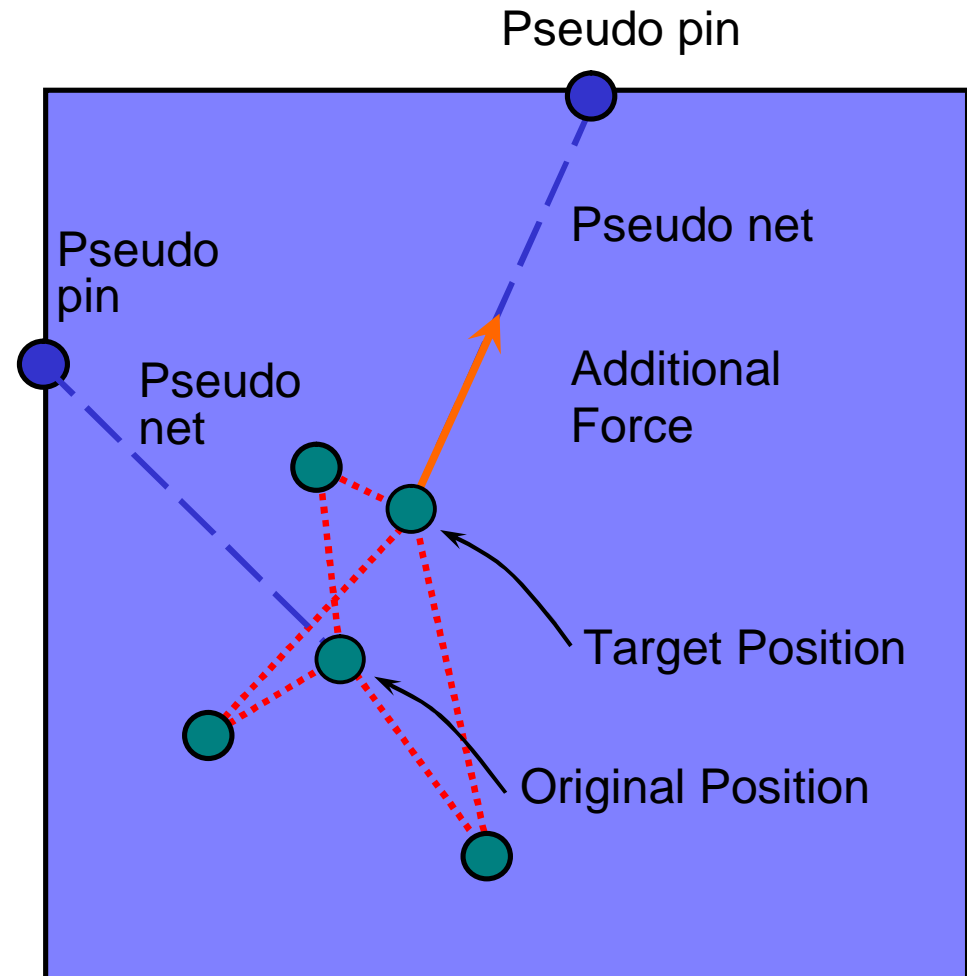
$$NB_L = \frac{(OB_L - x_span)(U_C + \delta) + OB_R(U_L + \delta)}{U_L + U_C + 2\delta}$$

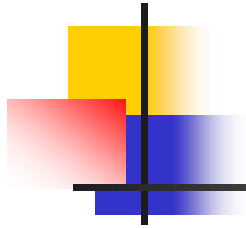
$$NB_R = \frac{OB_L(U_R + \delta) + (OB_R + x_span)(U_C + \delta)}{U_R + U_C + 2\delta}$$

$$\delta = 1.5$$

Pseudo pin and Pseudo net

- Need to add forces to prevent cells from collapsing back
- Done by adding pseudo pins and pseudo nets
- Only diagonal and linear terms of the quadratic system need to be updated
- Takes a single pass of $O(n)$ time to regenerate quadratic system matrix





Outline

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3. Iterative Local Refinement

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Macro Block Legalization

- Formulated as a fixed-outline floorplanning problem to resolve overlaps with minimum perturbation
- Sequence pair (SP) to represent a floorplan
- Use low temperature simulated annealing to generate a good sequence pair
- Solve the problem independently for x and y

Minimum Perturbation Floorplan Realization Problem

Given: n macros with target coordinates (x_i^*, y_i^*) for $i = 1, \dots, n$ and a sequence pair (p, q)

Determine: Legalized Coordinates (x_i, y_i) s.t. $\sum_{i=1}^n |x_i - x_i^*| + |y_i - y_i^*|$ is minimized.



Iterative Clustering Algorithm

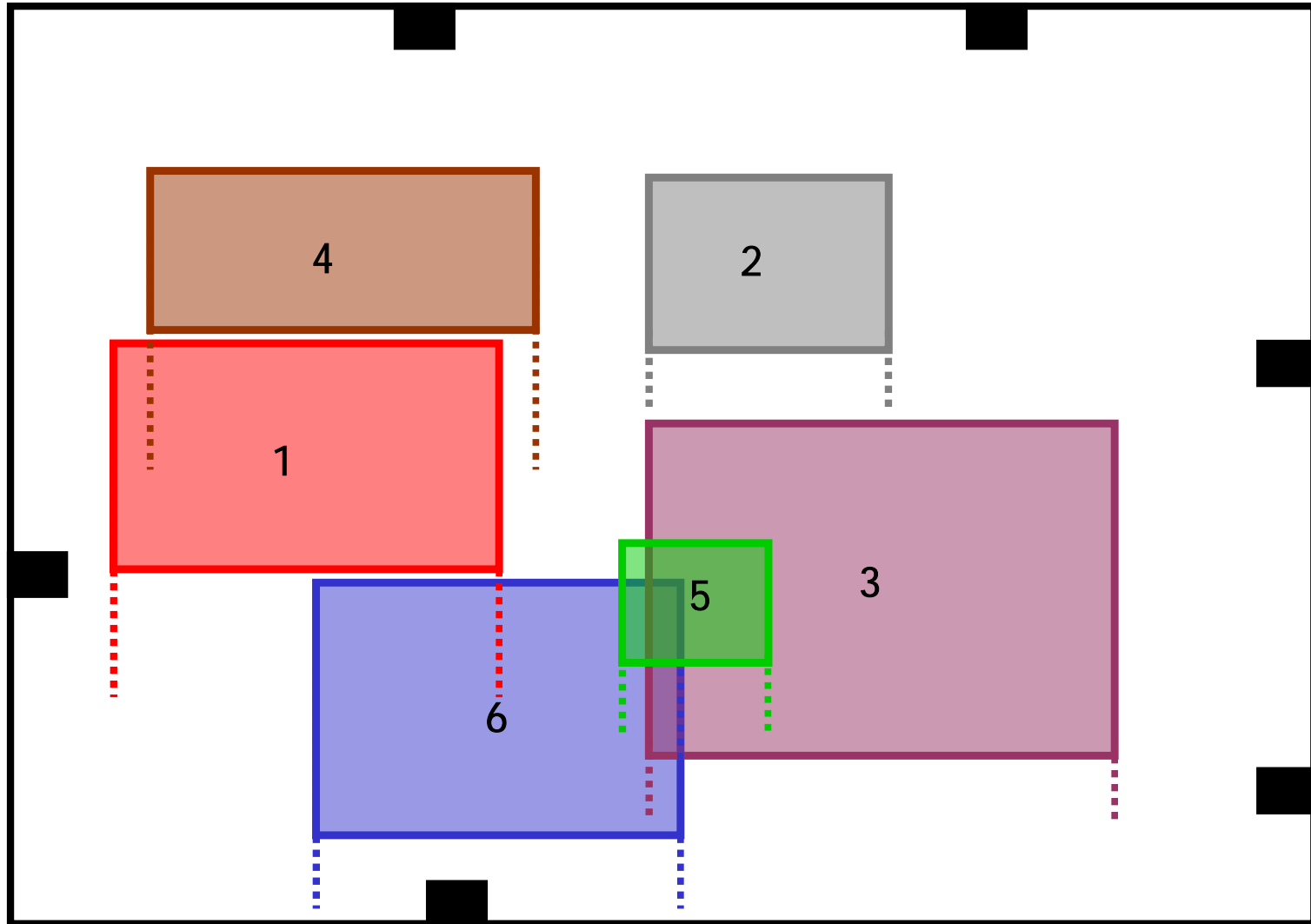
- Solves the Minimum Perturbation Floorplan Realization Problem

