

Memory Size Computation for Multimedia Processing Applications

Hongwei Zhu

Ilie I. Luican

Florin Balasa

University of Illinois at Chicago





Outline

- Introduction: research context
- The memory size computation problem
- Storage requirements of an array reference
- Exact memory size computation using data-dependence analysis
- Experimental results
- Conclusions



Introduction: Research Context

Real-time multidimensional processing systems

(video and image processing, real-time 3D rendering, audio and speech coding, medical imaging, etc.)

- A large part of power dissipation is due to

data transfer and data storage

Fetching operands from an off-chip memory for addition consumes 33 times more power than the computation

[Catthoor 98]

- Area cost often largely dominated by memories



Introduction: Research Context

In the early years of high-level synthesis

memory management tasks tackled at scalar level



Algebraic techniques -- similar to those used
in modern compilers -- allow to handle
memory management at non-scalar level

Requirement: addressing the entire class of affine specifications

- multi-dimensional signals with (complex) affine indexes
- loop nests having as boundaries affine iterator functions
- conditions – relational and / or logical operators of affine fct.



The Memory Size Computation Problem

```
optDelta[0] = 0 // Code derived from a motion
                // detection algorithm [ Chan 93 ]
for (i=8; i<=120; i++)
  for (j=6; j<=120; j++)
    { Delta[i][j][0] = 0
      for (k=i-8; k<=i+8; k++)
        for (l=j-8; l<=j+8; l++)
          Delta[i][j][17*(k-i) + l - j + 145] = A[i][j] - A[k][l]@1
          + Delta[i][j][17*(k-i) + l - j + 144]
          optDelta[113*l + j - 911] = Delta[[i][j][289]
          + optDelta[113*l + j - 912]
    }
Opt = optDelta[12769]
```

The Memory Size Computation Problem

How many memory locations are necessary to store the signals of a multimedia algorithm



Any scalar signal must be stored only during its lifetime



Signals having disjoint lifetimes can share the same location

The number of scalars in the illustrative algorithm: 3,749,063
The amount of necessary storage: 33,284

This paper presents an algorithm computing exactly the amount of storage locations

Computation of Array Reference Size

```
for (i=0; i<=4; i++)
```

```
    for (j=0; j <= 2i && j <= -i+6; j++)
```

```
        ... A [2i+3j+1] [5i+j+3] [4i+6j+2] ...
```

How many memory locations are necessary
to store the array reference

A [2i+3j+1] [5i+j+3] [4i+6j+2]

