



UCSC

CLOCK TREE OPTIMIZATION FOR ELECTROMAGNETIC COMPATIBILITY (EMC)

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Outline

2

- Background
- Problem formulation
- Van Ginneken's dynamic programming
- Our algorithm
- Experimental results
- Conclusion

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3

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Electromagnetic Interference (EMI)

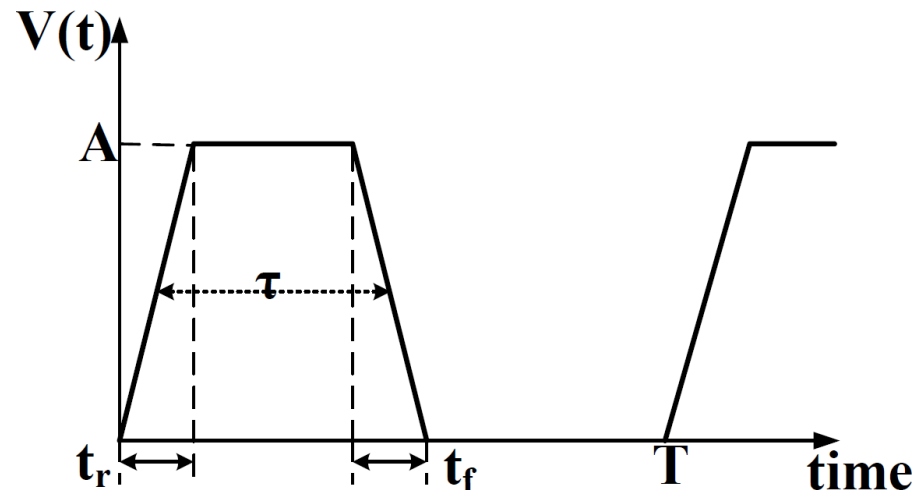
4

- On-chip Electromagnetic Interference (EMI)
 - Signal integrity, reflections
 - Simultaneous switching noise (SSN)
 - Previous work
 - Decoupling capacitances
 - Random jitter insertion, spread spectrum
 - Clock design
 - Polarity of buffers
 - Skew
 - Reduce buffer sizes
- } Manual optimization
NOT CTS

Spectral Analysis of Clock Signal

5

- Clock in time domain
 - Period T , frequency f , amplitude A
 - Rising/falling time, t_r/t_f
 - duty cycle $D = \tau/T$



Spectral Analysis of Clock Signal

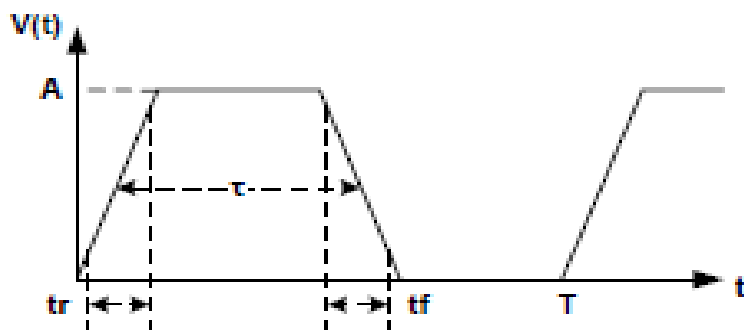
6

- Clock in frequency domain
 - Fourier analysis
 - Periodic function \rightarrow sum of a series of sine and cosine functions

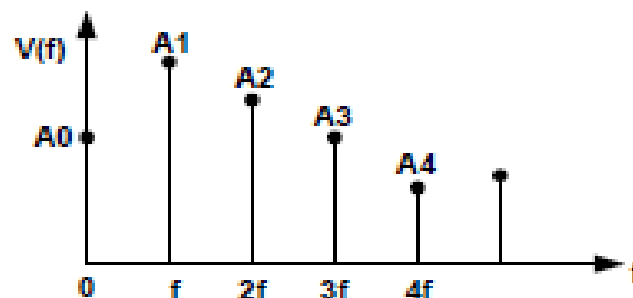
$$V(t) = A_0 + A_1 \cos(\omega_0 t + \phi_1) + A_2 \cos(\omega_0 t + \phi_2) + A_3 \cos(\omega_0 t + \phi_3) + \dots$$

$$A_0 = \frac{1}{T} \int_0^T v(t) dt = A \frac{\tau}{T}$$

$$|A_n| = 2A \frac{\tau}{T} \left| \frac{\sin(n\pi\tau/T)}{n\pi\tau/T} \right| \left| \frac{\sin(n\pi\tau_r/T)}{n\pi\tau_r/T} \right|$$