Main Idea:

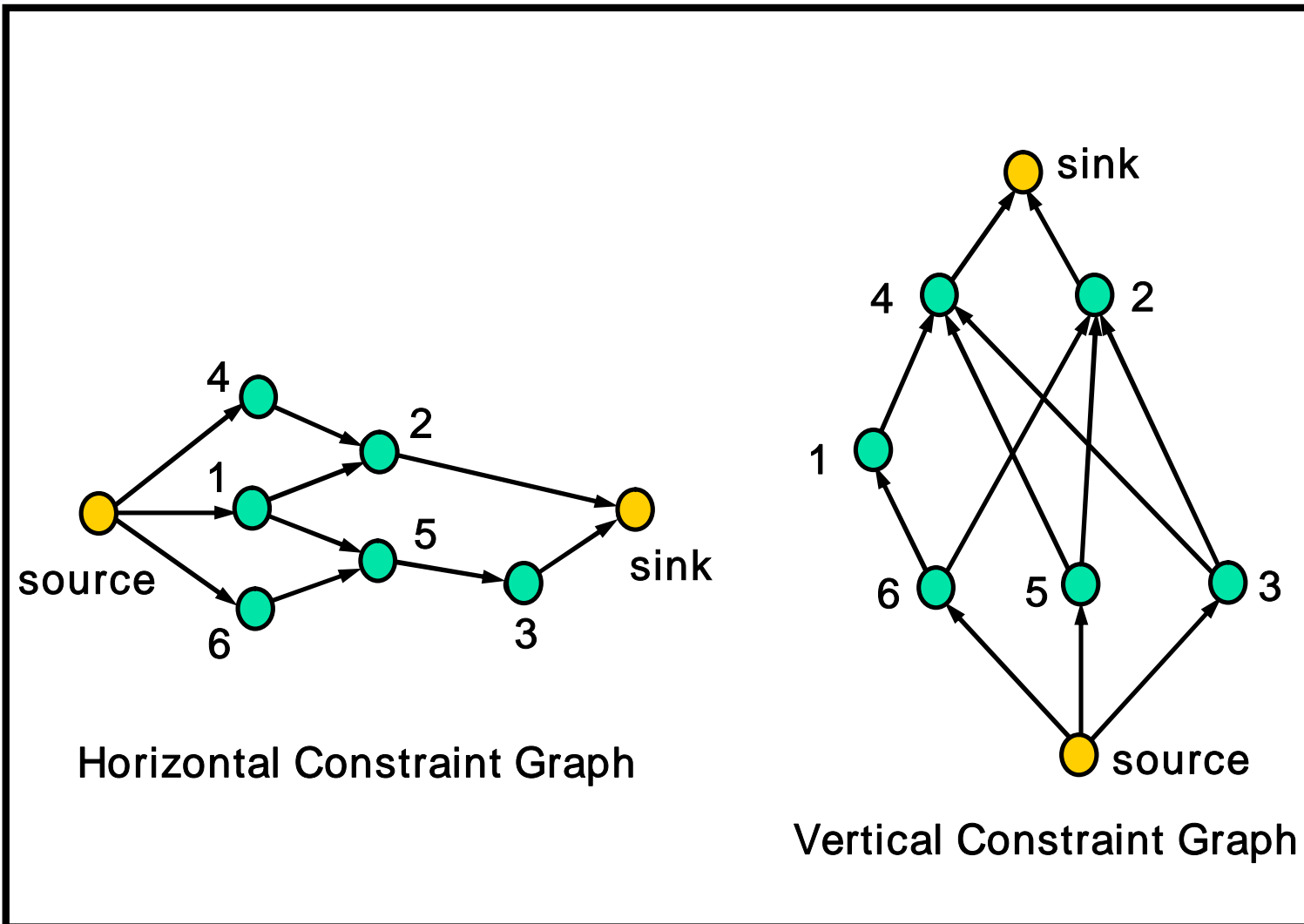
- If we know which macros to cluster in the optimal solution, then the position of the cluster is easy to find.
- To find correct clustering:
 - Add macros one by one from left to right.
 - Form cluster if overlap occurs.
 - Shift clusters to the left towards their optimal positions
- Optimal for a given sequence pair
- Runtime Complexity: $O(n^2)$. Very efficient in practice.



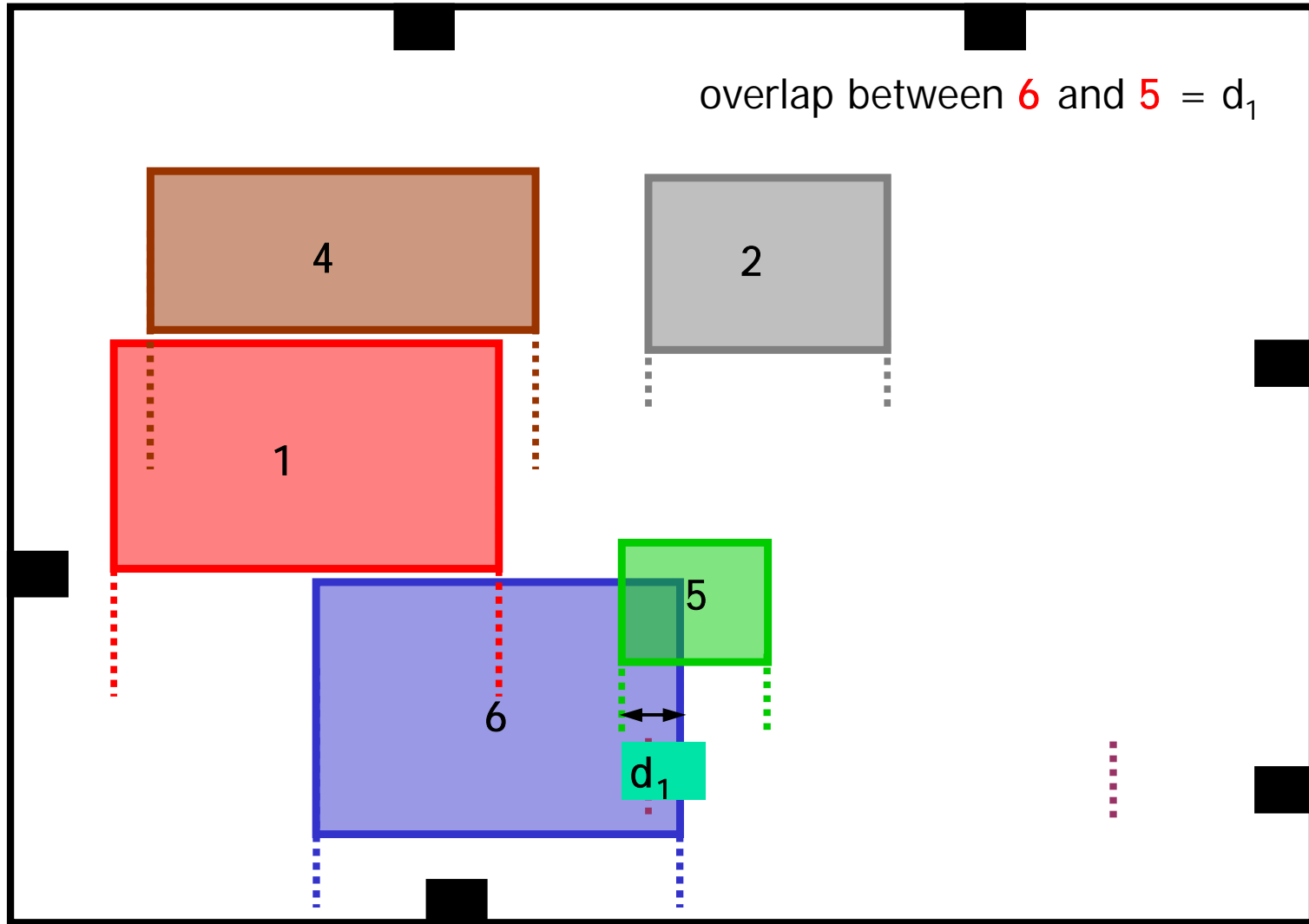
(1) Initial Placement of macros with horizontal overlap



