

Advanced Tools for Simulation and Design of Oscillators/PLLs

Xiaolue Lai and Jaijeet Roychowdhury

University of Minnesota,
Minneapolis, USA

Oscillators: A Special Simulation Challenge

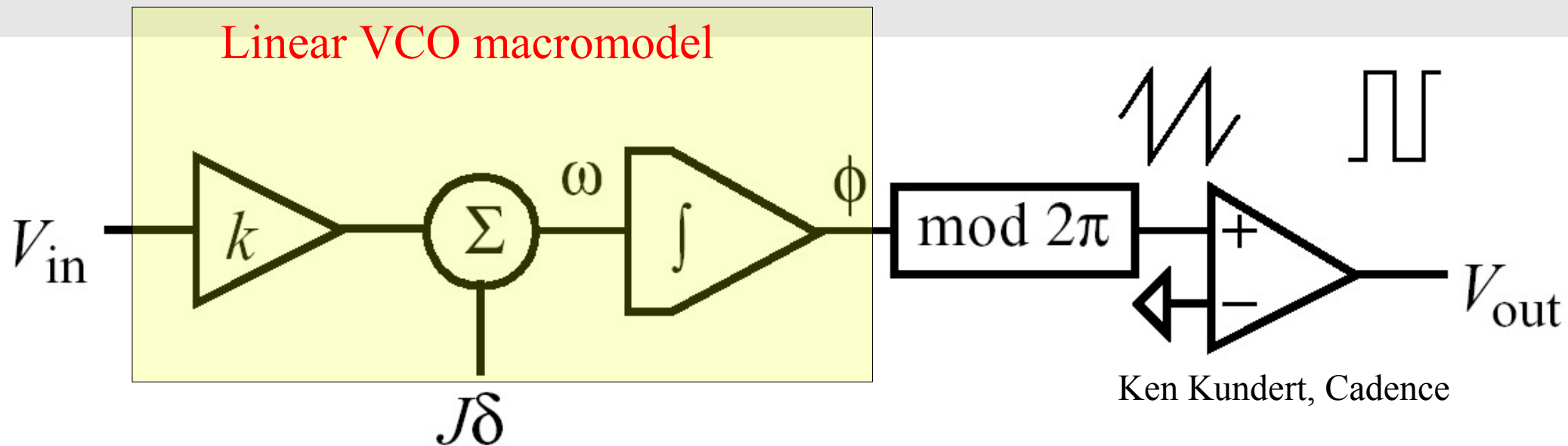
- **Computation/size/accuracy**: much greater than for amps/mixers
 - inefficient for even 1-transistor oscillators
 - long startups: **many cycles**
 - **tiny timesteps** needed per cycle
 - integrated RF: 100s to 1000s of transistors
 - **errors** dependent on size of timesteps, integration method, **size of perturbations**
 - fundamental cause: **marginal phase stability** of all oscillators
 - numerical errors integrate over time

SPICE-based perturbation analysis of oscillators is not a good idea

Alternatives to SPICE-level simulation

- Use simplified phase macromodels
 - Obtain effects of external perturbations on phase directly without simulating the full circuit
 - (Linear Time-Invariant (LTI) models)

Linear VCO macromodel

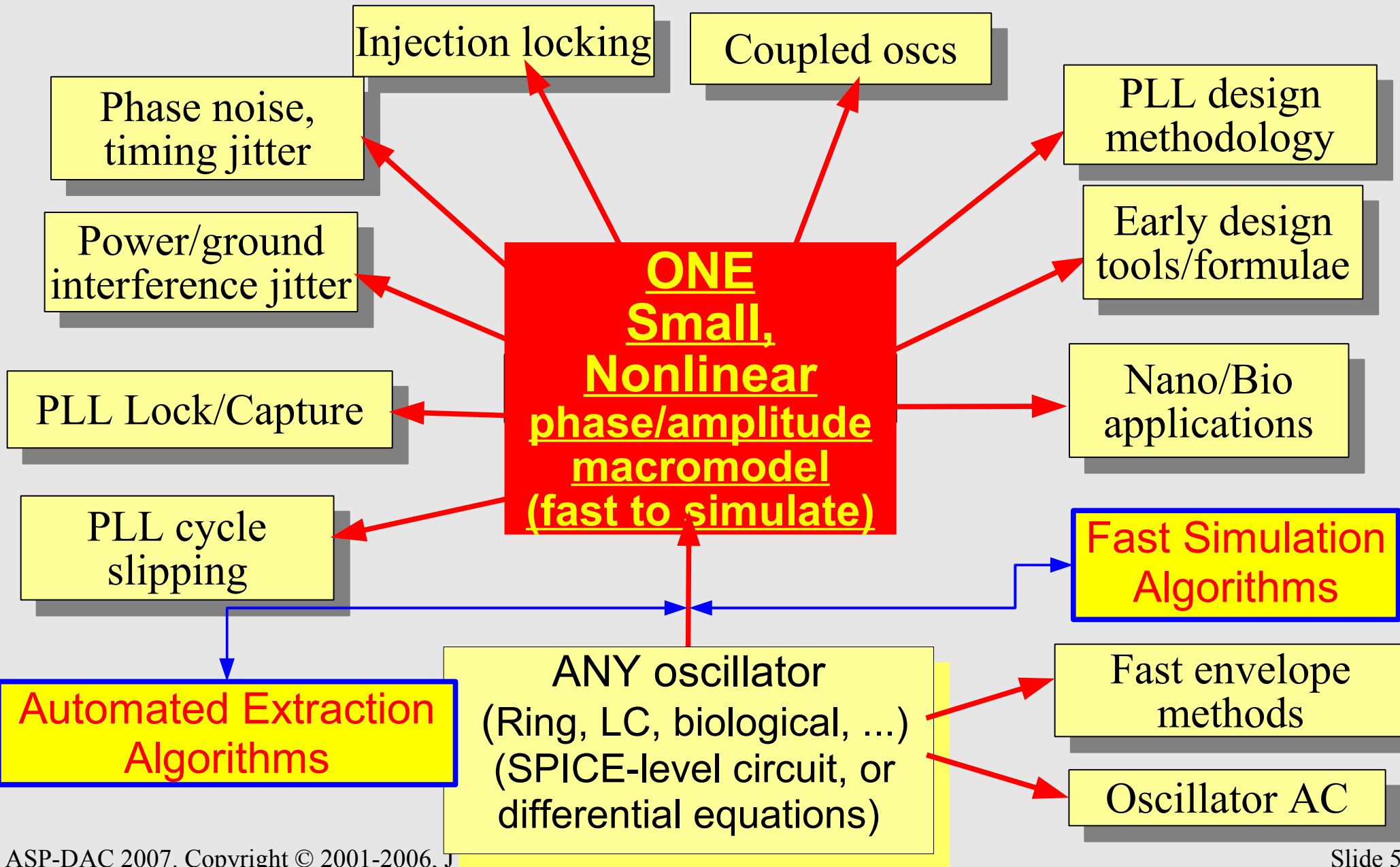


Ken Kundert, Cadence

Limitations of Linear Phase Macromodels

- Linear models are **not generally applicable** for all effects
- LTI model: **narrow applicability**
- LPTV models, including:
 - Kaertner's LPTV IRF
 - Hajimiri's closed-form ISF
 - **better, but validity depends on circuit/dynamical effects**
- **Eg, cannot capture nonlinear phenomena**
 - injection locking, jitter, cycle slips, power grid noise effects, ...