Clock signal in time domain



Clock signal in frequency domain

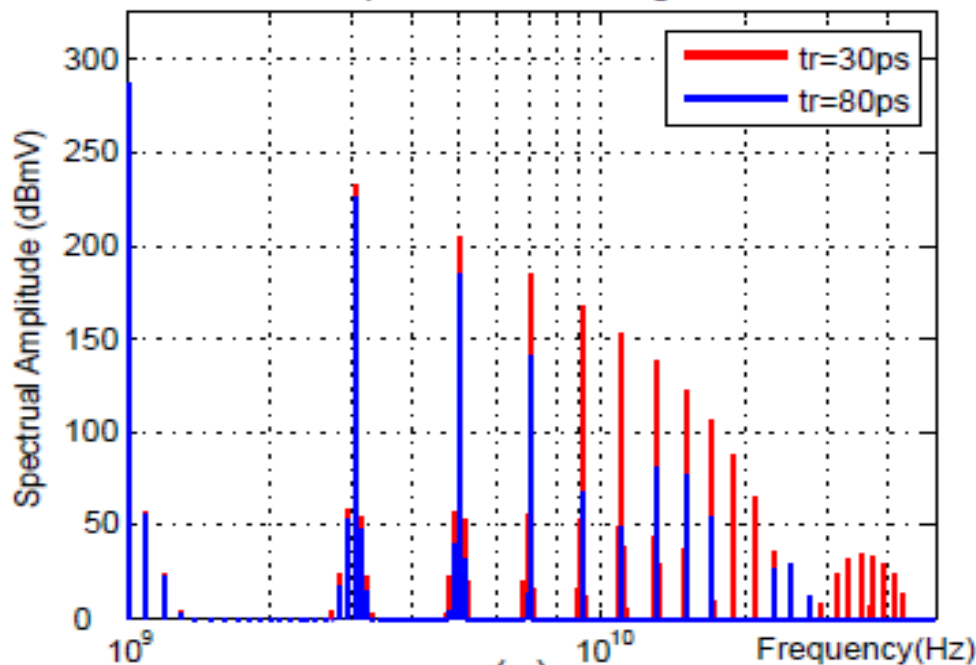
Spectral Analysis of Clock Signal

7

- Majority of spectrum power lies below f_{max}

$$f_{max} \approx 1/t_r$$

- High-frequency spectrum: *rising/fall time, t_r/t_f*

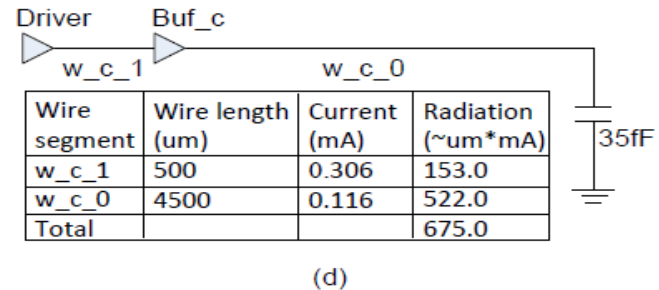
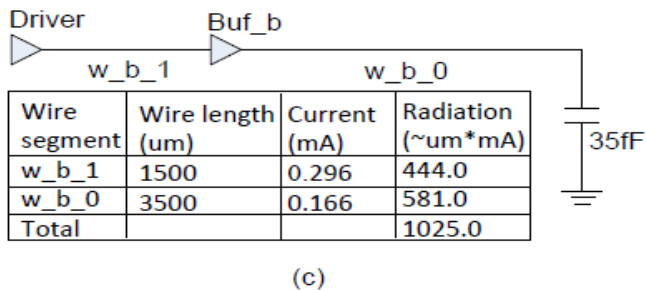
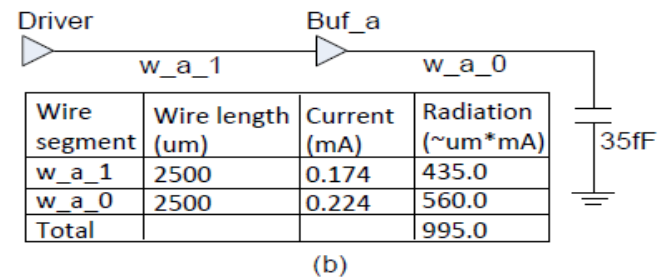
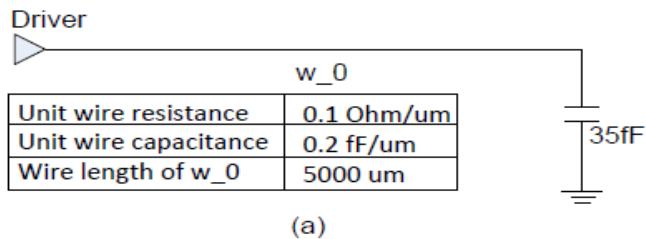


