

PLLSim

- An Ultra Fast Phase locked Loop Simulation Tool

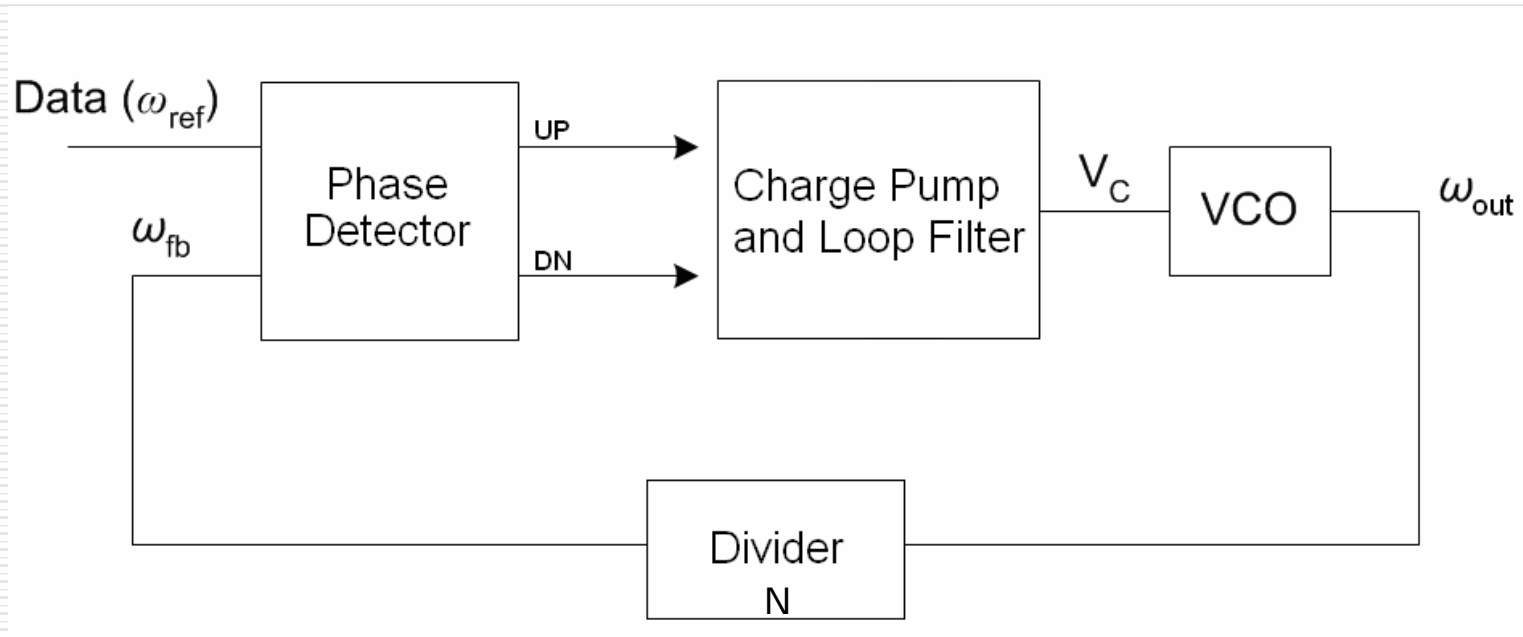
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School of ITEE, University of Queensland



Presentation Overview

- PLLs, and why they are hard to simulate
 - A behavioral model for bang-bang type PLLs
 - Applying this model to make PLLSim
 - Performance of PLLSim
 - Modeling the non-ideal behavior typical of bang-bang PLLs
 - Summary & Questions
-

Basic Charge Pump PLL

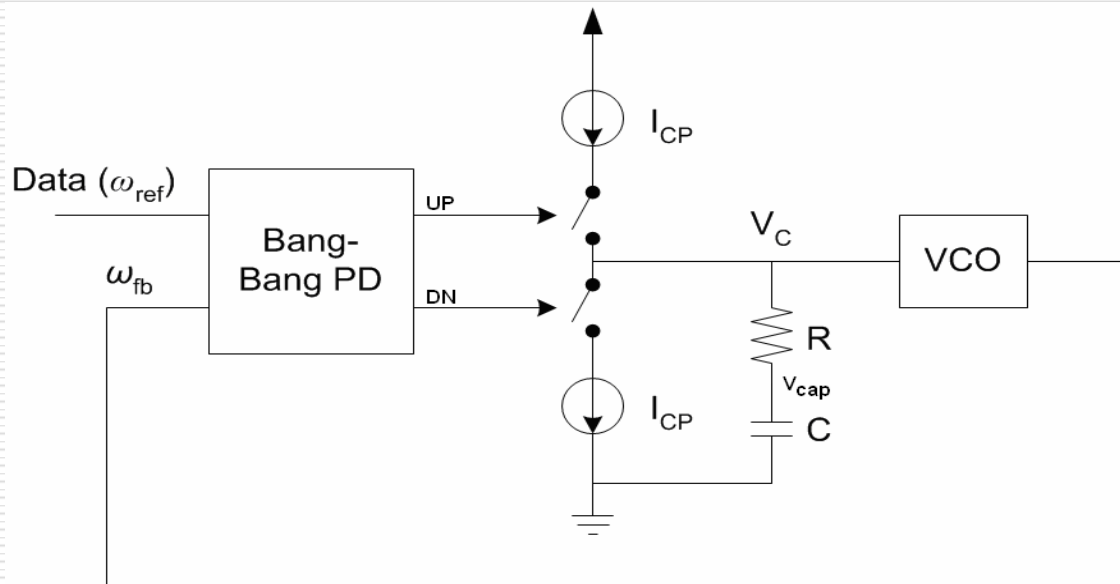


- ❑ For bang-bang type PLL's, parameters such as locking time, and capture range are not well understood.
 - ❑ The design process relies heavily on simulation.
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The Problem With Simulation

- ❑ Time step simulators such as Matlab Simulink, and SPICE are typically used
 - ❑ We require tens to hundreds of time slices to simulate a period of the recovered clock
 - ❑ The recovered clock can be significantly higher than the reference clock due to the divider
 - ❑ A PLL typically requires several tens of thousands of cycles in order to achieve lock
 - ❑ = **Excessively Long Simulation Times**
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Modeling a 2nd order Bang-bang Phased Locked Loop



We Define:

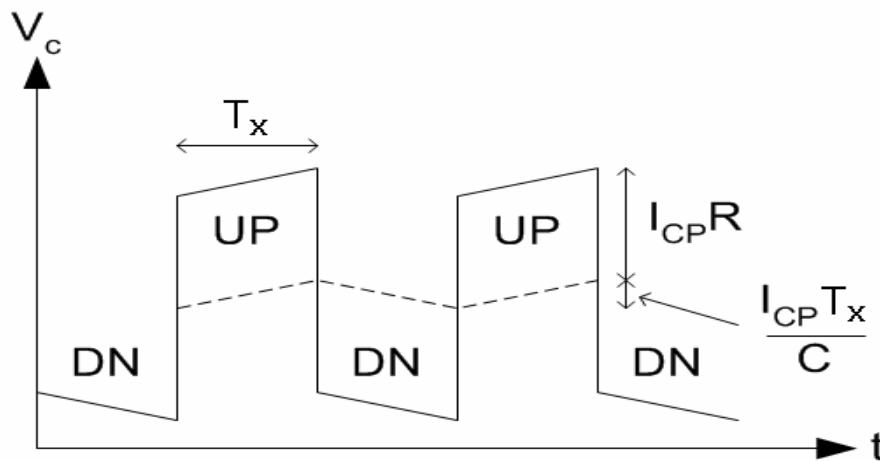
$$\omega_{err}(t)$$

$$\phi_{err}(t)$$

$$T_X(t)$$

- ❑ PLL State is characterized by a frequency error and a phase error
- ❑ We calculate how these change every period of the reference signal

Ripple on the VCO control voltage due to UP and DN pulses



Based on the graph, we can calculate the change on phase and frequency error due to an UP or DN pulse

- $\Delta\omega(t) = K_{VCO} I_{cp} T_x(t) / C$
- $\Delta\phi(t) = K_{VCO} I_{cp} R T_x(t) + 0.5 T_x(t) \Delta\omega$
- $\omega_{err}(t + T_x(t)) = \omega(t) + \zeta \Delta\omega(t)$
- $\phi_{err}(t + T_x(t)) = \phi(t) + \zeta \Delta\phi(t) + \omega_{err}(t) T_x(t)$
- $\zeta = 1$ for an UP pulse, $\zeta = -1$ for a DN pulse

2nd order Bang-bang PLL Model

We define $\Delta\omega`$ and $\Delta\phi`$ as:

$$\Delta\omega` = K_{VCO} I_{cp} T_{ref} / C$$

$$\Delta\phi` = K_{VCO} I_{cp} R T_{ref} + 1/2 T_{ref} \Delta\omega`$$

∞

$$\Delta\omega(t) = \Delta\omega` T_X(t) / T_{ref}$$

$$\Delta\phi(t) = (\Delta\phi` - 1/2 T_{ref} \Delta\omega`) + 1/2 T_X(t) \Delta\omega(t)$$

PLL system can be summarised by $\Delta\omega`$ and $\Delta\phi`$

2nd order Bang-bang PLL Model

During an UP pulse:

$$T_X(t) = 2\pi / (\omega_{fb}(t) + K_{VCO} I_{cp} R + \frac{1}{2} \Delta\omega(t))$$

During a DN pulse:

$$T_X(t) = 2\pi / (\omega_{fb}(t) - K_{VCO} I_{cp} R - \frac{1}{2} \Delta\omega(t))$$

The third term is very small compared to the other terms, so can be approximated by $\Delta\omega$ with negligible loss in accuracy.