Automatically-extracted Oscillator Macromodel works for ALL effects, ALL oscillators



Automatically Extracted Nonlinear Oscillator Macromodel

$$\dot{\alpha}(t) = v_1^T(t + \alpha(t)) \cdot b(t)$$

Phase
error/ jitter

Perturbation Projection
Vector (PPV/NISF)

Noise
"Input"

Phase macromodel is nonlinear and scalar
(nonlinear = captures complex dynamics)
(scalar = small, fast to evaluate)

Drop-in replacement for linear phase models

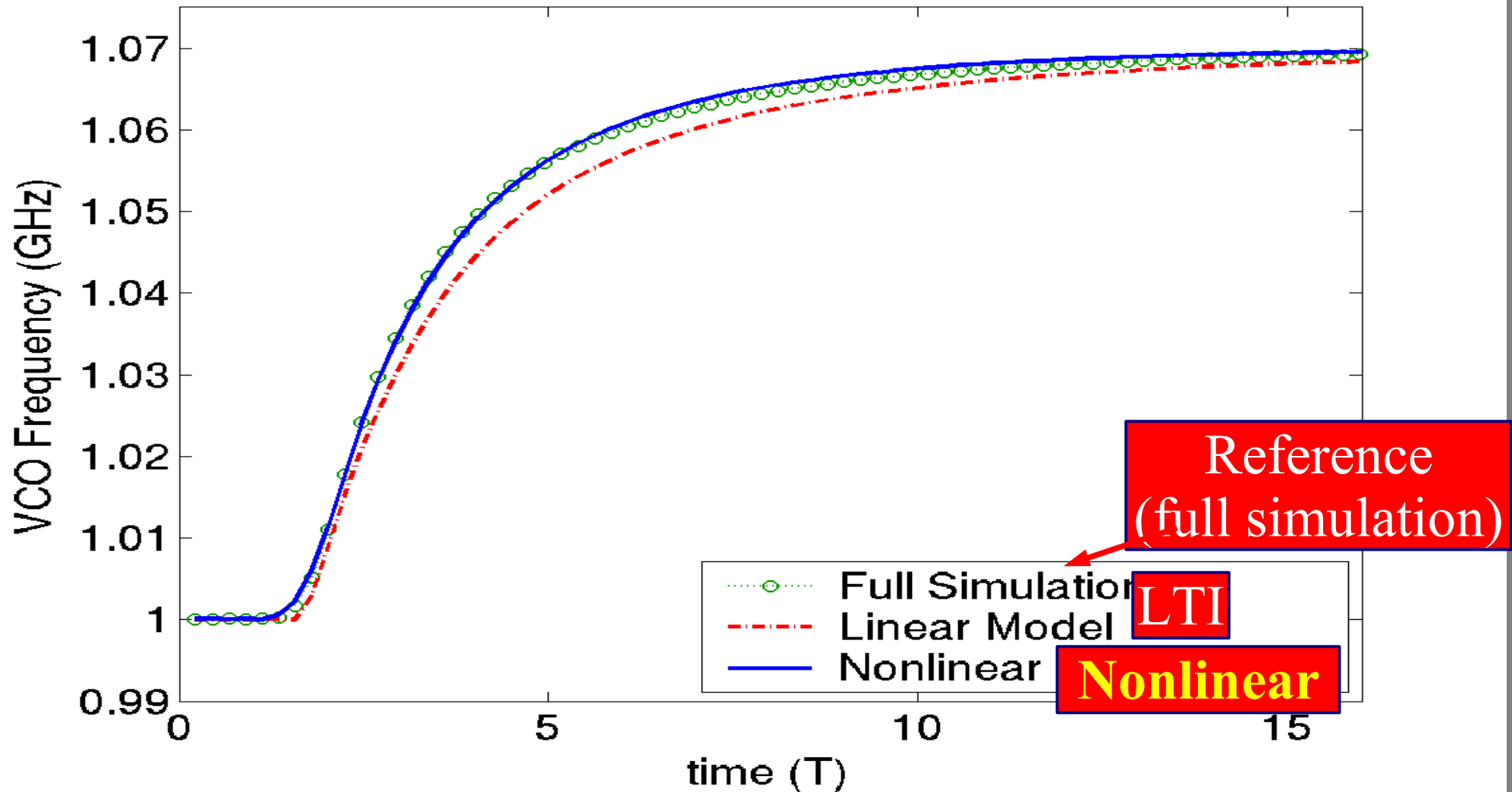
Feature Comparison with Existing Methods

	LTI	LPTV	Our approach
Jitter from white noise	✗	✓ ✗ ⓘ	✓
Flicker/coloured jitter	✗	?	✓
Supply interference jitter	✗	✗ ✓ ⓘ	✓
VCO frequency control	✓ ✗ ⓘ	✓ ⓘ	✓
Injection locking	✗	✗	✓
PLL lock/capture	✓ ⓘ	✓ ⓘ	✓
Cycle slipping	✗ ⓘ	?	✓
Amplitude effects	NA	NA	✓
Model generation speed	Poor ⓘ	Poor	Excellent
Model gen. robustness	Poor	Mediocre	Good ⓘ
Model simulation speed	Excellent	Excellent	Excellent