Spectrum of clock signal

$$t_r=30ps \quad f_{max}=31.8G$$
$$t_r=80ps \quad f_{max}=11.9G$$

Radiation Emission

- Radiation emission
 - ▣ Radiation power \propto frequency \times length \times current
 - ▣ Frequency \rightarrow fixed
 - ▣ Total wire length \rightarrow fixed
- Different buffer locations \rightarrow different radiation



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9

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Problem Formulation

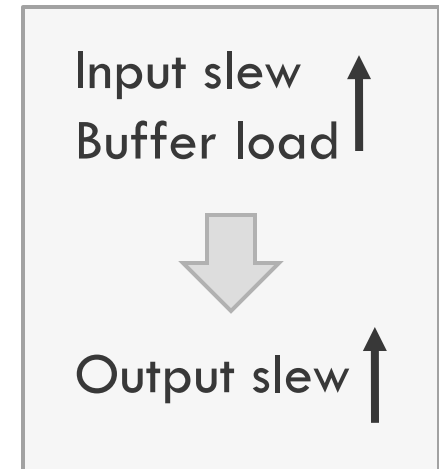
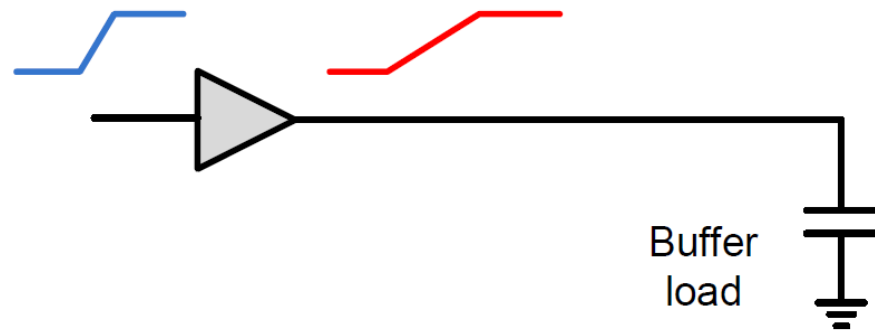
10

- Given:
 - A buffered clock tree T
 - Buffer library $L = \{s_1, s_2, s_3, \dots, s_n\}$
 - Maximum slew rate constraint S_{\max} : noise immunity
 - Minimum slew rate constraint S_{\min} : EMC
- Output:
 - Minimize skew, power (traditional metrics in CTS)
 - Location p_i and size s_i of each buffer $b_i \in B$
 - Reduce high-frequency spectrum contents

Slew Rates Constraints

11

- Problem: control slew rate in a feasible range
 - ▣ Buffer output slew rate: input slew, buffer load