We have:

$$\begin{aligned} T_X(t) &= 2\pi / (\omega_{fb}(t) + \zeta (\Delta\phi / T_{ref})) \\ &= 2\pi / (\omega_{ref} + \omega_{err}(t) + \zeta (\Delta\phi / T_{ref})) \end{aligned}$$

In Summary

$$\omega_{err}(t + T_X(t)) = \omega(t) + \zeta \Delta\omega(t)$$

$$\varphi_{err}(t + T_X(t)) = \varphi(t) + \zeta \Delta\varphi(t) + \omega_{err}(t) T_X(t)$$

$\zeta = 1$ for an UP pulse, $\zeta = -1$ for a DN pulse

$$\Delta\omega(t) = \Delta\omega \cdot T_X(t) / T_{ref}$$

$$\Delta\varphi(t) = (\Delta\varphi \cdot -\frac{1}{2} T_{ref} \Delta\omega \cdot) + \frac{1}{2} T_X(t) \Delta\omega(t)$$

$$T_X(t) = 2\pi / (\omega_{ref} + \omega_{err}(t) + \zeta (\Delta\varphi \cdot / T_{ref}))$$

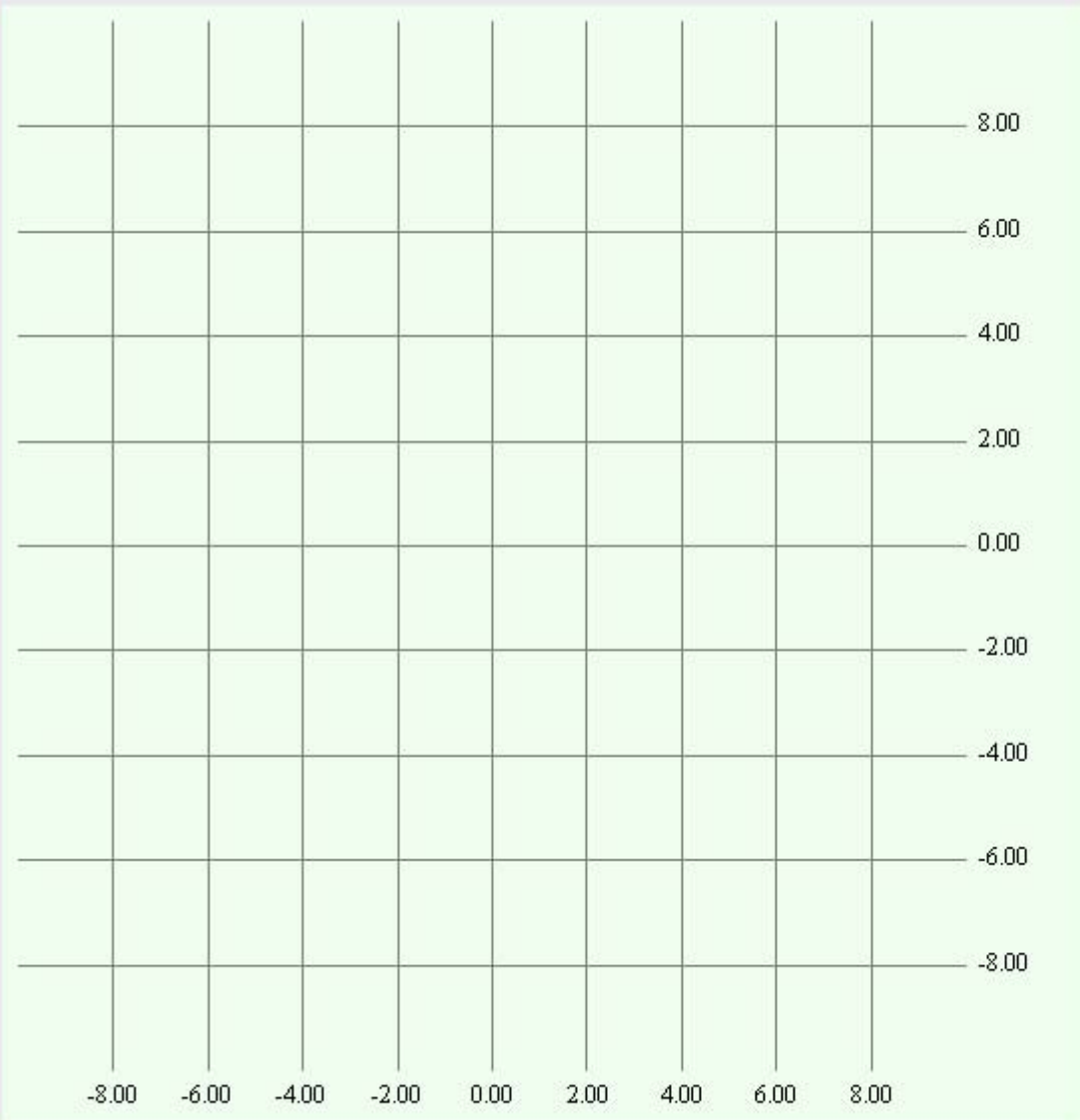
$$\Delta\omega \cdot = K_{VCO} I_{cp} T_{ref} / C$$

$$\Delta\varphi \cdot = K_{VCO} I_{cp} R T_{ref} + \frac{1}{2} T_{ref} \Delta\omega \cdot$$

PLLSim Engine

We have state variables: ω_{err} , φ_{err} , and t

- 1) Check our phase error: +ve = DN pulse, -ve = UP pulse
 - 2) Calculate $T_X(t)$, and update t , $\omega_{err}(t)$, and $\varphi_{err}(t)$ according to our equations
 - 3) Store results (t, ω_{err}) and (t, φ_{err})
 - 4) Goto 1)
-



Coordinates
x: -9.873418 y: 3.396947

- | Show | Hide |
|--------------------------|-------|
| <input type="checkbox"/> | plot0 |
| <input type="checkbox"/> | plot1 |

-> <-

Add

Duplicate

Remove

- Show Points Debug
 Frequency Phase

H Grid Lines V Grid Lines
9 9

Zoom Last

Zoom Out

Zoom all

Exit

Plot Setup

Nothing

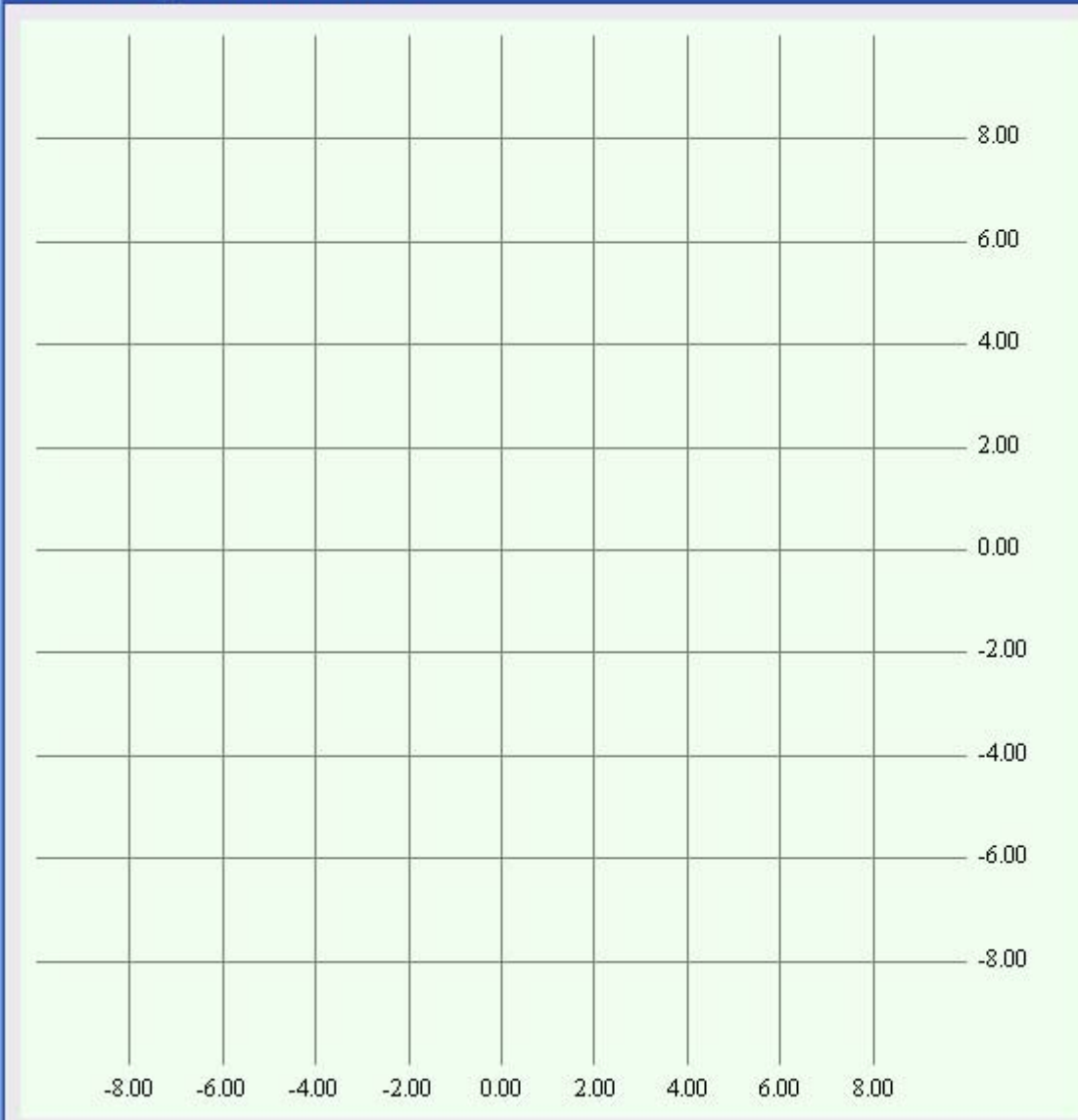
- plot1 Plot Name
0 Phase Step
0 Freq Step
0 Phase Err
0 Freq Err
0 Ref Freq
0 End Time