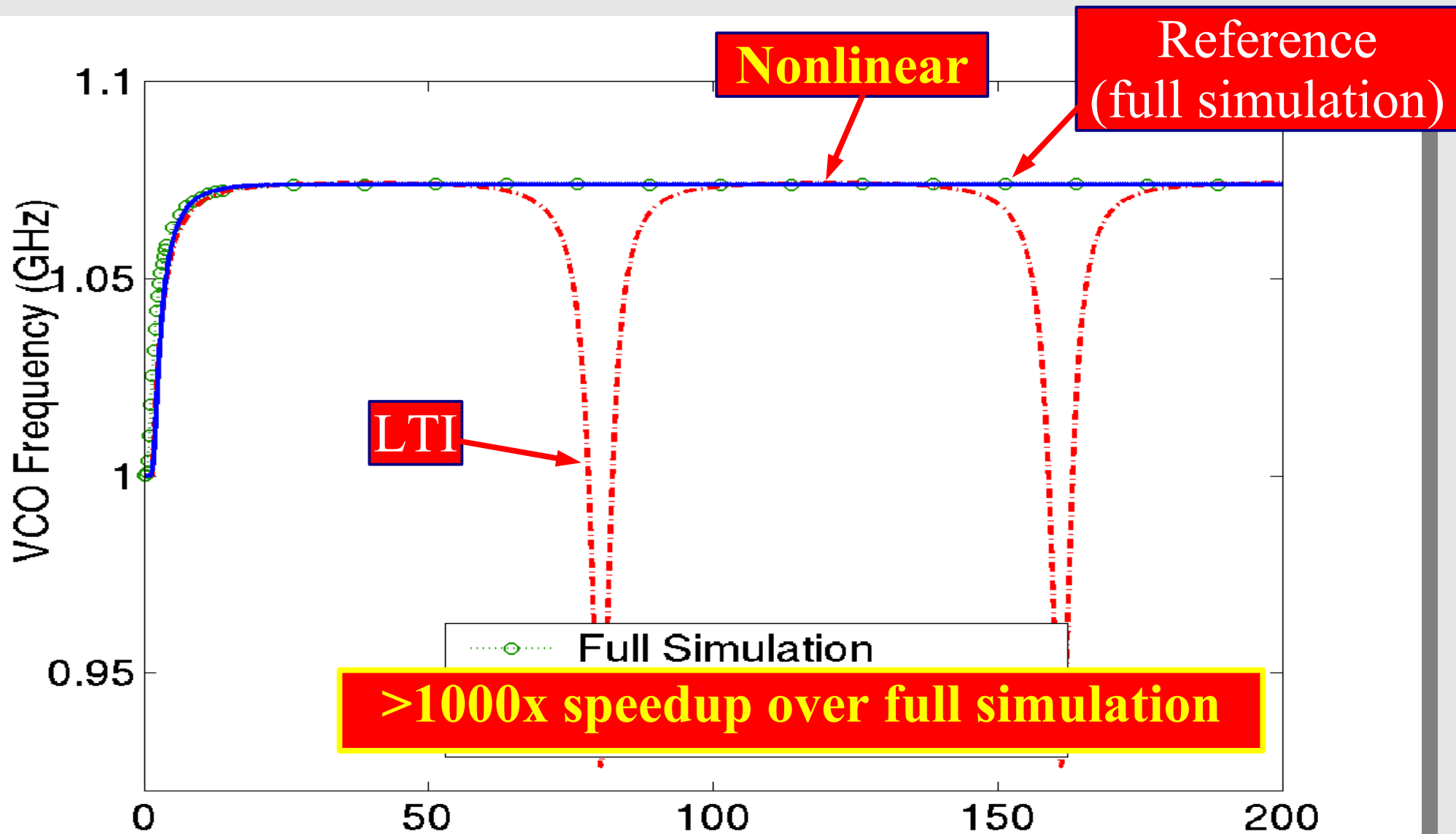
PLL Capture and Lock Transients

PLL Capture/Lock: $f_{ref}=1.07f_0$

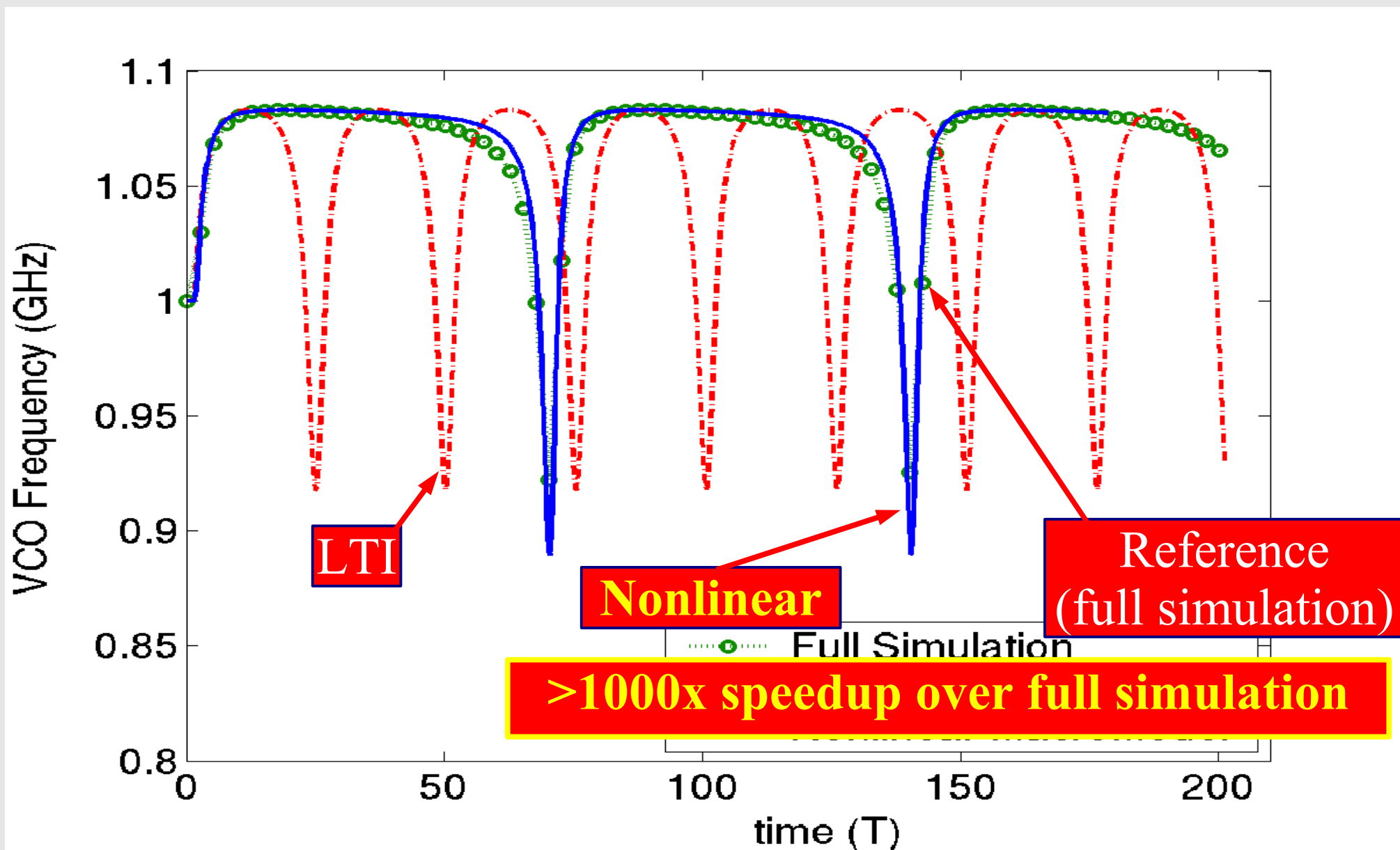
>1000x speedup over full simulation



PLL Capture/Lock: $f_{ref} = 1.074 f_0$

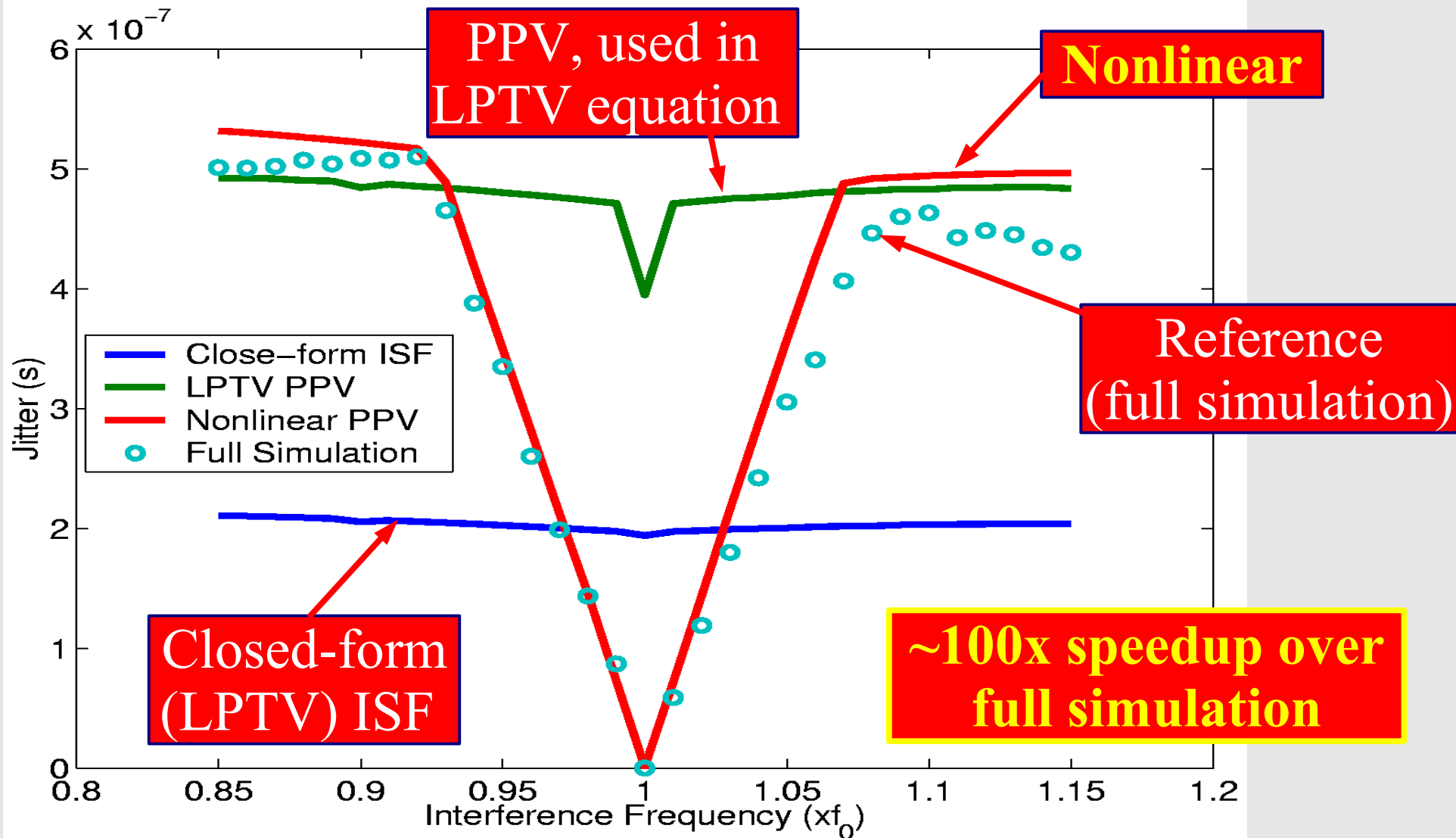