- Solution: control the buffer load in a feasible range

$$S_{\max} \sim S_{\min} \longleftrightarrow C^H \sim C^L$$

Outline

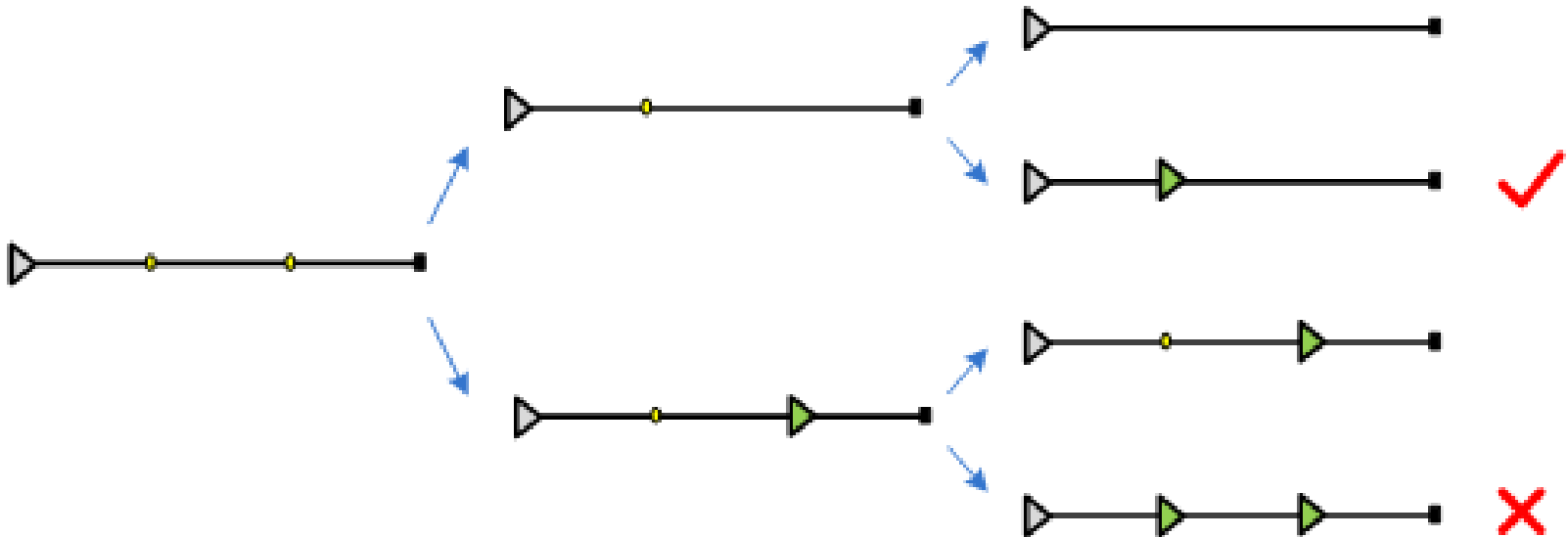
12

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Van Ginneken's Dynamic Programming

13

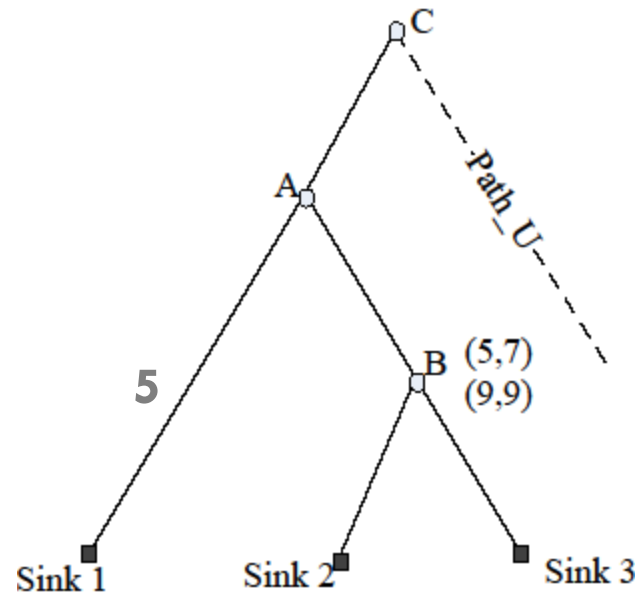
- Goal: maximize slack/RAT, minimize delay
- Method:
 - Generate all possible solution
 - Deleted dominated solutions/Pruning
 - worse down stream load cap & worse RAT/delay



Dynamic Programming in CTS

14

- Clock tree
 - ▣ Skew: difference between each pair of sinks
- Pruning
 - ▣ Base on delay
 - ▣ Base on skew