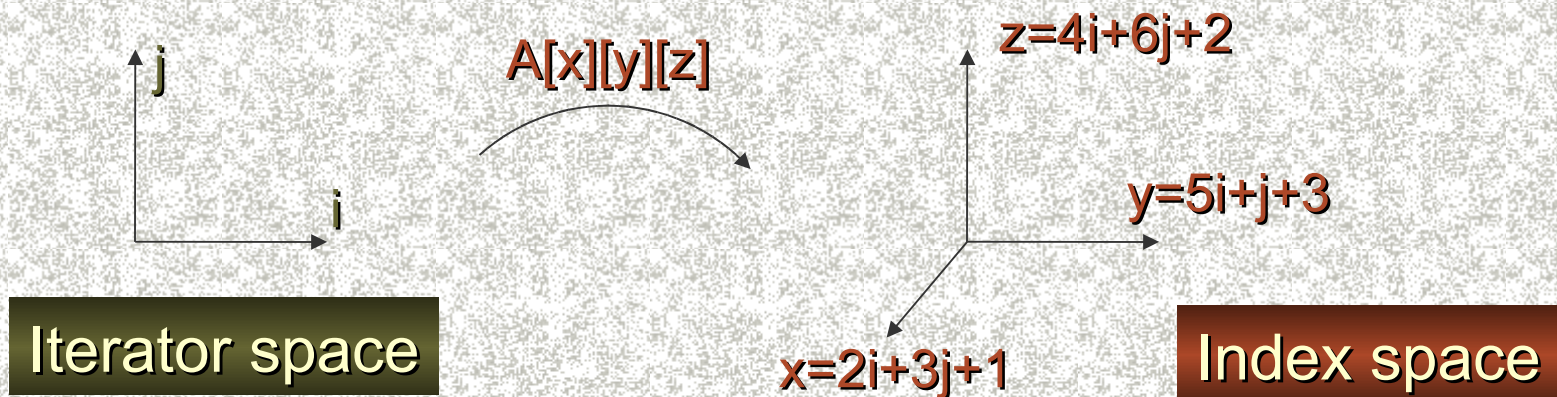


Computation of Array Reference Size

```
for (i=0; i<=4; i++)
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  for (j=0; j <= 2i && j <= -i+6; j++)
```

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    ... A [2i+3j+1] [5i+j+3] [4i+6j+2] ...
```

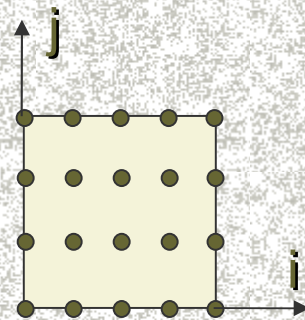


Computation of Array Reference Size

```
for (i=0; i<=511; i++)
```

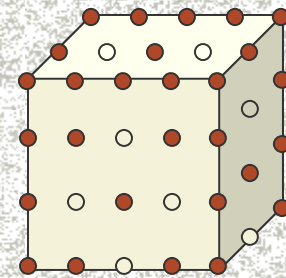
```
  for (j=0; j<=511; j++)
```

```
    ... A [2i+3j+1] [5i+j+2] [4i+6j+3] ...
```



Iterator space

$A[x][y][z]$



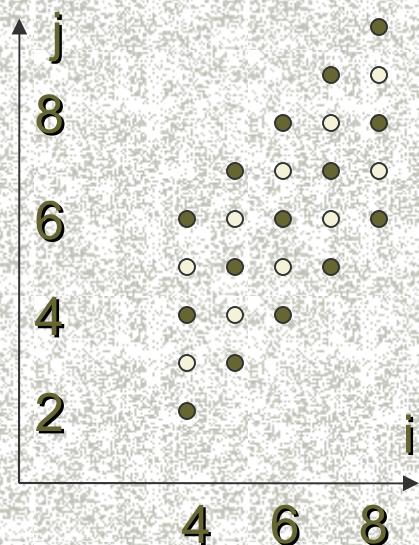
Index space

Computation of Array Reference Size

Remark The iterator space may have “holes”, too

for ($i=4; i \leq 8; i++$)

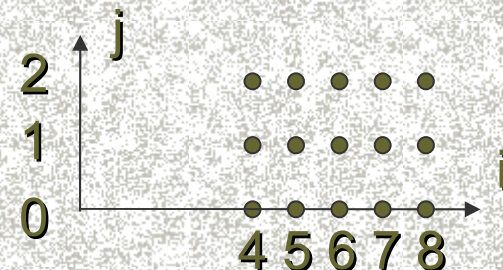
for ($j=i-2; j \leq i+2; j+=2$) ... $C[i+j]$...



for ($i=4; i \leq 8; i++$)

for ($j=0; j \leq 2; j++$) ... $C[2i+2j-2]$...

normalization



Computation of Array Reference Size