PLL Capture/Lock: $f_{ref} = 1.083 f_0$

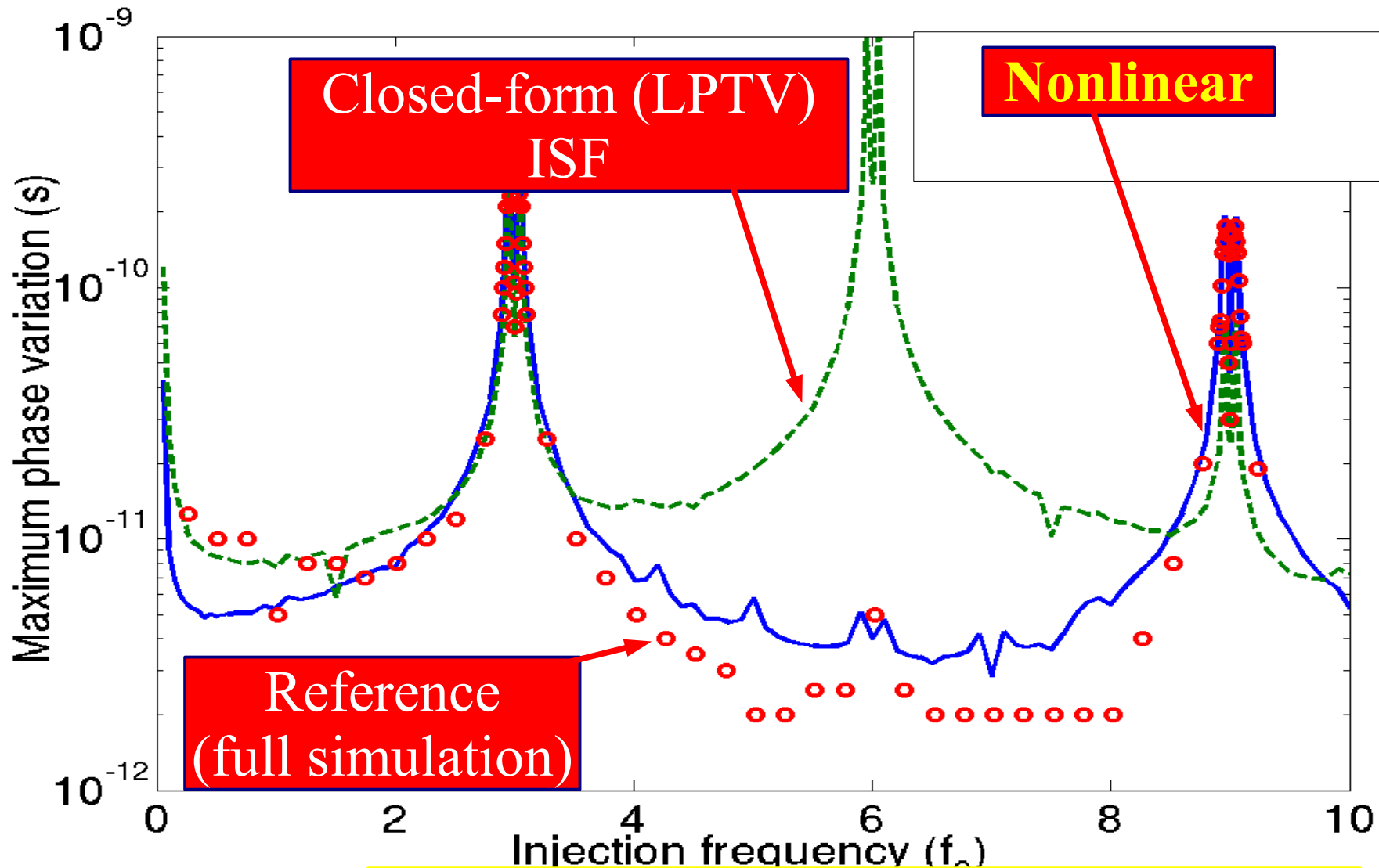


Oscillator and PLL jitter due to Supply Interference

Ring Oscillator: Per-cycle jitter as a function of sinusoidal supply interference frequency