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15

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Top Level Algorithm

16

- Dynamic programming
 - ~~Optimize whole tree~~
 - Optimize the critical path
 - Reduces complexity
- All buffers on non-critical path are fixed
- Timing of non-critical path are fixed
- Non-critical path as reference when do pruning

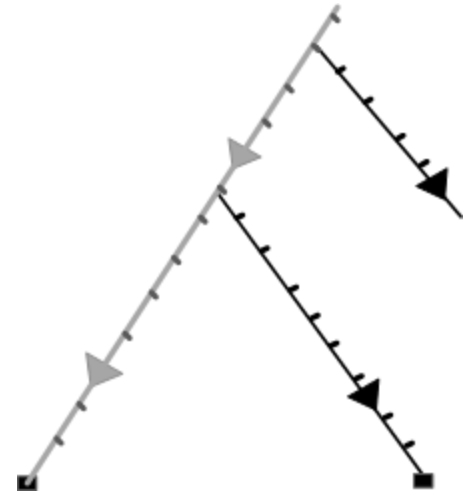
Top Level Algorithm

17

- Procedure
 - Step 1: segment edges
 - Step 2: relocate and size the critical path (DP)
 - Step 3: update timing
 - Step 4: repeat step2~4 until no improvement

Improvement:

skew, power, radiation, slew rate



Relocating and Sizing the Critical Path

18

Relocate and size buffers on critical from sink to root

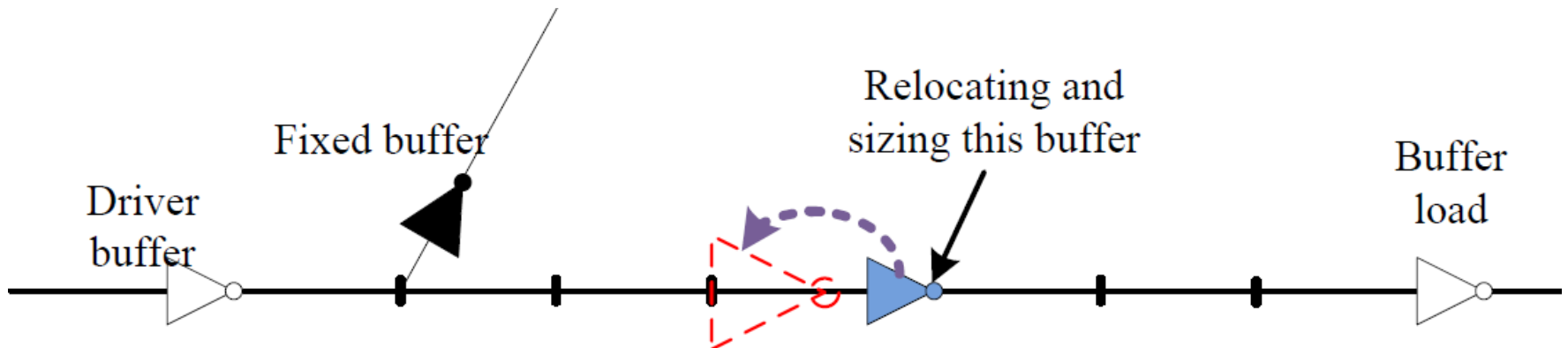
For each buffer b_i

Generate all possible position and size combinations (p_i, s_i)