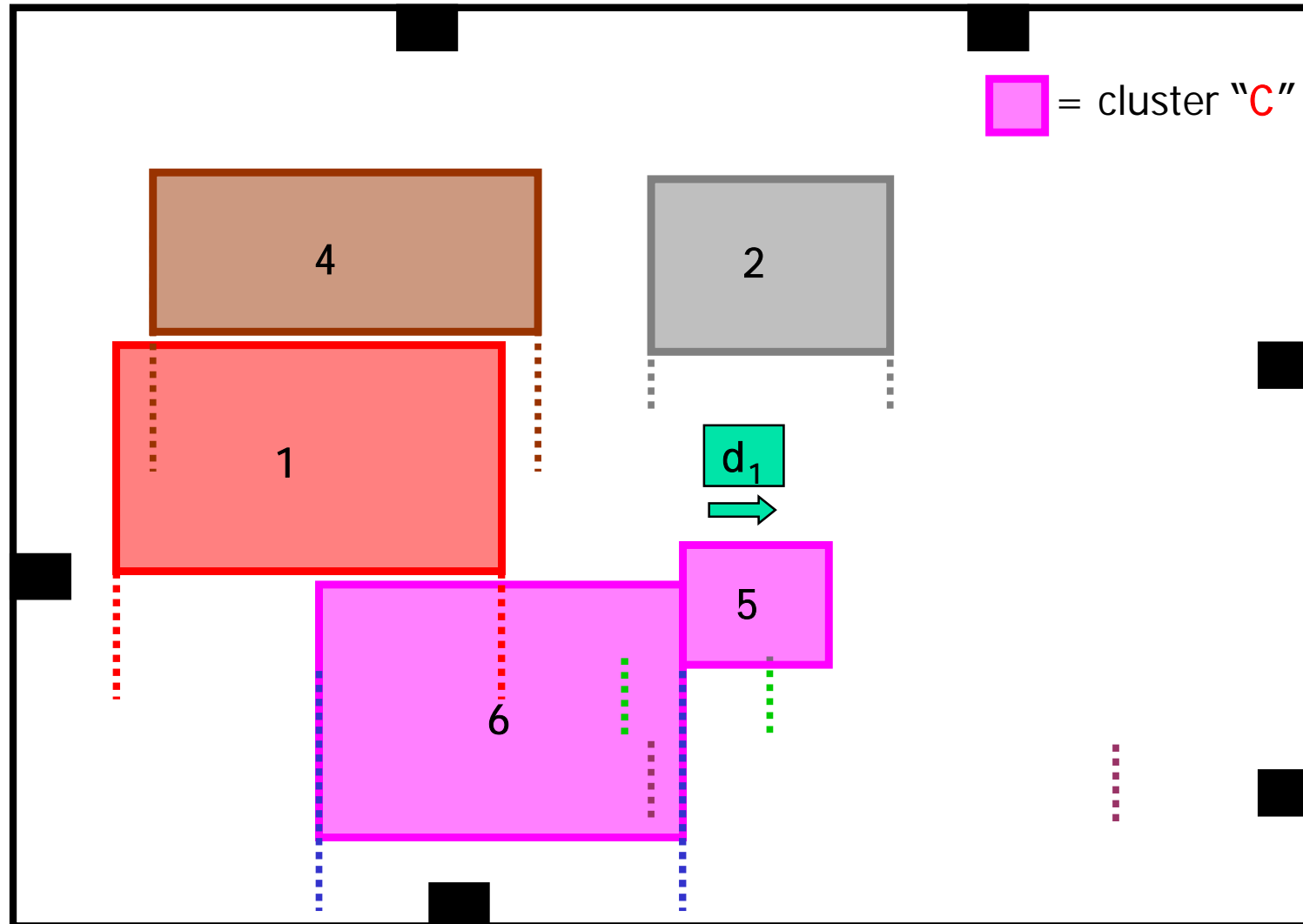
(2) Best Sequence Pair $(p, q) = (4\ 1\ 2\ 6\ 5\ 3, 6\ 1\ 5\ 3\ 4\ 2)$



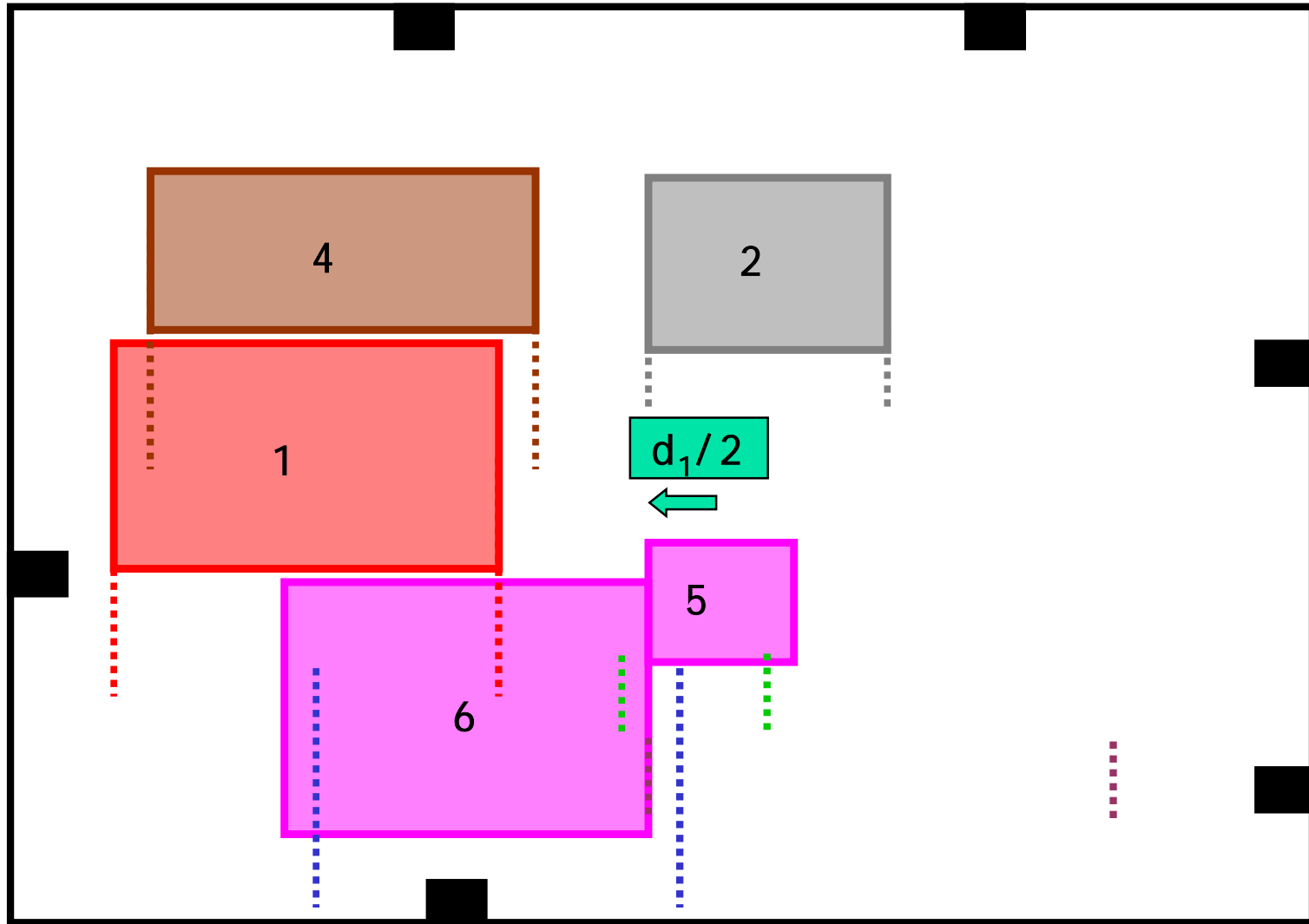
(3) Go through horizontal sequence and add macros from left to right; macros added: 4, 1, 2, 6, 5