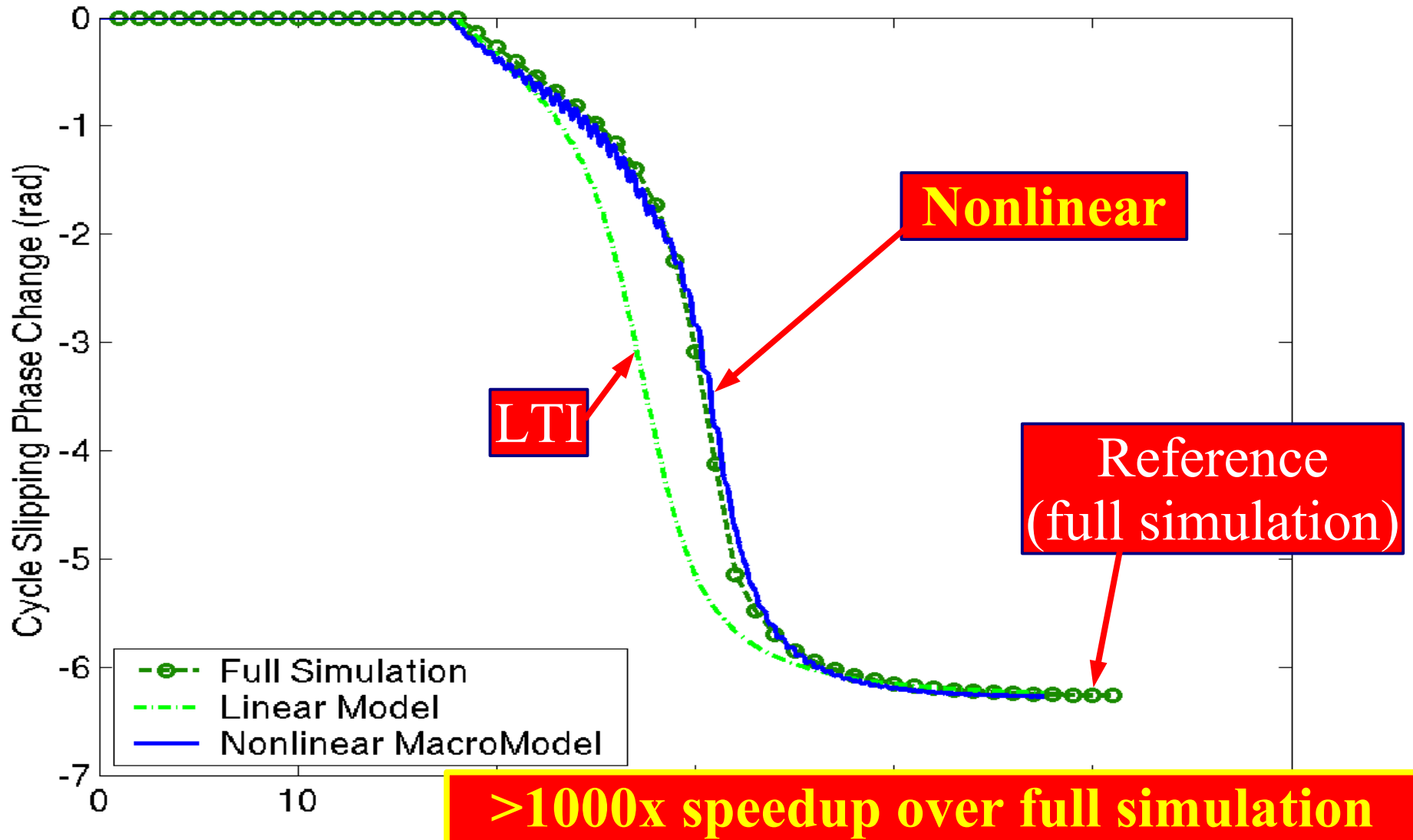
PLL: Max jitter as function of supply interference frequency