- Degrees / Hertz
 Radians

Set Colour

Non-Linearities

Confirm



Coordinates
x: -9.873418 y: 3.396947

Show Hide

	plot0
	plot1

-> <-

Add

Duplicate

Remove

Show Points Debug

Frequency Phase

H Grid Lines V Grid Lines

9 9

Zoom Last

Zoom Out

Zoom all

Exit

Plot Setup

Nothing

- Nothing
- Analytic
- Simulate
- From File
- x^2

0 Freq Step

0 Phase Err

0 Freq Err

0 Ref Freq

0 End Time

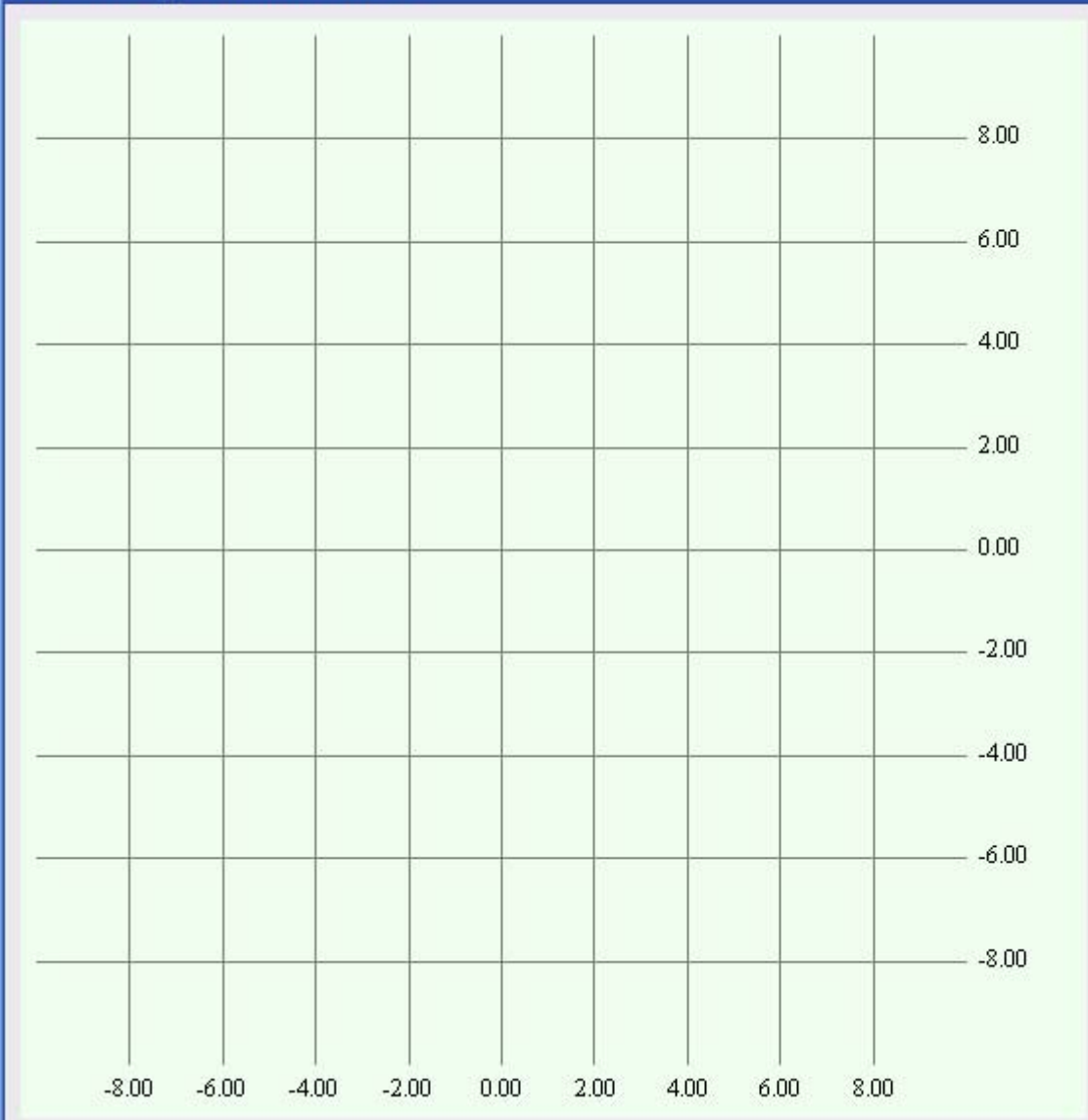
Degrees / Hertz

Radians

Set Colour █

Non-Linearities

Confirm



Coordinates
x: -9.873418 y: 3.396947

Show Hide

	plot0
	plot1

-> <-

Add

Duplicate

Remove

Plot Setup *

Simulate

plot1 Plot Name

3 Phase Step

20e3 Freq Step

0 Phase Err

30e6 Freq Err

500e6 Ref Freq

20e-6 End Time

Degrees / Hertz

Radians

Set Colour

Non-Linearities

Confirm

Color

Basic colors:

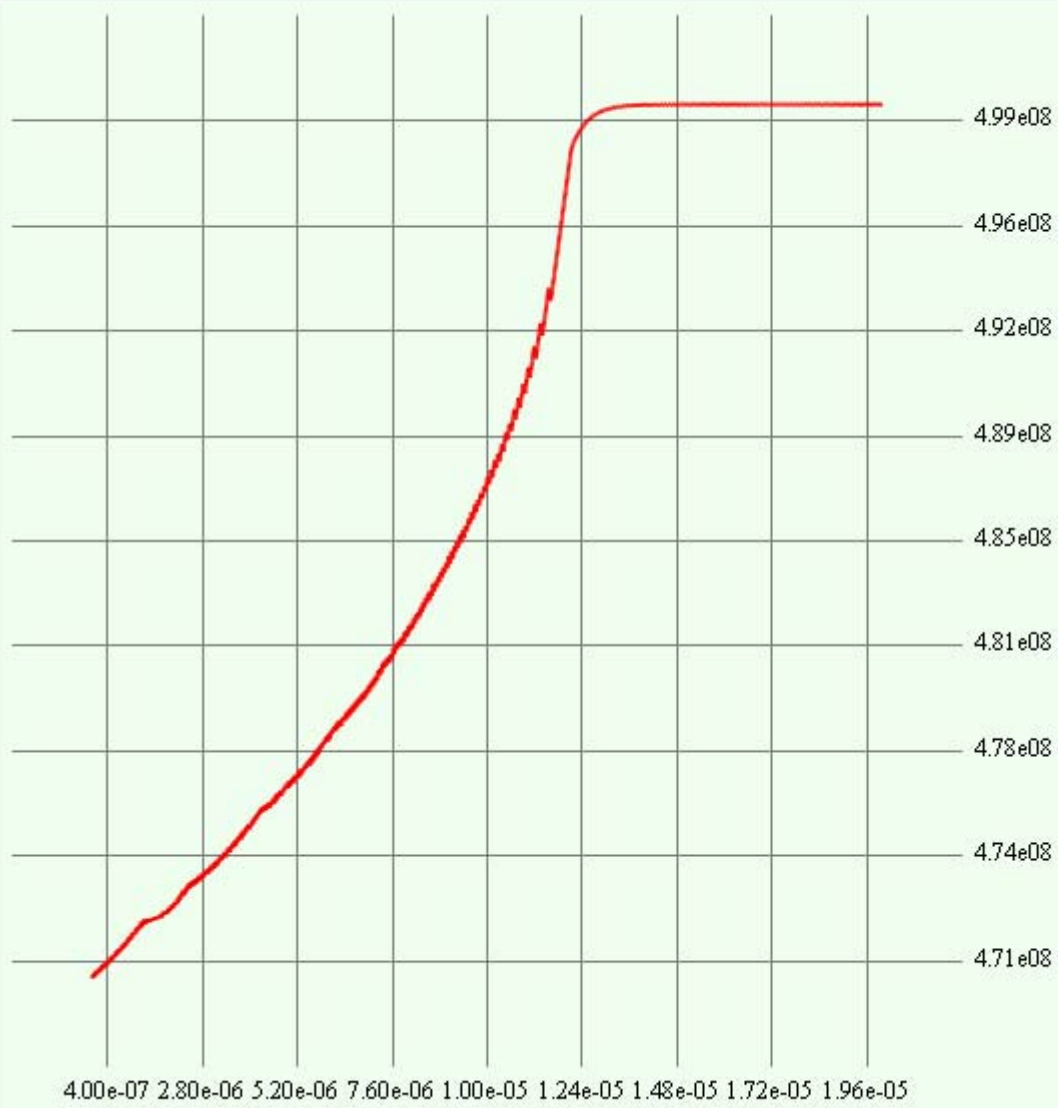
Custom colors:

<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>
<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>	<input type="text"/>

Define Custom Colors >>

OK Cancel

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Coordinates
x: -9.578059 y: -1.641221

Show	Hide
plot1	plot0

->

<-

Add

Duplicate

Remove

Show Points

Debug

Frequency

Phase

H Grid Lines

9

V Grid Lines

9

Zoom Last

Zoom Out

Zoom all

Exit

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Coordinates
x: 2.1798e-05 y: 4.7943e08

Show Hide
plot0
plot1

->

<-

Add

Duplicate

Remove

Show Points

Debug

Frequency

Phase

H Grid Lines

9

V Grid Lines

9

Zoom Last

Zoom Out

Zoom all

Exit

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Coordinates
x: 5.2405e-06 y: 4.7152e08

Show	Hide
plot1	plot0

-> <-

Add

Duplicate

Remove

Show Points Debug
 Frequency Phase

H Grid Lines V Grid Lines
9 9

Zoom Last

Zoom Out

Zoom all

Exit

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Coordinates
x: $-1.0394e-07$ y: $4.7466e08$

Show	Hide
plot1	plot0

-> <-

Add

Duplicate

Remove

Show Points Debug
 Frequency Phase

H Grid Lines V Grid Lines
9 9

Zoom Last

Zoom Out

Zoom all

Exit

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Coordinates
x: 1.6090×10^{-6} y: 4.7210×10^8

Show	Hide
plot1	plot0

-> <-

Add

Duplicate

Remove

Show Points Debug
 Frequency Phase

H Grid Lines V Grid Lines
9 9

Zoom Last

Zoom Out

Zoom all

Exit

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Coordinates
x: 1.0861e-05 y: 209.397400