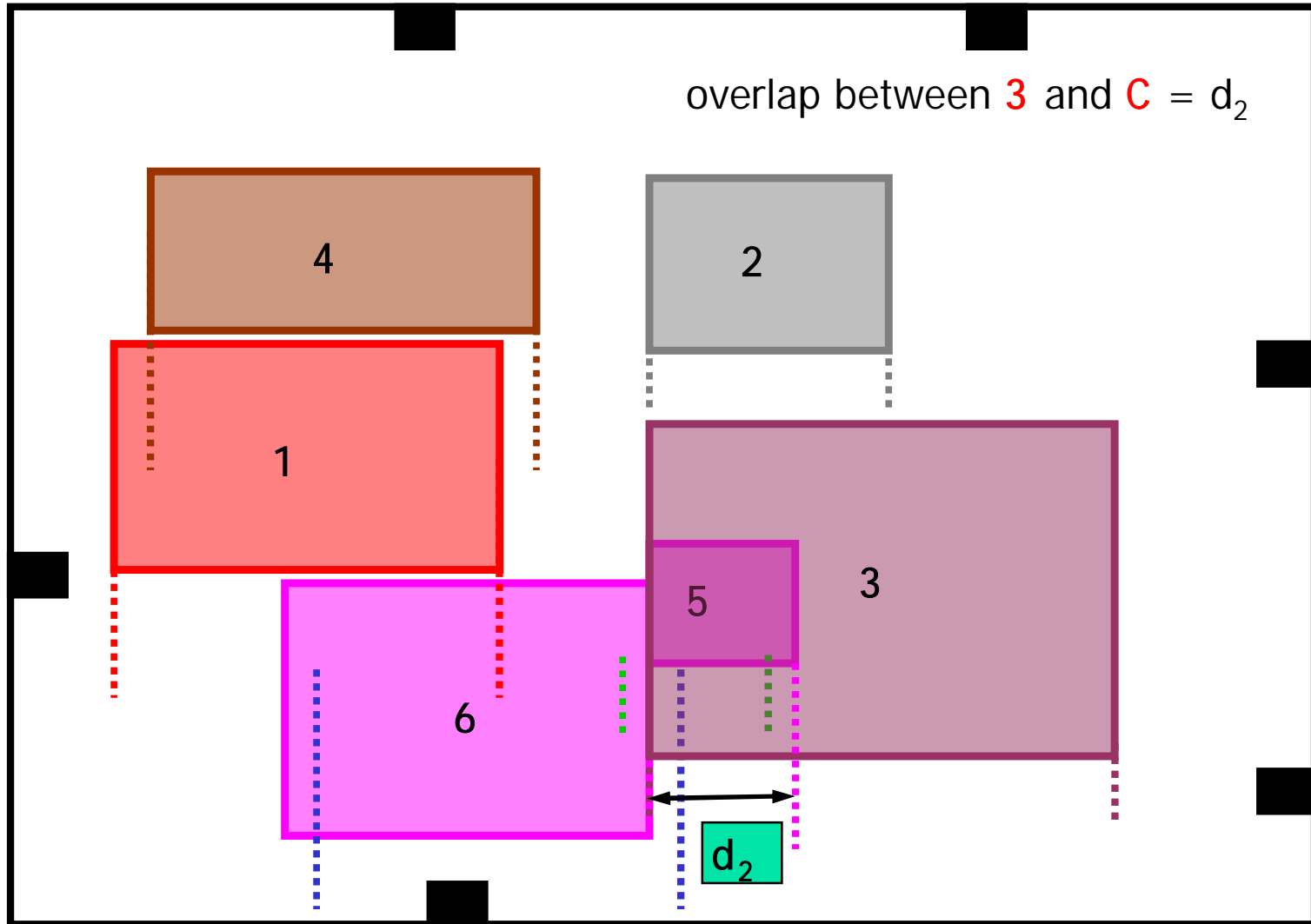
(4) Shift macro 5 from target position because of overlap and form cluster



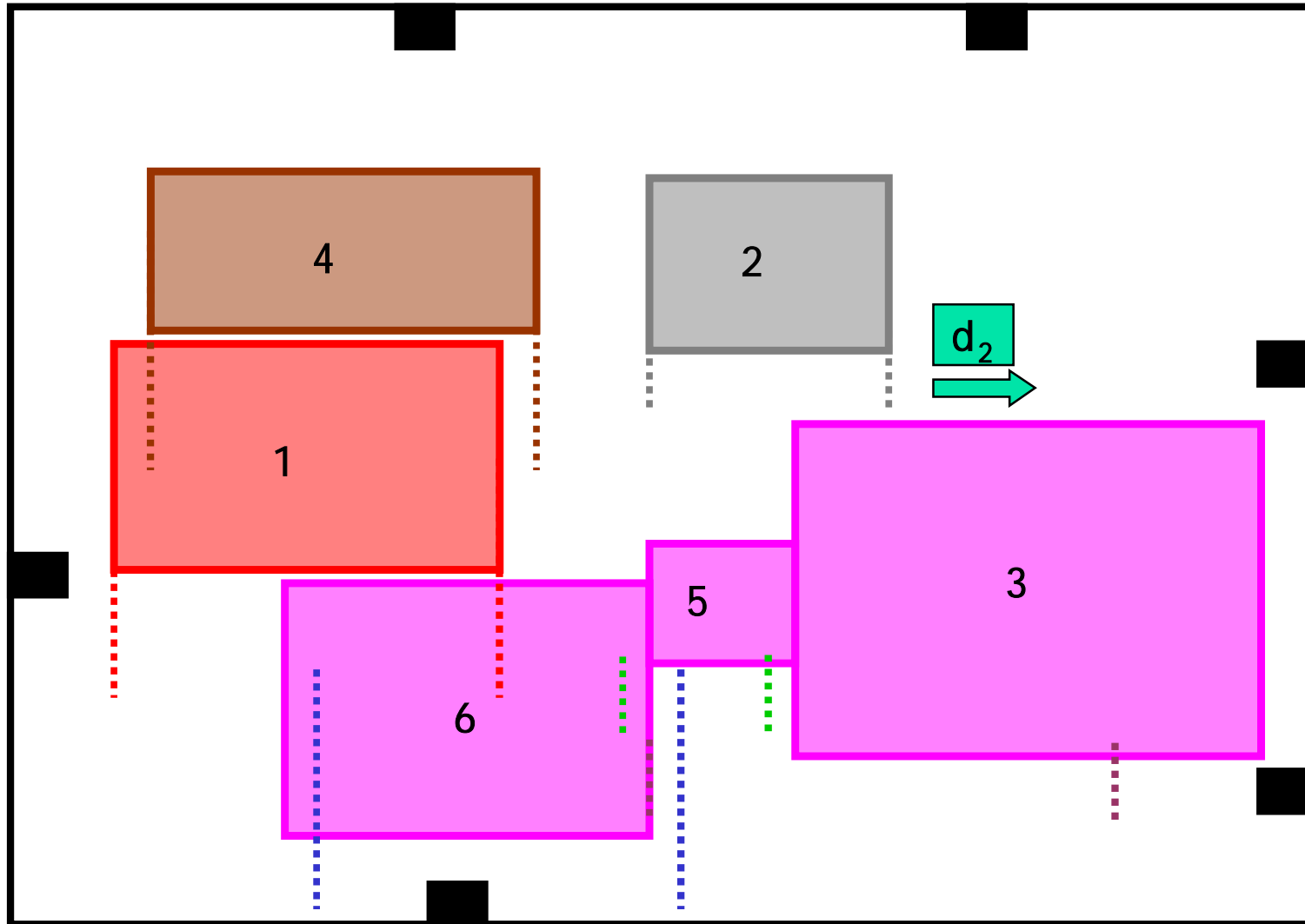
(5) Shift cluster **C** to the left towards its optimal position