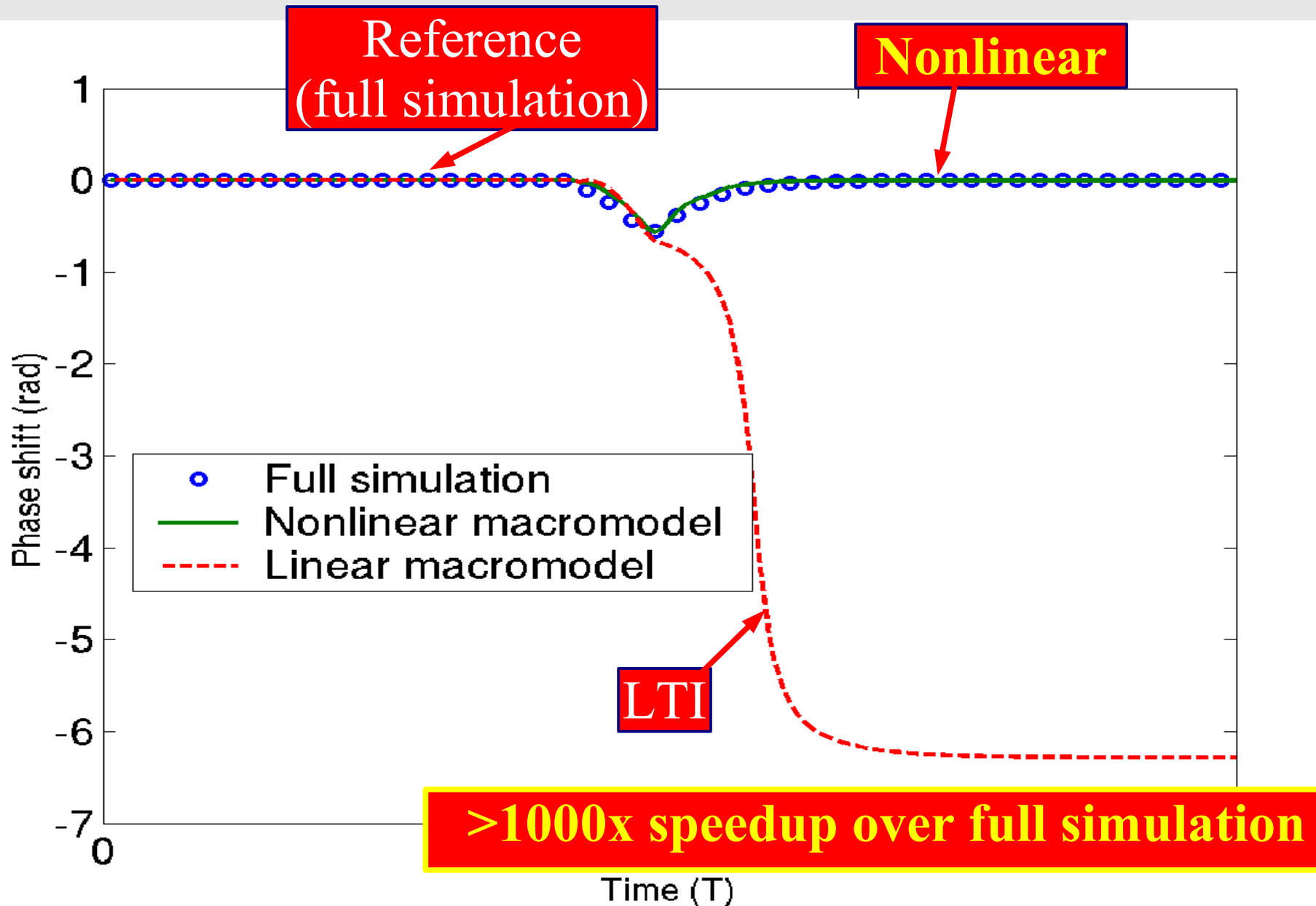
>1000x speedup over full simulation

PLL Cycle Slipping

PLL: cycle slipping (5mA, 10T shock)

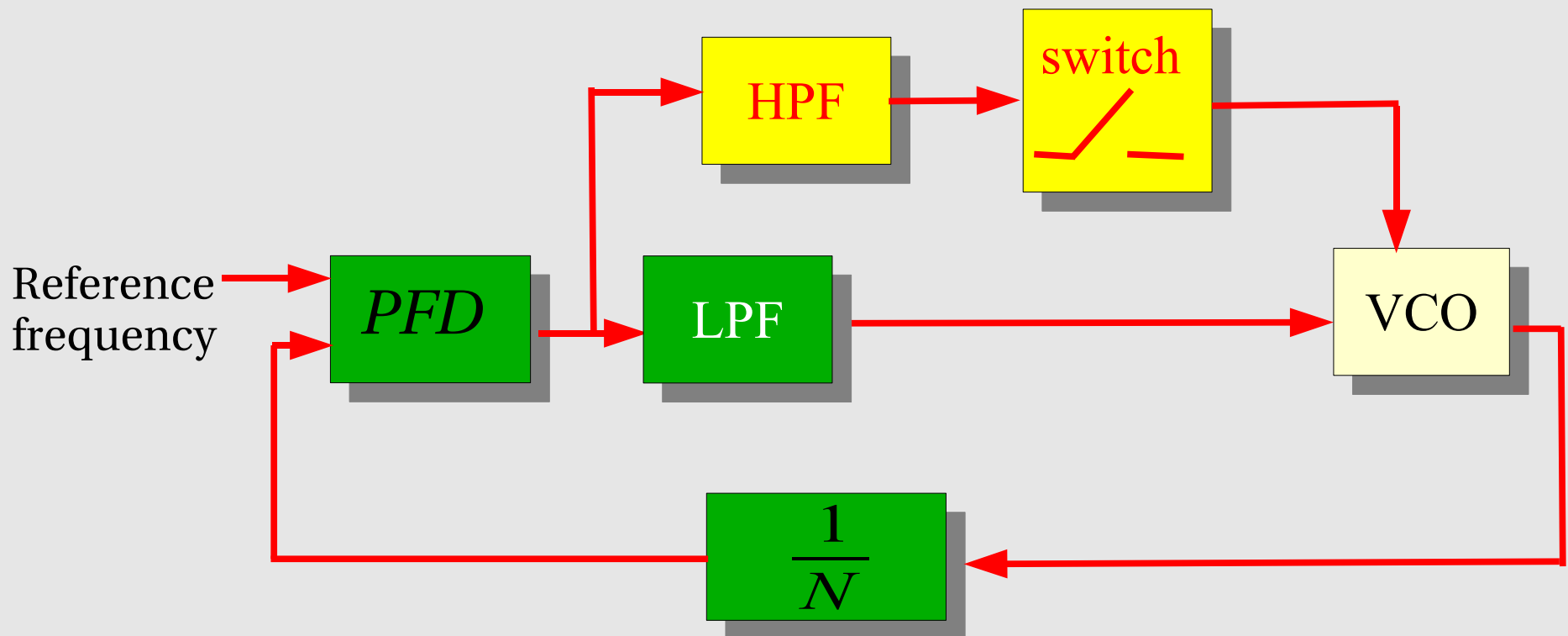


PLL: cycle slipping (3mA, 10T shock)