Show	Hide
plot1	plot0

-> <-

Add

Duplicate

Remove

- Show Points
- Debug
- Frequency
- Phase

H Grid Lines: 9
V Grid Lines: 9

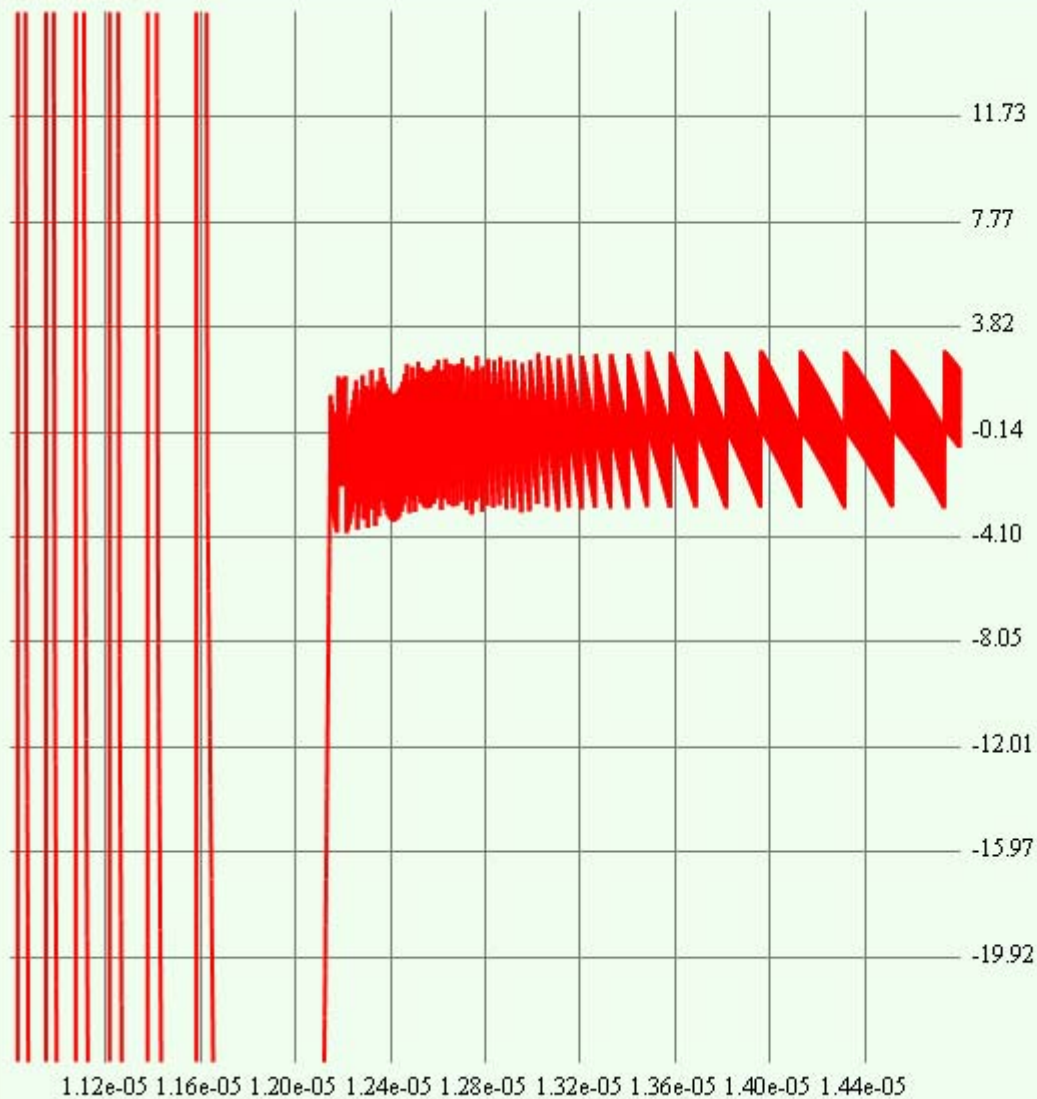
Zoom Last

Zoom Out

Zoom all

Exit

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Coordinates

x: 1.4759×10^{-5}

y: 2.473658

Show

plot1

Hide

plot0

->

<-

Add

Duplicate

Remove

Show Points

Debug

Frequency

Phase

H Grid Lines

9

V Grid Lines

9

Zoom Last

Zoom Out

Zoom all

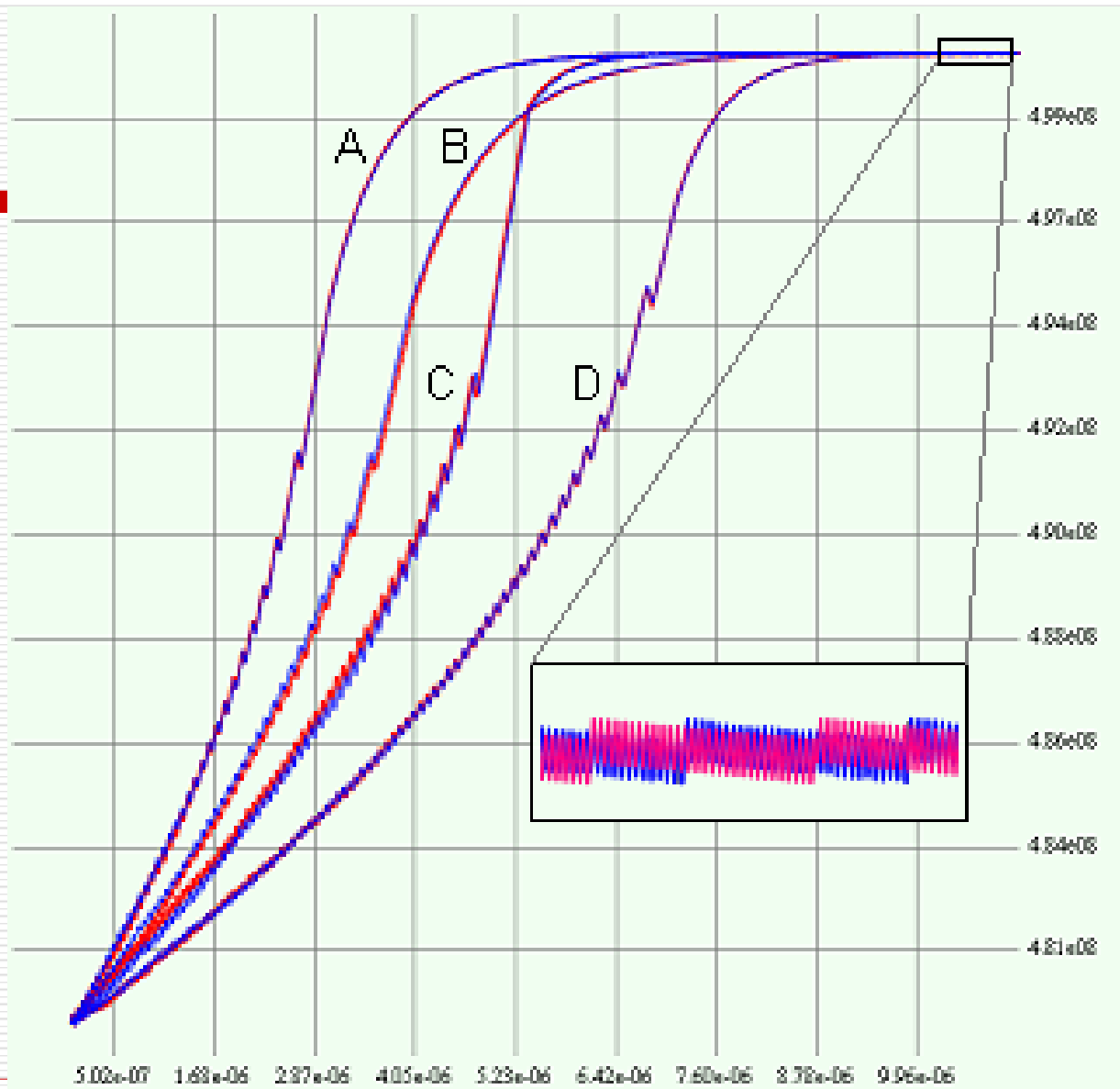
Exit

Simulation Configurations

Plot	$\Delta \Phi$	$\Delta \omega$	ω_{ref}	$\omega_{\text{err}}(0)$	$\Phi_{\text{err}}(0)$
A	5°	20kHz	500MHz	20MHz	-90°
B	5°	15KHz	500MHz	20MHz	-90°
C	3°	20KHz	500MHz	20MHz	-90°
D	3°	15KHz	500MHz	20MHz	-90°

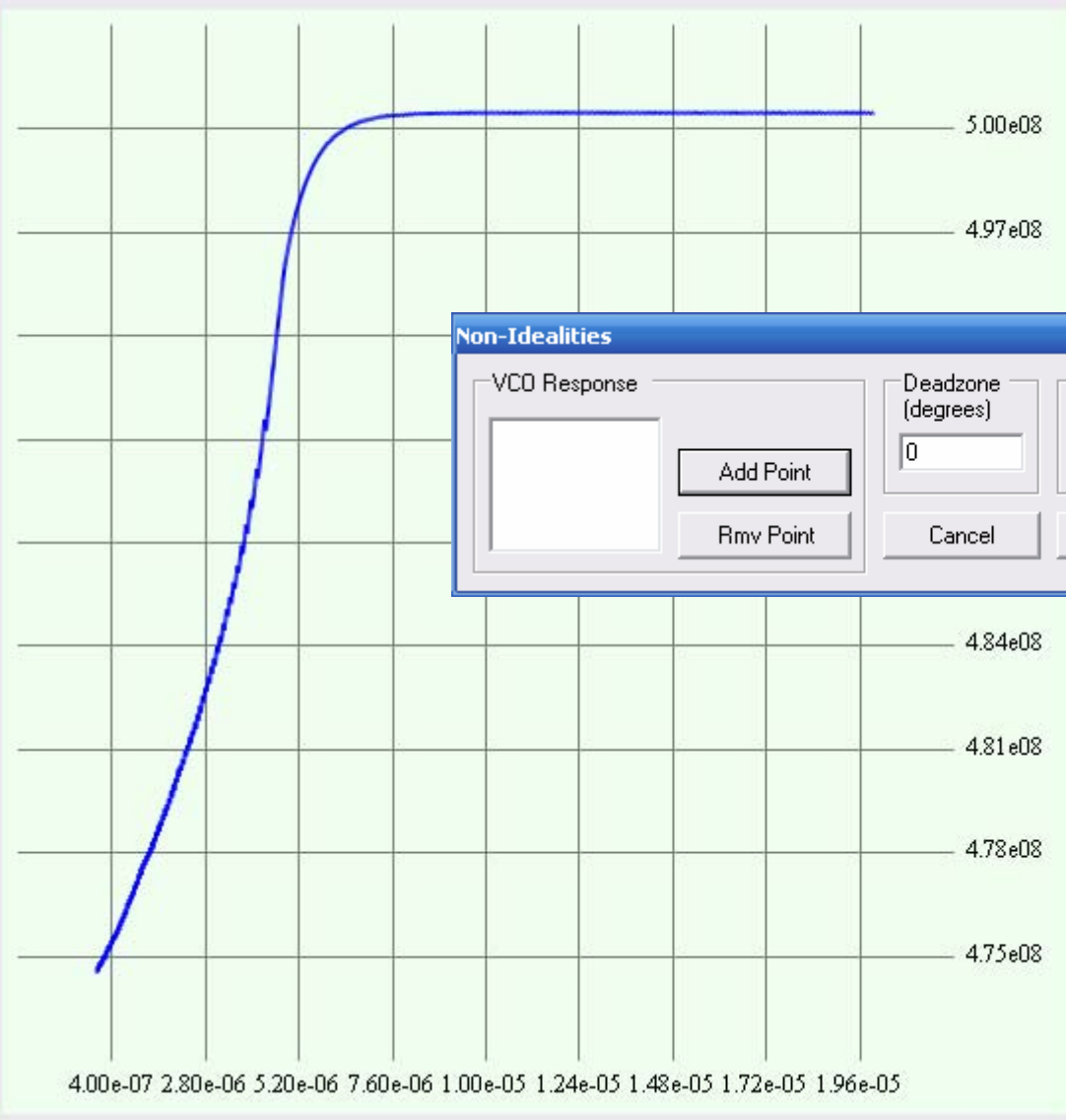
Performance Comparison

Simulation Configuration	Simulation Time	PLLSim Time	Simulink Time	Speedup
A	20 us	5.9 ms	389 s	6.95e04
B	30 us	8.8 ms	730 s	8.30e04
C	20 us	5.9 ms	403 s	6.83e04
D	30 us	8.7 ms	697 s	8.01e04



Non Ideal Behavior

- ❑ Non-linear VCO response
 - ❑ Phase detector deadzone
 - ❑ Phase detector latency
 - ❑ Also handle random reference data sources
-