Check the capacitance constraints of each combination

If satisfy, save this solution

End for



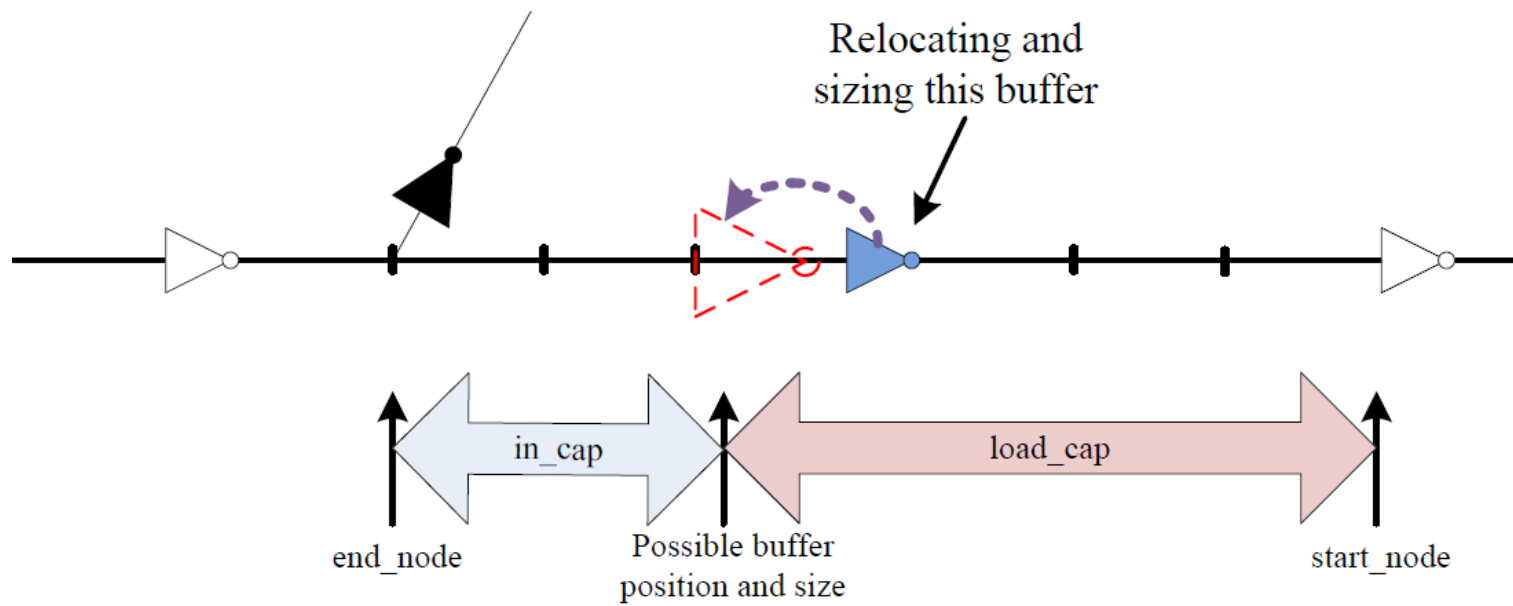
Capacitance Constraints

19

- Slew rate constraints
- Capacitance constraints

$$C_{l_k}^L \leq out_cap \leq C_{c_k}^H$$

$$in_cap \leq C^H$$



Interval Solution Pruning

20

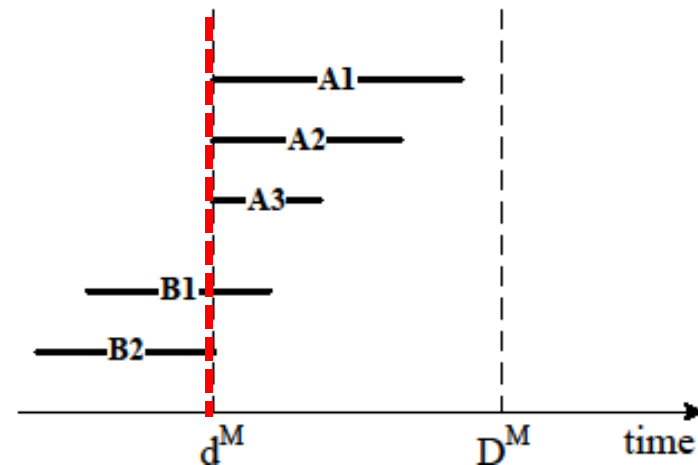
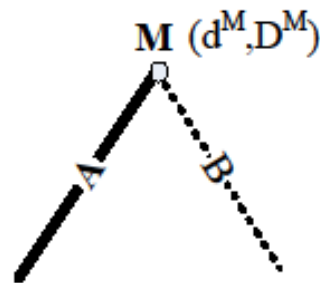
- Only do pruning at merging nodes
- Based on minimum/maximum delay
- Delays in original tree: (d^M, D^M)
- Classify the solutions into two categories:
 - ▣ $d = d^M$: A1, A2, A3
 - ▣ $d < d^M$: B1, B2