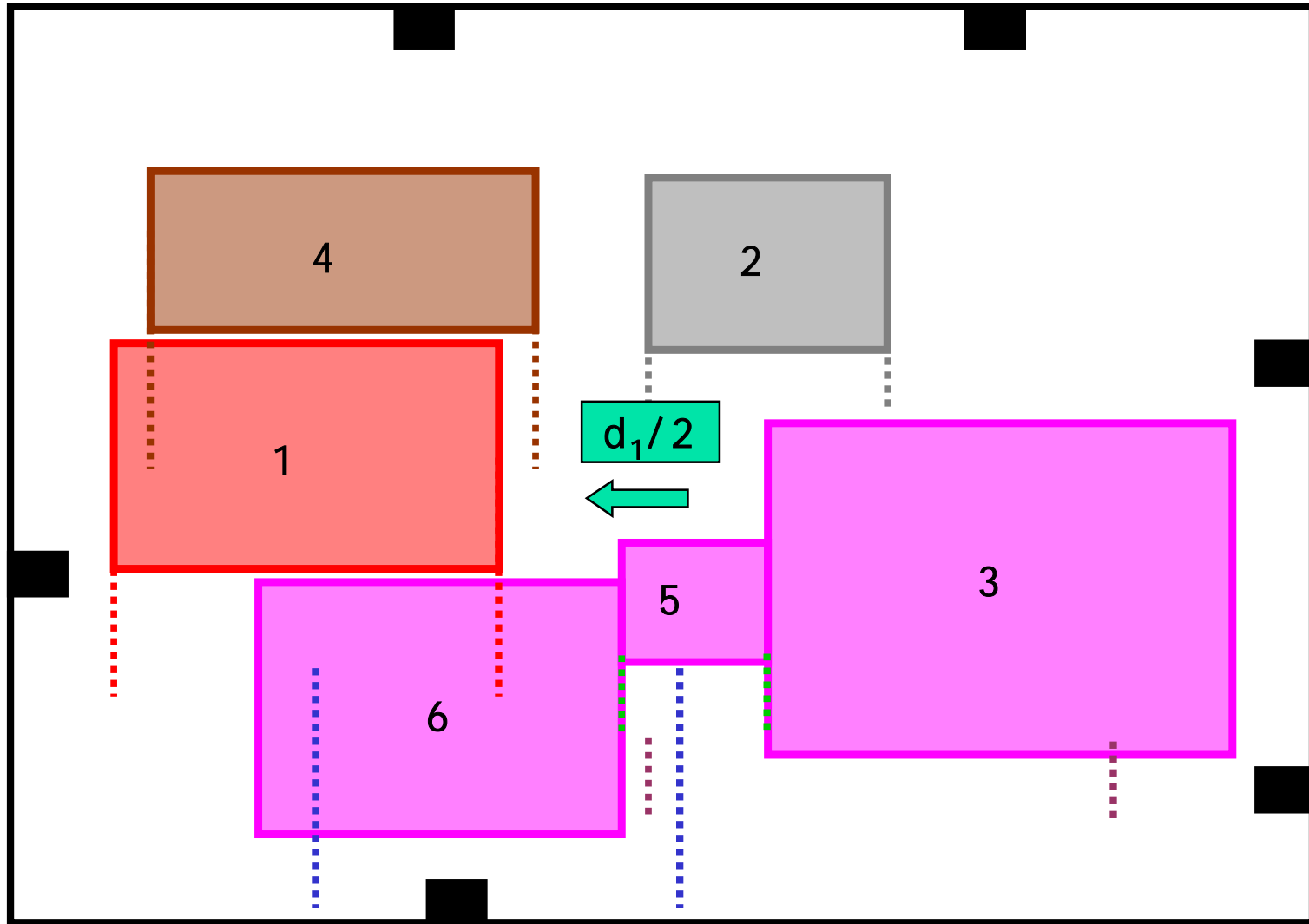
(6) Add next macro in the sequence (macro 3)



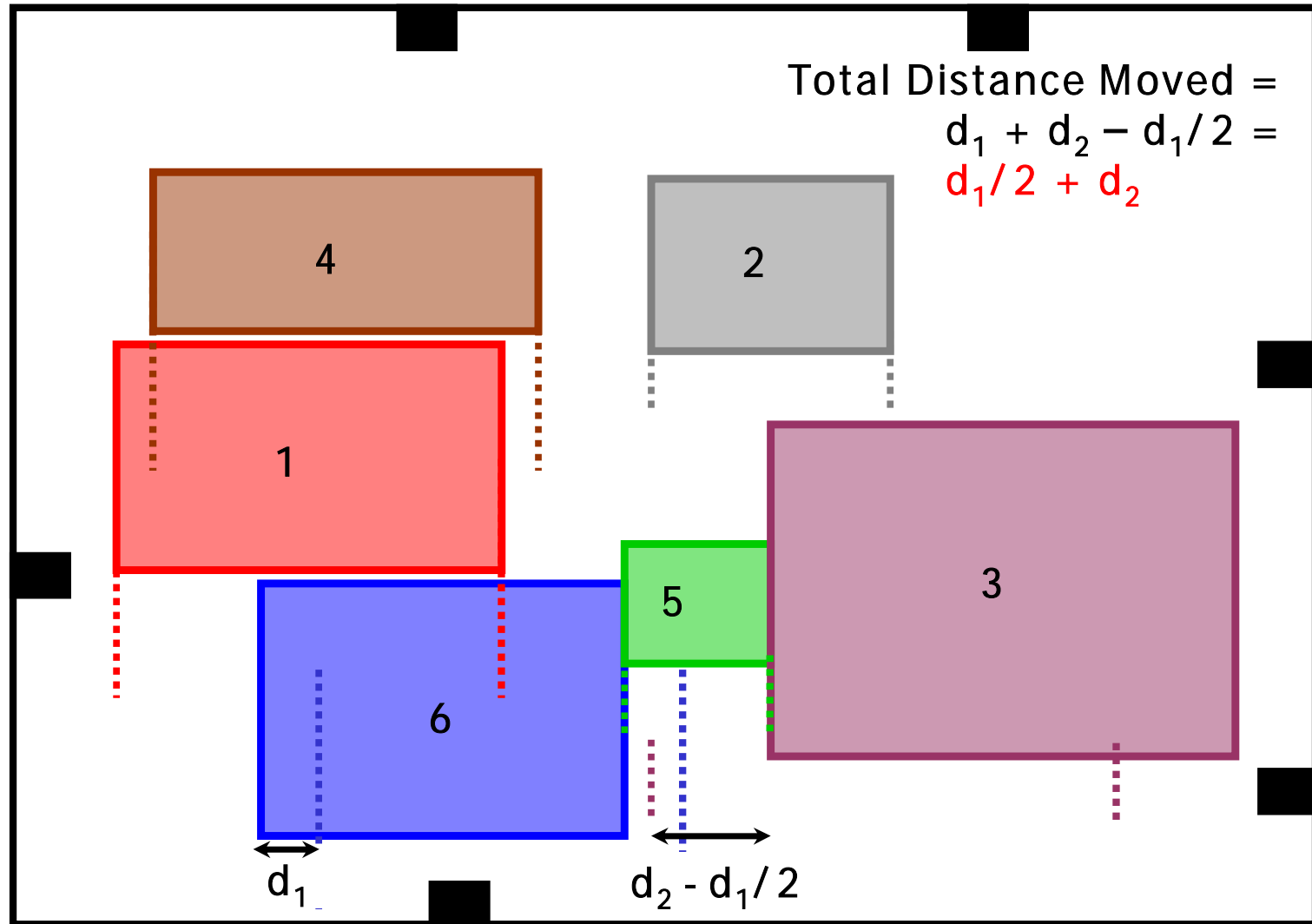
(7) Shift macro **3** from target position because of overlap and form cluster