Coordinates
x: 1.5498e-06 y: 4.7412e08

Show Hide

plot1	
-------	--

Non-Idealities

VCO Response

Deadzone (degrees): 0

Transition Probability: 1

PD Latency (0..1): 0

Buttons: Add Point, Rmv Point, Cancel, Help, Ok

Frequency Phase

H Grid Lines: 9 V Grid Lines: 9

Zoom Last

Zoom Out

Zoom all

Exit

Plot Setup *

Simulate

plot0 Plot Name

5 Phase Step

20000 Freq Step

0 Phase Err

35000000.0000 Freq Err

499999999.999 Ref Freq

2E-05 End Time

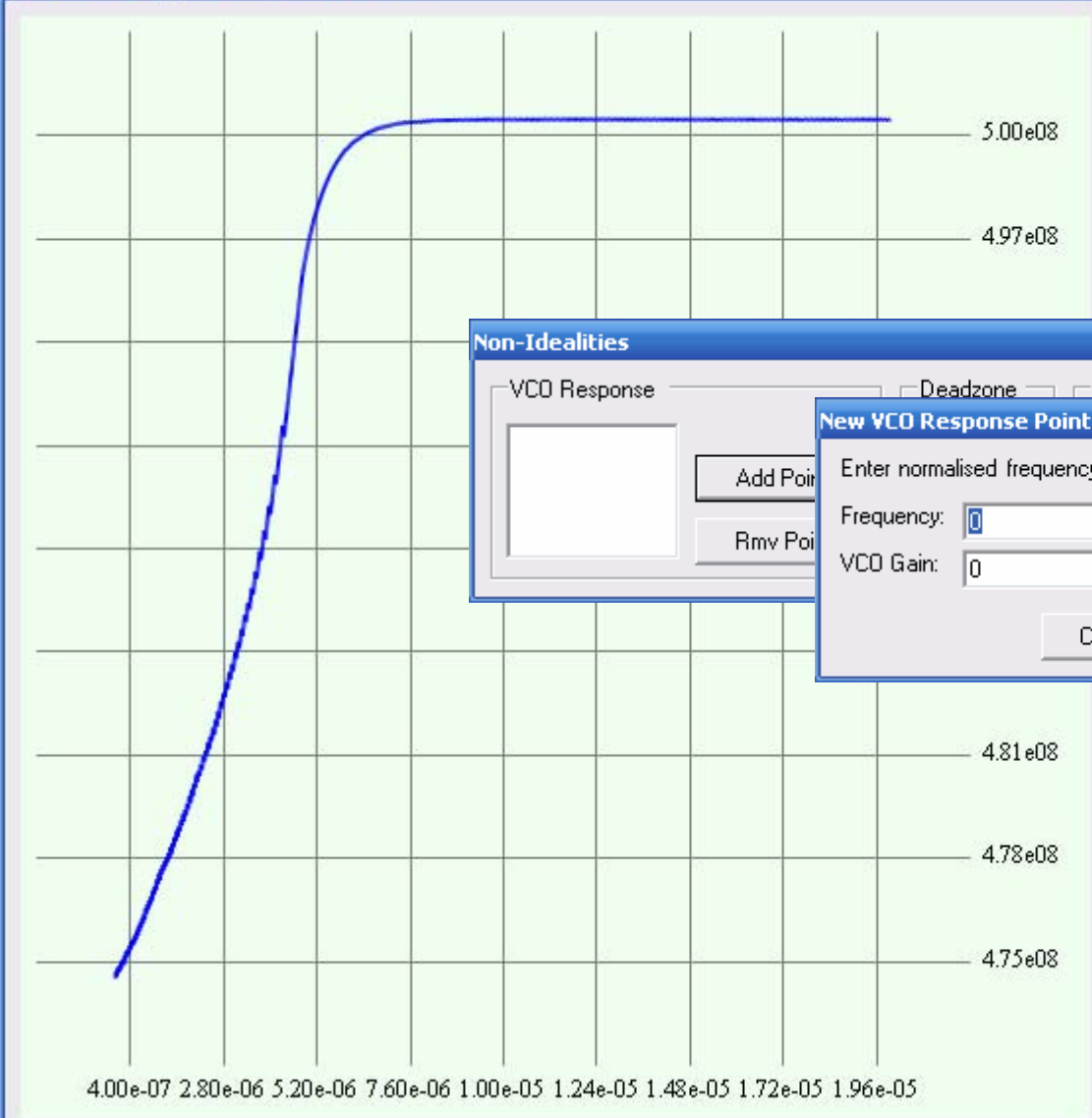
Degrees / Hertz

Radians

Set Colour

Non-Linearities

Confirm



Coordinates
x: 1.5498e-06 y: 4.7412e08

Show Hide

plot1	
-------	--

Non-Idealities

VCO Response Deadzone Transition PD Latency

Add Point

Rmv Point

New VCO Response Point

Enter normalised frequency and normalised gain:

Frequency:

VCO Gain:

Cancel Ok

Plot Setup *

Simulate

plot0	Plot Name
5	Phase Step
20000	Freq Step
0	Phase Err
35000000.0000	Freq Err
499999999.999	Ref Freq
2E-05	End Time

Degrees / Hertz
 Radians

Set Colour █

Non-Linearities

Confirm

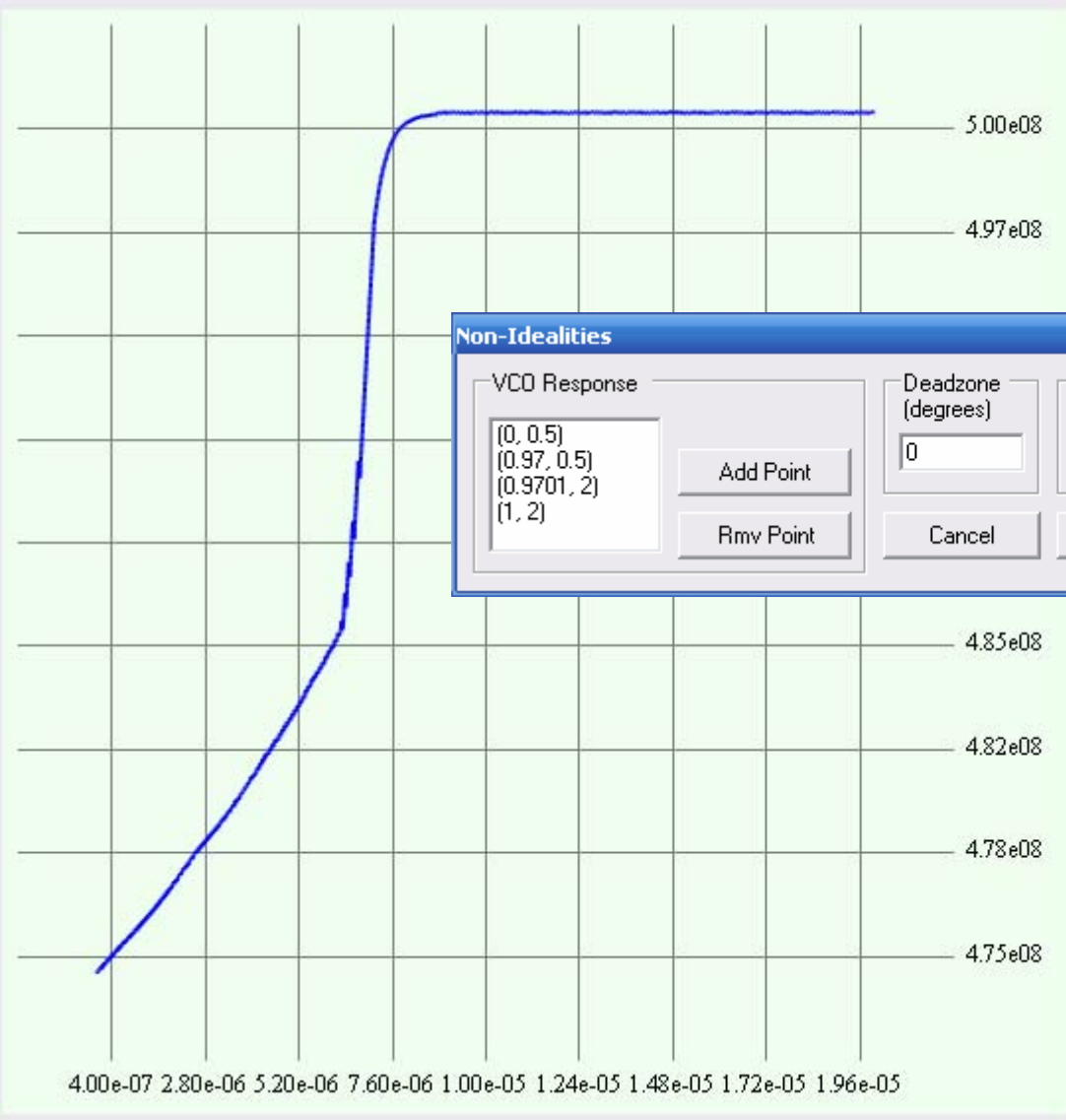
H Grid Lines V Grid Lines

Zoom Last

Zoom Out

Zoom all

Exit



Coordinates
x: 1.3291e-05 y: 5.0249e08

Show	Hide
plot0	

Non-Idealities

VCO Response [0, 0.5] [0.97, 0.5] [0.9701, 2] [1, 2]	Deadzone (degrees) 0	Transition Probability 1	PD Latency (0..1) 0
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Buttons: Add Point, Rmv Point, Cancel, Help, Ok

Frequency Phase

H Grid Lines: 9 V Grid Lines: 9

Zoom Last
Zoom Out
Zoom all
Exit

Simulate

plot0	Plot Name
5	Phase Step
20000	Freq Step
0	Phase Err
35000000.0000	Freq Err
499999999.999	Ref Freq
2E-05	End Time

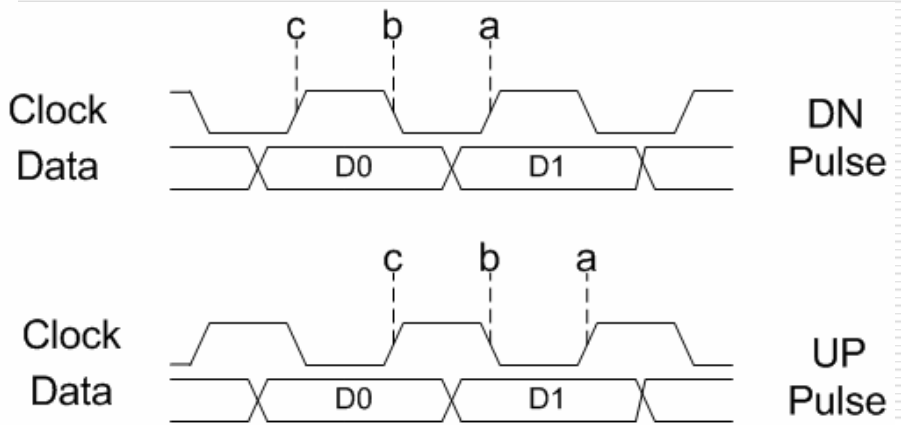
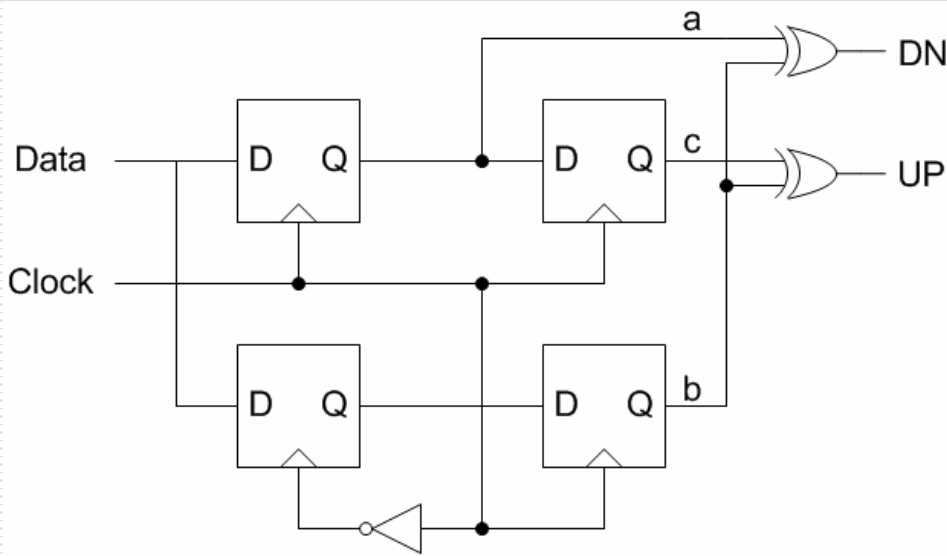
Degrees / Hertz
 Radians