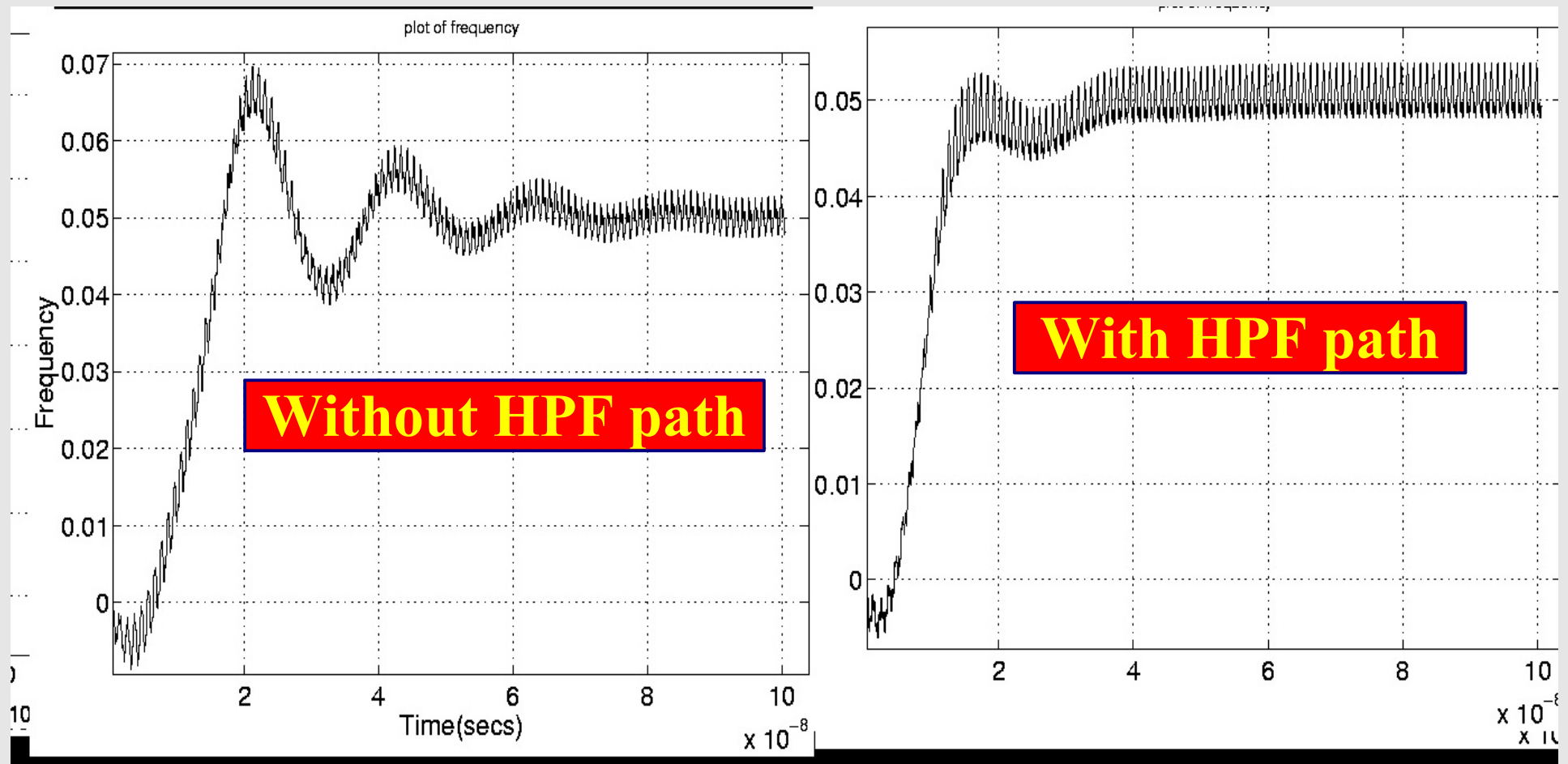
Impact of Nonlinear Macromodels on PLL Design Process

Injection-aided PLL structure



- **Lock acquisition time reduction is important**
- **High-pass path: induces injection locking**
 - **speeds lock acquisition**
- **Once locked, HPF path is switched out of the loop**
 - **to lower phase noise in lock**

PLL Capture (freq shift vs time)



- ~3x faster lock acquisition due to injection aiding

Nonlinear PLL Macromodel: Benefits for Design

- **Linear macromodels: wrong results (though fast)**
 - can mislead, waste design time
- **Nonlinear macromodels: can be trusted during design**
 - sanity checking via SPICE-level simulation: still indispensable
 - ~80 simulations in all
 - ~5 full SPICE-level simulations
 - macromodel offers **100-1000x speedup** over full
 - few minutes/simulation (including macromodel generation)
 - Enables much more thorough exploration of design space
 - **many combinations of parameters, injection paths, ...**
 - **Impractical using full simulation alone**
 - Design exploration completed in ~1 week
 - Estimate: 10x saving in design time vs prior methodologies
 - (with much more complete exploration)

Coupled Oscillator Systems

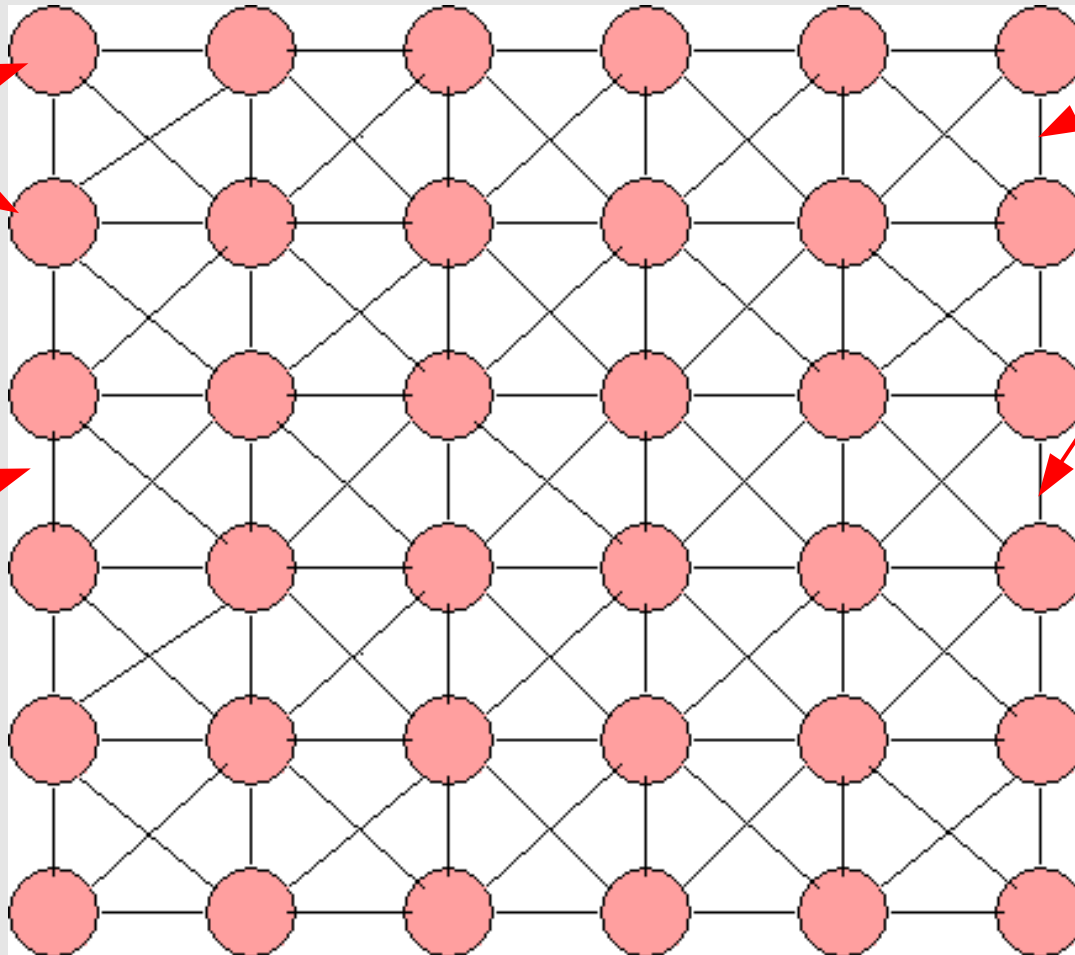
Brusselator biochemical oscillators

$$\begin{cases} \frac{\partial u}{\partial t} = A - (B+1)u + (1 + \gamma \cdot \sin(2\pi ft))u^2v + D_u \nabla^2 u \\ \frac{\partial v}{\partial t} = Bu - u^2v + D_v \nabla^2 v, \end{cases}$$