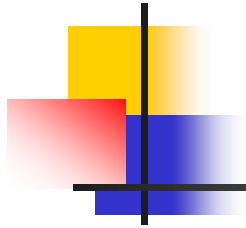


(8) Shift cluster **C** to the left towards its optimal position

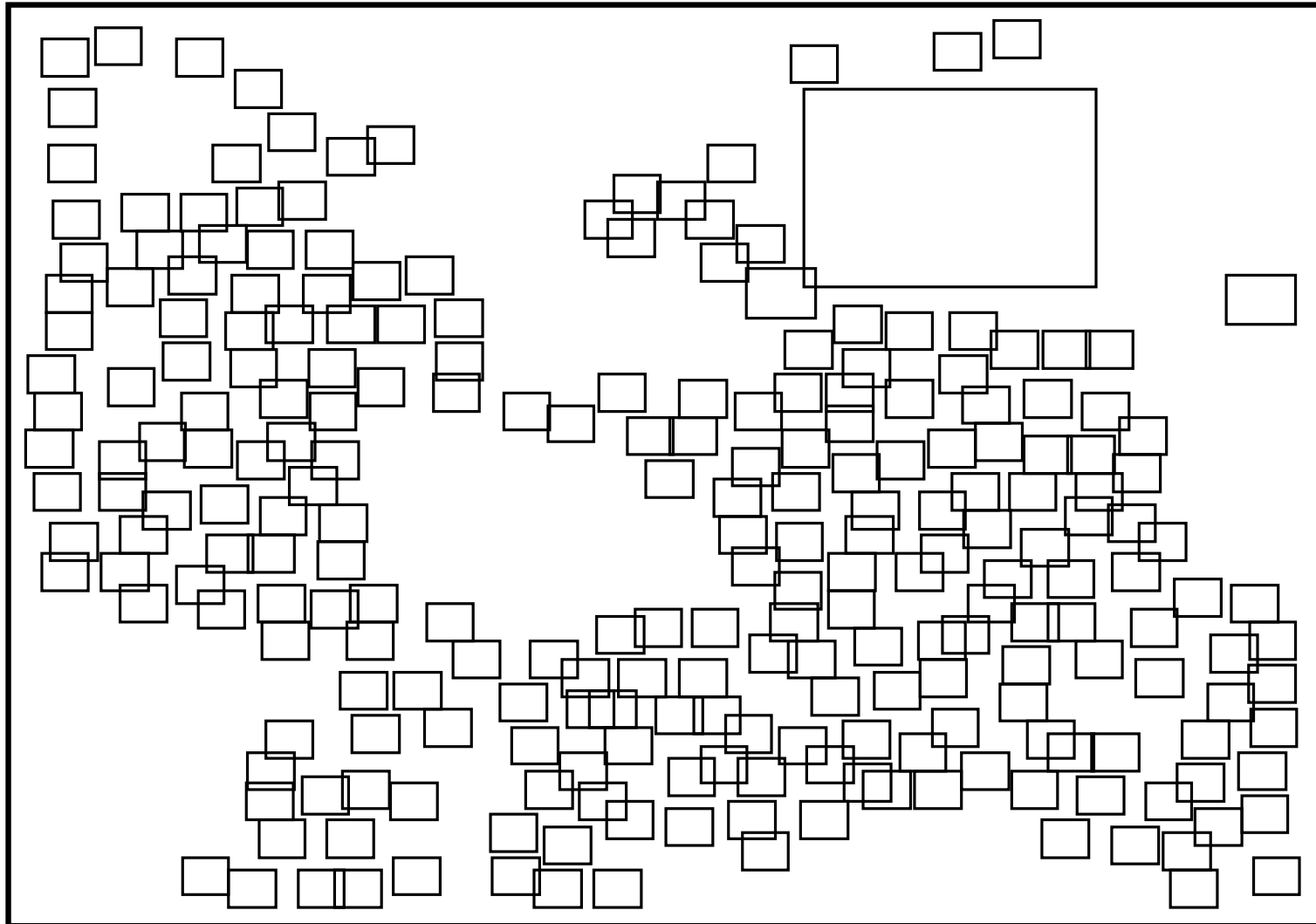


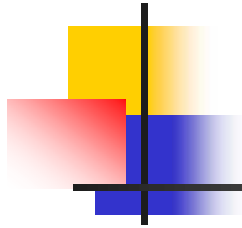
(9) Final Position of macros with no overlap



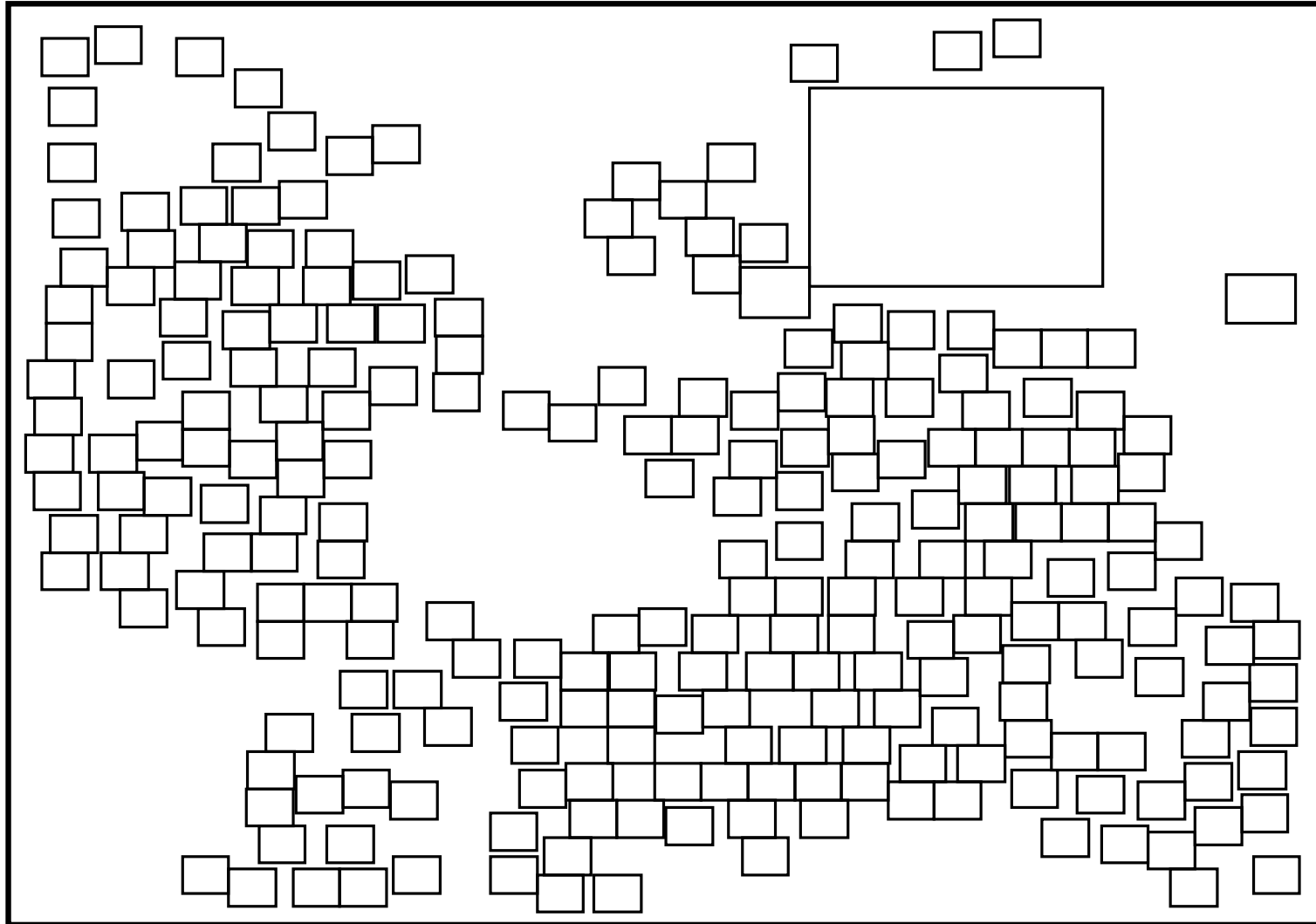


Macros Before Legalization (ibm01)





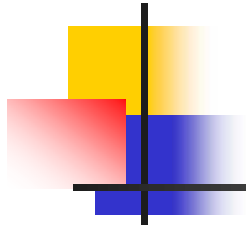
Macros After Legalization (ibm01)





