Circuit Lines for Guiding the Generation of Random Test Sequences for Synchronous Sequential Circuits

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Motivation

| circuit | determ | random |
|---------|--------|--------|
| s208 | 63.72 | 36.74 |
| s382 | 91.23 | 12.28 |
| s526 | 81.80 | 8.65 |
| s1423 | 93.33 | 41.45 |
| s5378 | 79.06 | 63.42 |
| b09 | 81.19 | 22.62 |
| b11 | 92.19 | 19.01 |
| b14 | 88.12 | 44.64 |



- Review of repeated synchronization a cause for the low fault coverage of random primary input sequences.
- Extension of repeated synchronization internal lines repeatedly set to the same values.
- Internal line selection.
- Experimental results.

Repeated Synchronization [Pomeranz & Reddy, ETS-07]

An input cube c synchronizes a subset of state variables S(c) if



Random Input Sequences

If c has a small number of specified values it is likely to appear often in a random primary input sequence.

This will cause the state variables in S(c) to be synchronized repeatedly and may prevent faults from being detected.

Solution: Identify the appearance of input cubes that synchronize state variables and replace them with different values.

Two-Phase Process

Phase 1: Identify a set of input cubes C that synchronize some or all of the state variables.

Phase 2: Modify a random primary input sequence T to eliminate the appearances in T of input cubes from C.

Complexity is polynomial in the circuit size.

Identifying Input Cubes

■ For i=0,1,...,M-1:

- Let v_i be a random primary input vector.
- Apply v_i to the primary inputs when the circuit is in the all-x state.
- Find the set S(v_i) of state variables that become specified one time unit later.
- Unspecify bits of v_i that leave all the state variables in S(v_i) specified.

Parameters

If S(c_i) is small, it is not important to avoid c_i. Require S(c_i)≥N_S for a constant N_S.

If c_i has a large number of specified inputs, it is not likely to appear as part of a random input sequence. Consider primary input vectors with N_I specified values, for a constant N_I.

Avoid an input cube with probability P<1 to allow the circuit to be synchronized.

Results (Fault Coverage)

| | | | modified random | |
|---------|--------|--------|-----------------|----------|
| circuit | determ | random | single | multiple |
| s208 | 63.72 | 36.74 | 63.26 | 63.72 |
| s382 | 91.23 | 12.28 | 86.97 | 89.47 |
| s526 | 81.80 | 8.65 | 70.09 | 78.56 |
| s1423 | 93.33 | 41.45 | 78.75 | 89.77 |
| s5378 | 79.06 | 63.42 | 73.32 | 76.49 |
| b09 | 81.19 | 22.62 | 54.76 | 80.71 |
| b11 | 92.19 | 19.01 | 83.93 | 86.04 |
| b14 | 88.12 | 44.64 | 70.21 | 81.32 |

Internal Line Values

If an internal line g assumes a value w repeatedly under a random primary input sequence, faults that require g=w' are not likely to be detected.

Define a set of lines G that includes nextstate variables as well as internal lines.

Avoid repeated synchronization of all the lines in G.

The Internal Lines in G

- Set $n_0(g)=n_1(g)=0$ for every line g.
- For i=0,1,...,M-1:
- Let v_i be a random primary input vector.
- Apply v_i to the primary inputs when the circuit is in the all-x state.
- For every line g:
 - If g=0 increment $n_0(g)$.
 - If g=1 increment $n_1(g)$.

Interpretation of n₀(g),n₁(g)

- We use a limited number M of primary input vectors.
- If n_w(g)>0 we expect that a random sequence will be able to set g=w.
- If n₀(g)=0 and n₁(g)=0 the value of g will be specified when the state is specified.

We consider g to be likely to be repeatedly set to w (or unlikely to be set to w') if n_w(g)>0 and n_w'(g)=0.

Candidate Lines for G

If n₀(g)>0 and n₁(g)=0, n₀₁(g)=n₀(g).
If n₁(g)>0 and n₀(g)=0, n₀₁(g)=n₁(g).
Otherwise, n₀₁(g)=0.

- Line g may be included in G only if n₀₁(g)>0.
- A higher value of n₀₁(g) makes it more important to include g in G.

Parameter N₀₁

For a given value of N₀₁, G includes all the next-state variables and every line g such that n₀₁(g)≥N₀₁.

Possible values for N_{01} : { $n_{01}(g)>0$ }.

In addition, M+1 will allow only next-state variables to be included in G.

Definition of Synchronization

Given a set of lines G, an input cube c synchronizes a subset of lines S(c) contained in G if applying c to the primary inputs, when the circuit is in the allunspecified state, results in the specification of the lines in S(c). Results for a Single Random Primary Input Sequence

- A single random sequence of length L=1000.
- M=10000.
- ■NS=1, 2,
- P=15/16, 14/16, ..., 8/16.
- All the possible values of N01.
- Find the best modified random sequence.

Results for a Single Sequence

| | | | modified random | |
|---------|--------|--------|----------------------|-------------------------------------|
| circuit | determ | random | N ₀₁ =M+1 | N ₀₁ <m+1< td=""></m+1<> |
| s208 | 63.72 | 36.74 | 63.26 | [7088] <mark>63.72</mark> |
| s382 | 91.23 | 12.28 | 86.97 | - |
| s526 | 81.80 | 8.65 | 70.09 | [5015]75.50 |
| s1423 | 93.33 | 41.45 | 78.75 | [2991]83.30 |
| s5378 | 79.06 | 63.42 | 73.32 | _ |
| b09 | 81.19 | 22.62 | 54.76 | [4971]70.24 |
| b11 | 92.19 | 19.01 | 83.93 | [5007]86.13 |
| b14 | 88.12 | 44.64 | 70.21 | [1559]71.42 |

Best Value of N₀₁

- One of the highest values possible.
- To modify multiple random sequences:
 - The three smallest values of NS.
 - P=15/16, 14/16, ..., 8/16.
 - The 10 highest values of N_{01} .
- All combinations for every sequence until 10 sequences do not improve the fault coerage.

Results for Multiple Sequences

| | | | modified random | |
|---------|--------|--------|-----------------|----------|
| circuit | determ | random | single | multiple |
| s208 | 63.72 | 36.74 | 63.72 | |
| s382 | 91.23 | 12.28 | 86.97 | 90.98 |
| s526 | 81.80 | 8.65 | 75.50 | 81.62 |
| s1423 | 93.33 | 41.45 | 83.30 | 89.77 |
| s5378 | 79.06 | 63.42 | 73.32 | 76.52 |
| b09 | 81.19 | 22.62 | 70.24 | 81.19 |
| b11 | 92.19 | 19.01 | 86.13 | 91.55 |
| b14 | 88.12 | 44.64 | 71.42 | 80.56 |

Conclusion

- An internal line may be set repeatedly to the same value by a random primary input sequence.
- This may prevent certain faults from being detected by the sequence.

A procedure that considers repeated setting of internal lines as well as repeated synchronization of next-state variables can improve the fault coverage significantly.