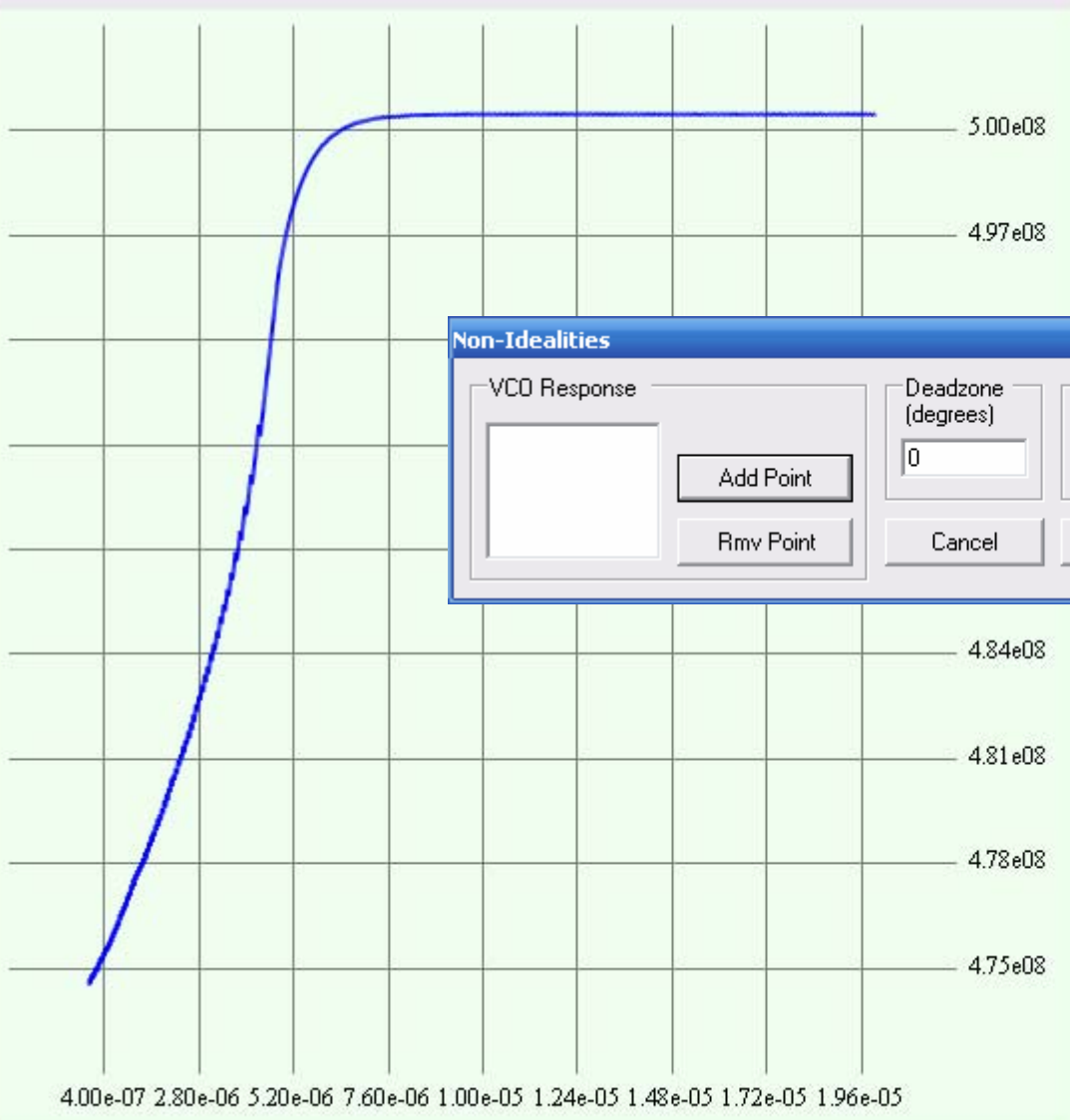
Set Colour: [Blue]

Non-Linearities:

Confirm

Latency in an Alexander PD





Coordinates
x: 1.5498e-06 y: 4.7412e08

Show	Hide
plot1	

Non-Idealities

VCO Response

Deadzone (degrees): 0

Transition Probability: 1

PD Latency (0..1): 0

Buttons: Add Point, Rmv Point, Cancel, Help, Ok

Frequency Phase

H Grid Lines: 9 V Grid Lines: 9

- Zoom Last
- Zoom Out
- Zoom all
- Exit

Simulate

plot0 Plot Name

5 Phase Step

20000 Freq Step

0 Phase Err

35000000.0000 Freq Err

499999999.999 Ref Freq

2E-05 End Time

Degrees / Hertz

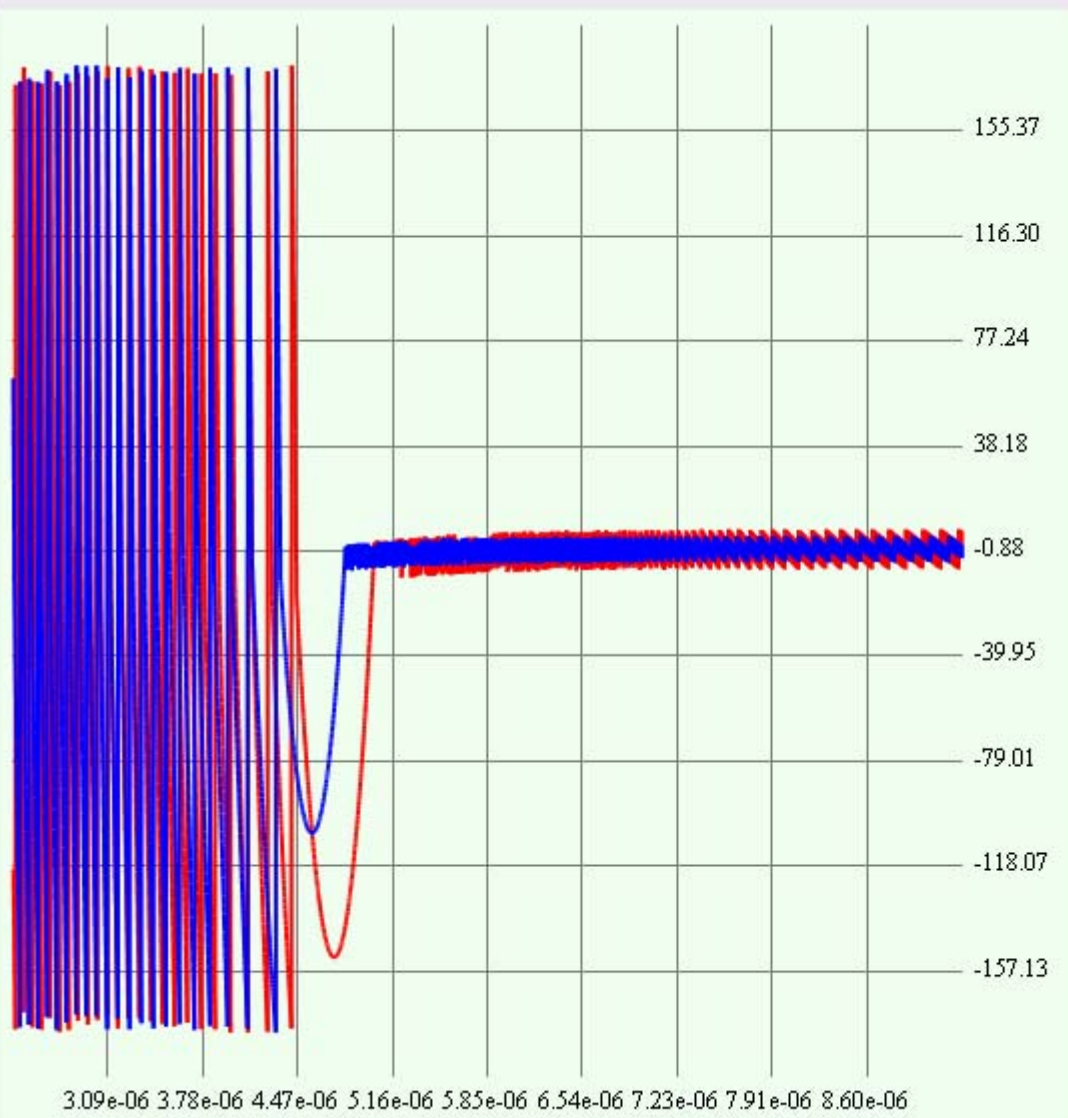
Radians

Set Colour

Non-Linearities

Confirm

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Coordinates
x: 8.7391e-06 y: 192.937200