```
for (i=0; i<=4; i++)
```

```
  for (j=0; j <= 2i && j <= -i+6; j++)
```

```
    ... A [2i+3j+1] [5i+j+3] [4i+6j+2] ...
```

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 5 & 1 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix}$$

Index space

← affine
mapping

Iterator space

$$0 \leq i \leq 4, \quad 0 \leq j \leq 2i, \quad j \leq -i+6$$

Computation of Array Reference Size

Any array reference can be modeled as a linearly bounded lattice (LBL)

$$\text{LBL} = \{ \mathbf{x} = \mathbf{T} \cdot \mathbf{i} + \mathbf{u} \mid \mathbf{A} \cdot \mathbf{i} \geq \mathbf{b} \}$$

Affine mapping

Iterator space

- scope of nested loops, and
- iterator-dependent conditions

LBL

← affine
mapping

Polytope

Computation of Array Reference Size

The size of the array reference
is the size of its index space – an LBL !!

$$\text{LBL} = \{ \mathbf{x} = \mathbf{T} \cdot \mathbf{i} + \mathbf{u} \mid \mathbf{A} \cdot \mathbf{i} \geq \mathbf{b} \}$$

$$f: \mathbf{Z}^n \longrightarrow \mathbf{Z}^m \quad f(\mathbf{i}) = \mathbf{T} \cdot \mathbf{i} + \mathbf{u}$$

Is function f a one-to-one mapping ??



If YES

$$\text{Size}(\text{index space}) = \text{Size}(\text{iterator space})$$



Computation of Array Reference Size

$$f: \mathbf{Z}^n \longrightarrow \mathbf{Z}^m \quad f(\mathbf{i}) = \mathbf{T} \cdot \mathbf{i} + \mathbf{u}$$

$$\mathbf{P} \cdot \mathbf{T} \cdot \mathbf{S} = \begin{bmatrix} \mathbf{H} & \mathbf{0} \\ \mathbf{G} & \mathbf{0} \end{bmatrix} \quad \text{Reduced Hermite Form}$$

H - nonsingular lower-triangular matrix

S - unimodular matrix

P - row permutation

Computation of Array Reference Size

Case 1 rank(**H**)=n

function f is a one-to-one mapping

for (i=0; i<=4; i++)

for (j=0; j<=2i && j<=-i+6; j++)

... A [2i+3j+1] [5i+j+3] [4i+6j+2] ...

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 5 & 1 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} i \\ j \end{pmatrix} + \begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix}$$

$$\mathbf{P} \cdot \mathbf{T} \cdot \mathbf{S} = \mathbf{I}_3 \begin{pmatrix} 2 & 3 \\ 5 & 1 \\ 4 & 6 \end{pmatrix} \begin{pmatrix} -1 & 3 \\ 1 & -2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ -4 & 13 \\ 2 & 0 \end{pmatrix} \begin{matrix} \mathbf{H} \\ \mathbf{G} \end{matrix}$$

locations $A[][] = \text{size} (0 \leq i \leq 4 , 0 \leq j \leq 2i, -i+6) = 21$

Computation of Array Reference Size

Case 2 rank(**H**) < n

function f is not
a one-to-one mapping

for (i=0; i<=511; i++)

for (j=0; j<=511; j++) ...

for (k=0; k<=511; k++) ... **B** [i+k] [j+k] ...

$$\mathbf{P} \cdot \mathbf{T} \cdot \mathbf{S} = \mathbf{I}_2 \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ & \mathbf{H} & \mathbf{0} \end{bmatrix}$$

$$\{ 0 \leq i, j, k \leq 511 \} \longrightarrow \{ 0 \leq I-K, J-K, K \leq 511 \}$$

locations **B** = size (0 ≤ I, J ≤ 1022 , I-511 ≤ J ≤ I+511) = 784,897
 (whereas the size of the iterator space is 512³ = 134,217,728)

Computation of Array Reference Size

Computation of the size of an integer polytope

```
for (i=0; i<=4; i++)
```

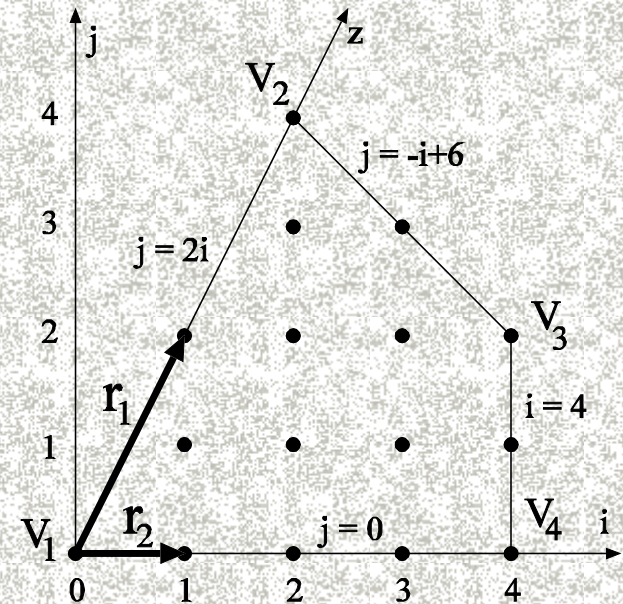
```
  for (j=0; j <= 2i && j <= -i+6; j++)
```