Legalize Standard Cells

- Divide rows in the placement region not occupied by macros into segments.
- To Satisfy Segment Capacities
 - Iteratively go through all segments.
 - For each cell in a segment, consider moving it to 8 nearest segments
 - Compute a score for each movement based on
 - Half-perimeter wirelength (HPWL) reduction
 - Cell density at the source and destination segments
 - Move to the segment with highest positive score
(Do not move if no positive score)
- Legalize cells within segments



Outline

Stage 1: Global Placement

1. Hybrid Net Model
2. Cell Shifting for mixed-mode designs
3. Iterative Local Refinement

Stage 2: Legalization

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Stage 3: Detailed Placement

1. Global Swap
2. Vertical Swap
3. Local Re-ordering
4. Single-segment Clustering



Detailed Placement: Approach

Perform *Single-Segment Clustering*

Repeat

Perform *Global Swap*

Perform *Vertical Swap*

Perform *Local Re-ordering*

Until no significant improvement

Repeat

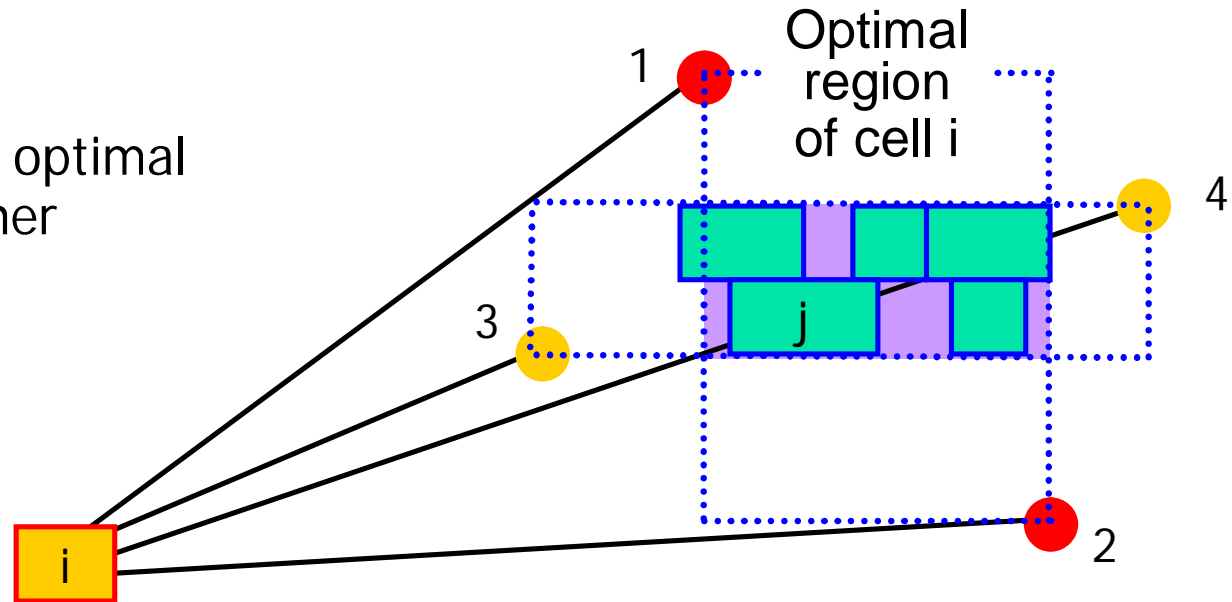
Perform *Single-Segment Clustering*

Until no significant improvement

Main DP Technique: Global Swap

- Idea:

move a cell to its optimal position while other cells are fixed



- Major steps:

- For each standard cell i , get its optimal region
- For every candidate cell j in the optimal region of cell i
 - compute the benefit to swap i with j
- For every candidate space s in the optimal region of cell i
 - compute the benefit to swap i with s
- Pick the cell or space with best benefit to perform the swap



Other DP Techniques

- Vertical Swap:
 - Move a cell vertically toward its optimal region to reduce the wirelength.
 - Interleave with global swap to accelerate convergence.
- Local Re-ordering
 - For 3 consecutive cells in a segment, get the best order in terms of wirelength
- Fixed-Order Single Segment Clustering
 - Cluster cells within segments to further reduce wirelength



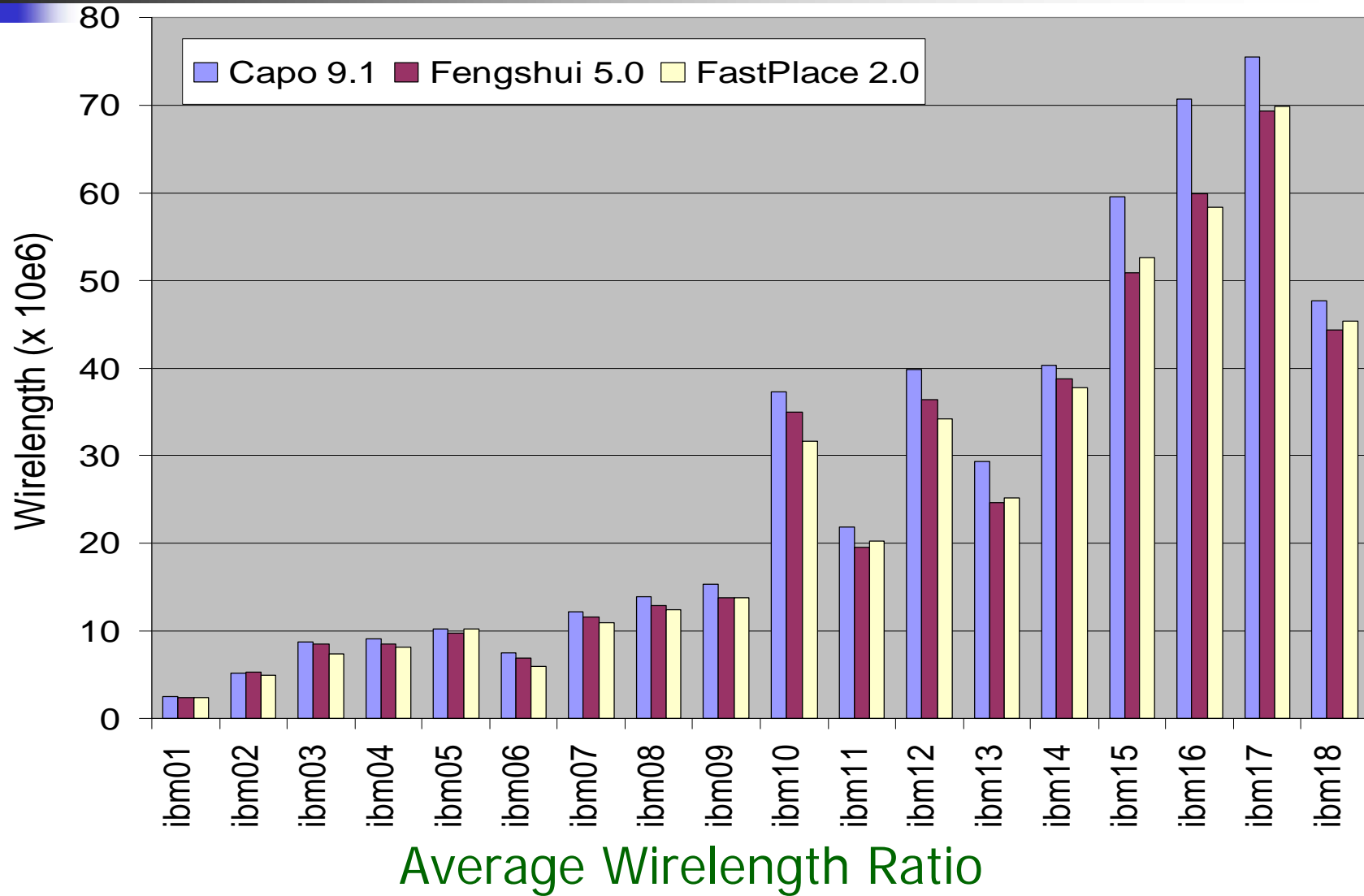
Experimental Setup

- ISPD02 IBM-MS Mixed-size placement benchmarks
- 12k – 210k movable nodes
- up to 786 macro blocks
- 20% whitespace