- | Show | Hide |
|-------|------|
| plot1 | |
| plot0 | |

-> <-

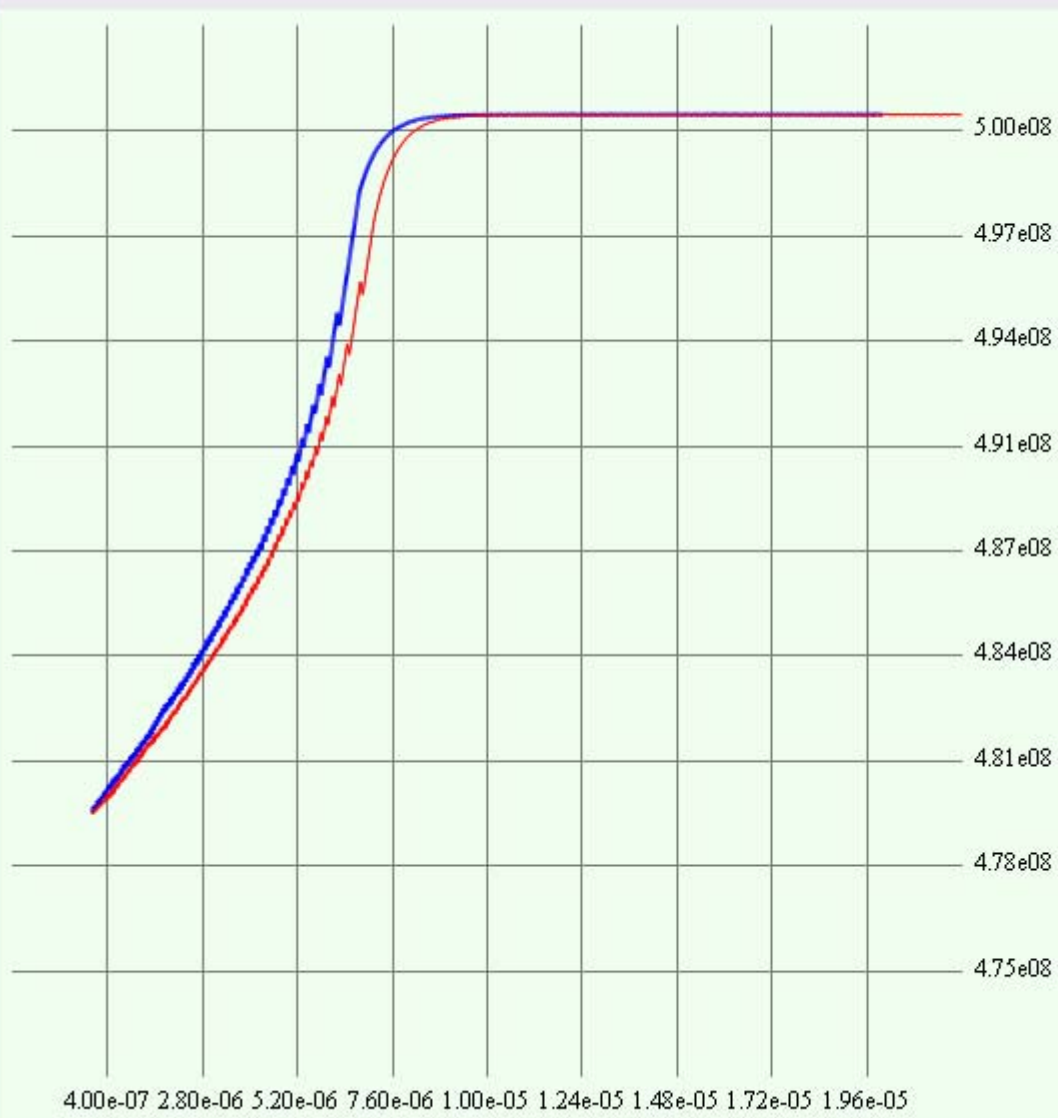
Add
Duplicate
Remove

Show Points Debug
 Frequency Phase

H Grid Lines V Grid Lines
9 9

Zoom Last
Zoom Out
Zoom all
Exit

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Coordinates
x: 1.4304e-05 y: 5.0241e08

- Show Hide
- plot0
 - plot1

-> <-

Add

Duplicate

Remove

Show Points Debug

Frequency Phase

H Grid Lines V Grid Lines

9 9

Zoom Last

Zoom Out

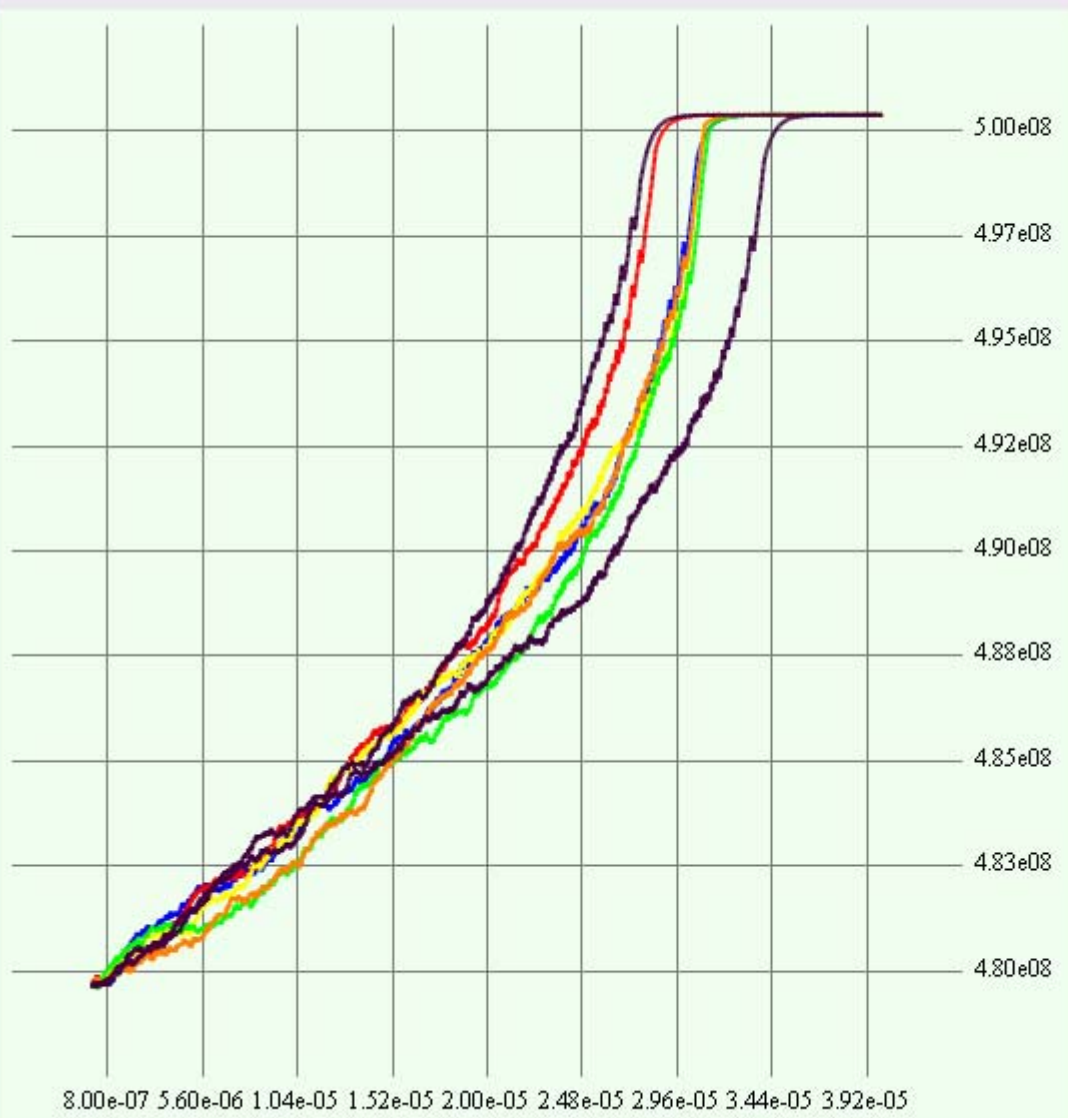
Zoom all

Exit

Non Ideal Behavior

- ❑ Non-linear VCO response
 - ❑ Phase detector deadzone
 - ❑ Phase detector latency
 - ❑ Also handle random reference data sources
-

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Coordinates
x: 3.8734e-05 y: 4.8600e08

- Show Hide
- plot1
 - plot2
 - plot3
 - plot4
 - plot5
 - plot6

-> <-

Add

Duplicate

Remove

Show Points Debug

Frequency Phase

H Grid Lines V Grid Lines

9 9

Zoom Last

Zoom Out

Zoom all

Exit

Summary

- ❑ Presented a model for bang-bang PLL behaviour
 - ❑ Showed how this model could be applied to a simulation program
 - ❑ Demonstrated remarkable speedup times for simulating bang-bang PLLs
 - ❑ Extended the simulator to handle some common non-idealities
 - ❑ You can download PLLSim at www.itee.uq.edu.au/~mchan
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