```
    ... A [2i+3j+1] [5i+j+3] [4i+6j+2]
```

Step 1

Find the vertices of the iterator space and their supporting polyhedral cones

$$C(V_1) = \{r_1, r_2\} = \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\}$$





Computation of Array Reference Size

Computation of the size of an integer polytope (cont'd)

Step 2 Decompose the supporting cones into unimodular cones (Barvinok's decomposition algorithm)

$$C(V_1) = + \left\{ \begin{matrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 0 \\ -1 \end{bmatrix} \end{matrix} \right\} + \left\{ \begin{matrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \end{matrix} \right\}$$

Step 3 Find the generating function of each supporting cone

$$F(V_1) = + \frac{1}{(1-xy^2)(1-y^{-1})} + \frac{1}{(1-y)(1-x)}$$

Step 4 Find the number of monomials in the generating function of the whole polytope $F = F(V_1) + F(V_2) + \dots$

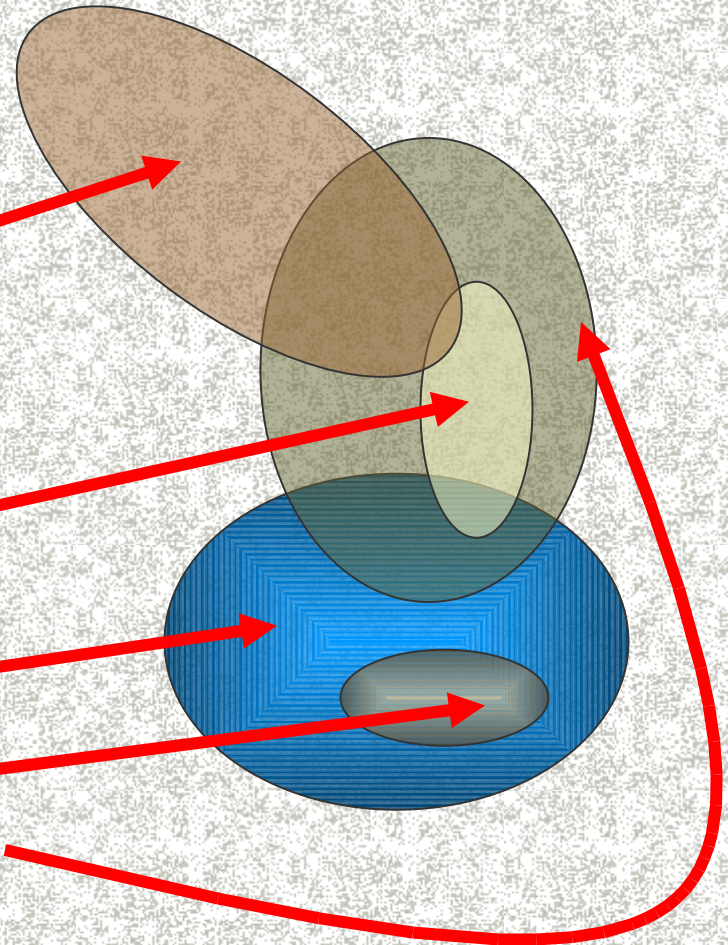
Memory Size Computation