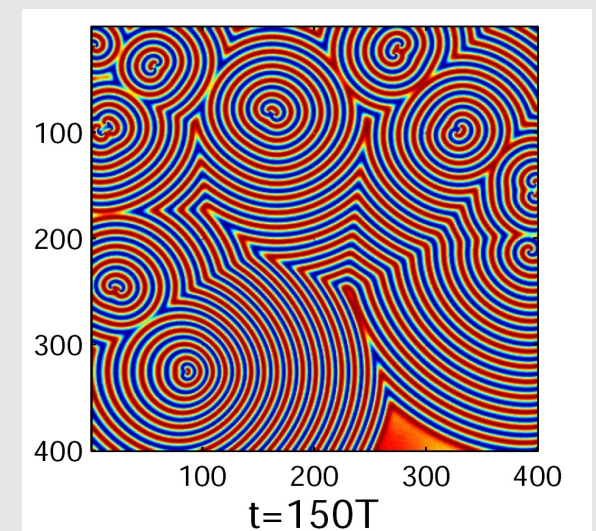
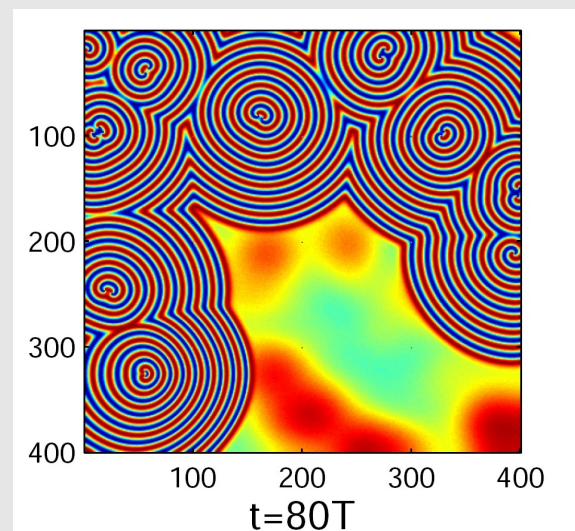
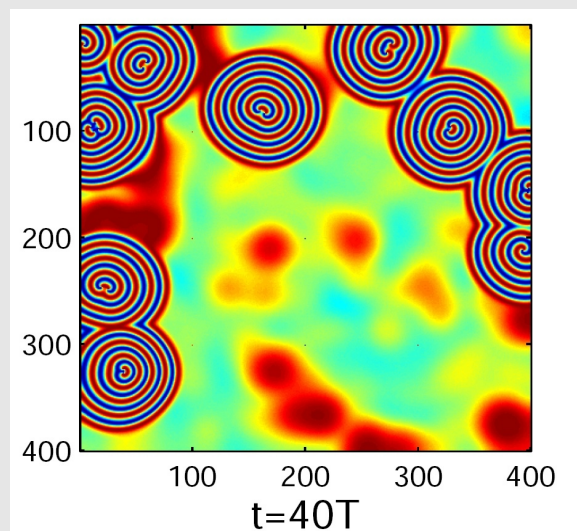
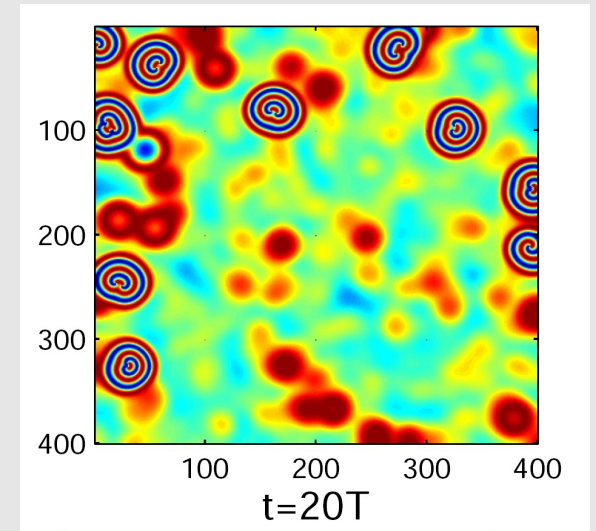
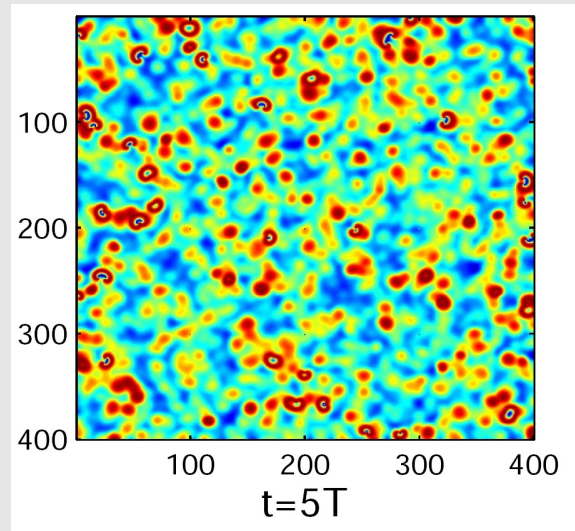
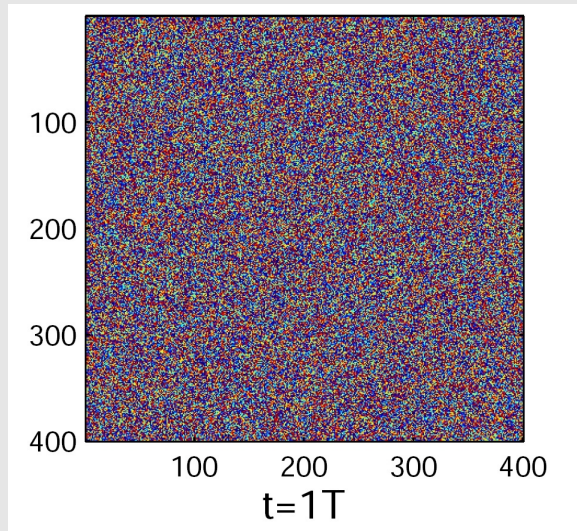
Coupling
(diffusion)
terms

Brusselator
biochemical
oscillators

“Network model” of
coupled oscillators



Spontaneous Pattern Formation: 160,000 coupled Brusselator oscillators ($g=1/15$)



Simulation time: 200 minutes for 160 cycles (MATLAB); est speedup 1200x

Summary

- Nonlinear oscillator macromodel captures:
 - injection locking
 - PLL lock and capture
 - PLL cycle slipping
 - phase noise and jitter in oscillators and PLLs
 - pattern formation in biochemistry
- Productivity enhancer for in design flows
 - 10x faster?
 - Better, more completely explored designs