- FastPlace 2.0 implemented in C
- Compared with:
 - Capo 9.1
 - Fengshui 5.0

- All experiments are on an Intel Xeon, 3.06GHz CPU

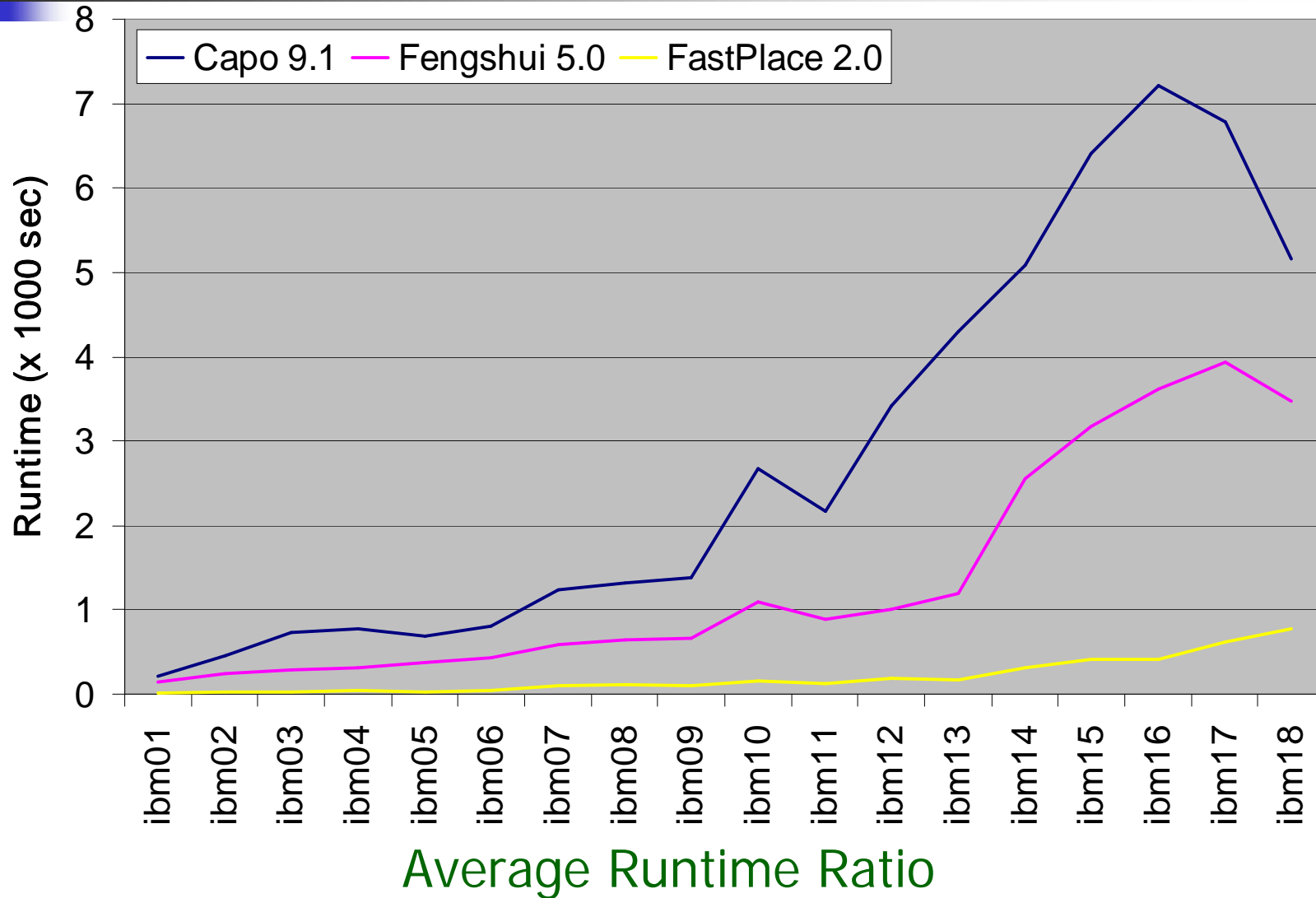
Half-Perimeter Wirelength



Capo / FastPlace : **1.12**

Fengshui / FastPlace : **1.03**

Runtime



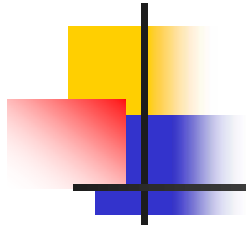
Capo / FastPlace : **16.84**

Fengshui / FastPlace : **7.84**



Conclusions and Future Work

- **FastPlace 2.0**: An Efficient analytical placer for Mixed-Mode designs
 - Cell Shifting for macro blocks
 - Iterative Clustering Algorithm for macro block legalization
 - Efficient standard-cell legalization in the presence of macros
 - Efficient and effective detailed placement algorithm
- **12% better** in wirelength and **16.8X faster** than Capo 9.1
- **3% better** in wirelength and **7.8X faster** than Fengshui 5.0
- Need to handle rotation and mirroring for macro blocks



Thank You

Questions ??



Iterative Clustering Algorithm

1. Find the immediate left and right neighbors of all macros
2. for $i = 1$ to n
3. Place macro p_i in its target position
4. Let C be a new cluster consisting of p_i
5. while C overlaps with other clusters do
6. Merge C with the closest cluster on its left
7. Let C be the new cluster formed
8. Shift C to its optimal position
9. if macro m in C is at its target position do
10. Detach m from C if necessary
 and goto step 8
11. endwhile
12. endfor

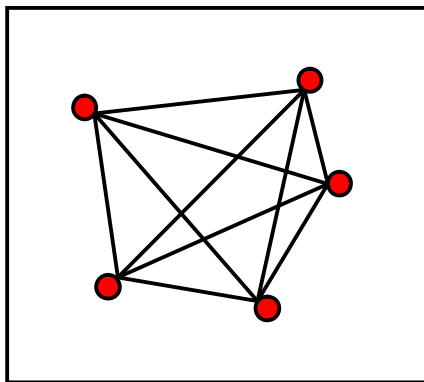


Analytical Placement Formulation

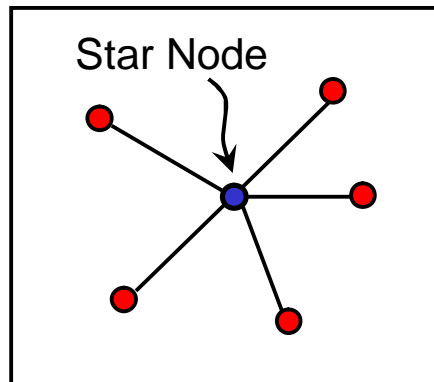
- Let (x_i, y_i) = Coordinates of the center of cell i
 w_{ij} = Weight of the net between cell i and cell j
 \mathbf{x}, \mathbf{y} = Solution vectors
- Cost of the net between cell i and cell j
$$= \frac{1}{2} w_{ij} \left((x_i - x_j)^2 + (y_i - y_j)^2 \right)$$
- Total cost = $\frac{1}{2} \mathbf{x}^T \mathbf{Q} \mathbf{x} + \mathbf{d}_x^T \mathbf{x} + \frac{1}{2} \mathbf{y}^T \mathbf{Q} \mathbf{y} + \mathbf{d}_y^T \mathbf{y} + \text{const}$
- Analytical Placement Framework:
repeat
Solve the convex quadratic program
Spread the cells
until the cells are evenly distributed

Hybrid Net Model

- Need to replace multi-pin nets by 2-pin nets in the convex QP formulation
- Use Incomplete Cholesky Conjugate Gradient (ICCG) solver
- Runtime is proportional to # of non-zero entries in Q
- Each non-zero entry in Q corresponds to one 2-pin net
- Traditionally, placers model each multi-pin net by a clique
- High-degree nets will generate a lot of 2-pin nets
- Slow down convex QP algorithms significantly



Clique Model



Star Model

# pins	Net Model
2	Clique
3	Clique
4	Star
5	Star
6	Star
...	...