```
# define n 6

for ( j=0; j<n ; j++ )
{ A [j] [0] = in0;
  for ( i=0; i<n ; i++ )
    A [j] [i+1] = A [j] [i] + 1;
}

for ( i=0; i<n ; i++ )
{ alpha [i] = A [i] [n+i];
  for ( j=0; j<n ; j++ )
    A [j] [n+i+1] =
      j < i ? A [j] [n+i] :
      alpha [i] + A [j] [n+i];
}

for ( j=0; j<n ; j++ ) B [j] = A [j] [2*n];
```



Memory Size Computation



Decompose the LBL's of the array refs.
into disjoint LBL's !!

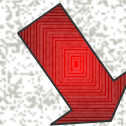
$LBL_1 \cap LBL_2 \rightarrow LBL$

$$\left\{ \begin{array}{l} LBL_1 = \{ \mathbf{x} = \mathbf{T}_1 \cdot \mathbf{i}_1 + \mathbf{u}_1 \mid \mathbf{A}_1 \cdot \mathbf{i}_1 \geq \mathbf{b}_1 \} \\ LBL_2 = \{ \mathbf{x} = \mathbf{T}_2 \cdot \mathbf{i}_2 + \mathbf{u}_2 \mid \mathbf{A}_2 \cdot \mathbf{i}_2 \geq \mathbf{b}_2 \} \end{array} \right.$$



$$\mathbf{T}_1 \cdot \mathbf{i}_1 + \mathbf{u}_1 = \mathbf{T}_2 \cdot \mathbf{i}_2 + \mathbf{u}_2$$

Diophantine system of eqs.



$$\{ \mathbf{A}_1 \cdot \mathbf{i}_1 \geq \mathbf{b}_1, \mathbf{A}_2 \cdot \mathbf{i}_2 \geq \mathbf{b}_2 \}$$

New polytope

Memory Size Computation

$$A0 = \{ x=j, y=0 \mid n-1 \geq j \geq 0 \}$$

$$A1 = \{ x=j, y=i \mid n-1 \geq j \geq 0, n-1 \geq i \geq 1 \}$$

$$A2 = \{ x=0, y=n \}$$

$$A3 = \{ x=i, y=i+n \mid n-1 \geq i \geq 1 \}$$

$$A4 = \{ x=i, y=i+n+1 \mid n-2 \geq i \geq 0 \}$$

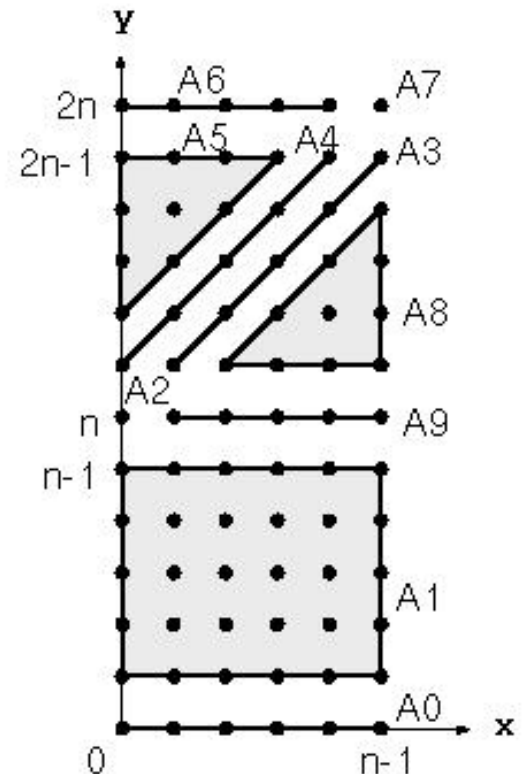
$$A5 = \{ x=j, y=i+n+1 \mid n-2 \geq i, j \geq 0, i-j \geq 1 \}$$

$$A6 = \{ x=i, y=2n \mid n-2 \geq i \geq 0 \}$$

$$A7 = \{ x=n-1, y=2n \}$$

$$A8 = \{ x=j, y=i+n \mid n-1 \geq j, i \geq 1, j-i \geq 1 \}$$

$$A9 = \{ x=j, y=n \mid n-1 \geq j \geq 1 \}$$



Decomposition of the array references of signal A
(illustrative example)



Memory Size Computation Algorithm

Step 1

For every indexed signal in the algorithmic specification, decompose the array references in disjoint LBL's

Step 2

Based on the LBL lifetime analysis, find the exact memory size at the boundaries between the blocks of code

Step 3

Analyzing the amounts of signals produced and consumed in each block, prune the blocks of code where the maximum storage cannot happen

Step 4

For each of the remaining blocks, compute the maximum memory size

- exploiting the one-to-one mapping property of array references
- computing the maximum iterator vectors of the scalars

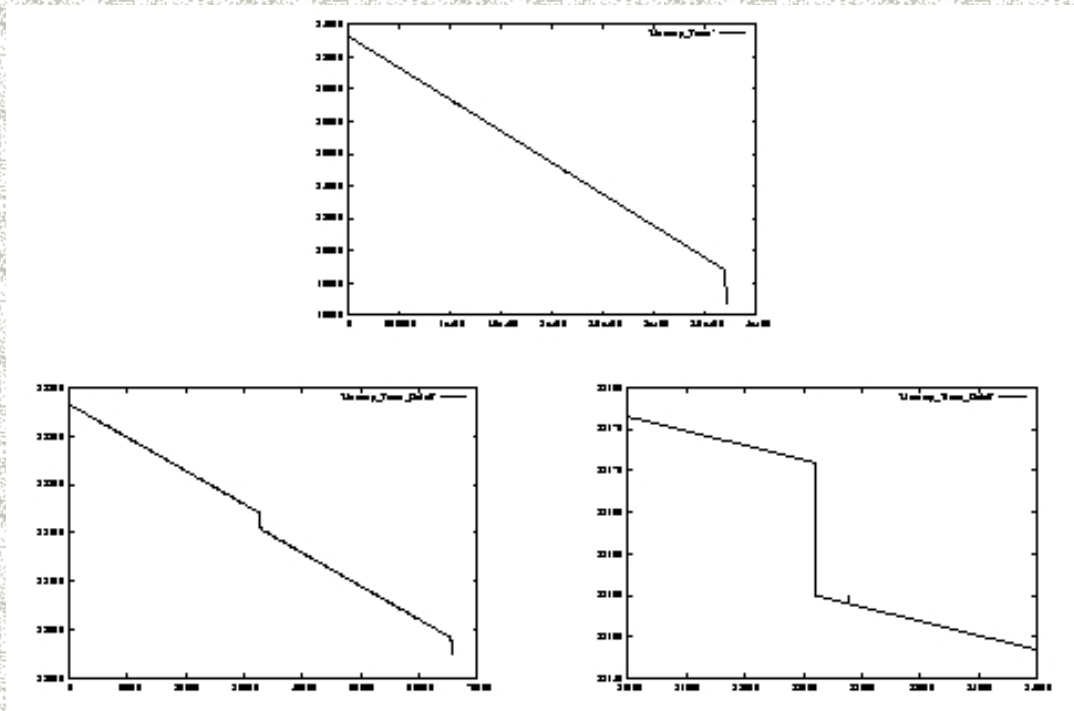


Experimental Results

Application (parameters)	# LBL's	# Scalar signals	# Storage locations	CPU sec
Regularity detection (MaxGrid=8, L=64)	28	4,752	2,304	< 1
Vocoder kernel	247	33,619	11,890	2
Motion detection (M=N=32, m=n=4)	583	72,543	2,740	2
(M=N=64, m=n=4)	1,255	318,367	9,524	11
Durbin alg. (N=500)	6,986	252,499	1,249	18
Dynamic prog. (N=500)	6,474	21,082,751	124,751	78
2D Gauss. blur filter (M=N=500)	7,479	2,735,027	250,005	103

Tests on a PC with a 1.85 GHz Athlon XP processor

Experimental Results



Memory size variation in the illustrative example

- abscissas: the number of data-path instructions in the code
- ordinates: the number of storage locations

The global maximum: $x=2$, $y=33,284$



Conclusions

- The storage of multi-dimensional signals has a significant influence on both the area and power consumption in multimedia processing systems
- Algebraic techniques are powerful non-scalar instruments in the memory management of multimedia signal processing
- This paper has presented a non-scalar approach for the exact computation of storage requirements in real-time multimedia algorithms

The End