Optimizing a maximum path

Path A: maximum delay path

Path B: fixed path

M : merging node



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21

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Experimental Setup

22

- 45nm technology
- ISCAS benchmarks
- Clock frequency: 1GHz
- Minimum slew: $S_{\min} = 50\text{ps}$
- Maximum slew: $S_{\max} = 100\text{ps}$
- Four different buffers in buffer library L

Experimental Results

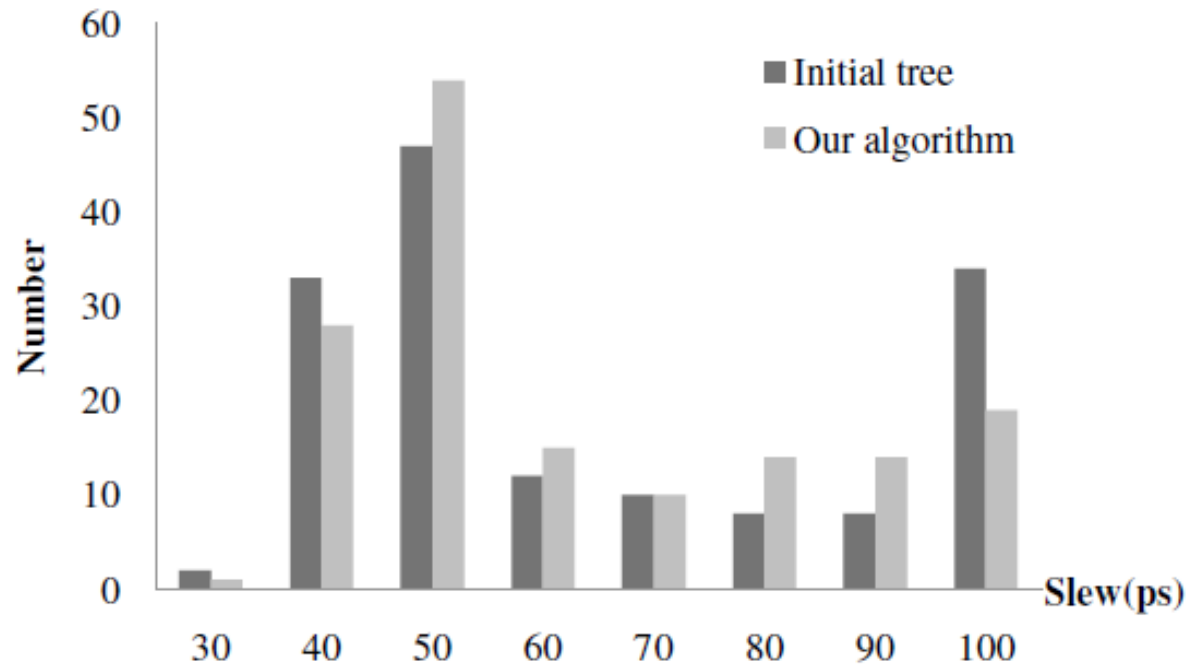
23

Benchmark		Initial tree				Our method					
Name	Sink	Power	Radiation	Skew	Slew < 50ps (%)	Power	Radiation	Skew	Slew < 50ps (%)	CPU (s)	Iteration (#)
s5378	179	1.0	1.00	1.00	44	1.02	0.99	0.57	33	0.7	10
s9234	211	1.0	1.00	1.00	43	1.01	0.95	0.49	31	1.5	10
s13207	638	1.0	1.00	1.00	50	1.00	0.88	0.74	30	9.9	9
s15850	534	1.0	1.00	1.00	38	1.00	0.88	0.78	28	5.9	4
s35932	1728	1.0	1.00	1.00	38	1.00	0.94	0.63	32	203.2	19
s38584	1426	1.0	1.00	1.00	64	1.00	0.98	0.81	48	90.7	8
Average	786	1.0	1.00	1.00	46	<u>1.01</u>	<u>0.94</u>	<u>0.67</u>	<u>34</u>	52.0	10

- Power: 1% ↑
- Skew: 33% ↓
- Radiation: 6% ↓
- Slew < 50ps: 46% → 34%
- Run time: 52s

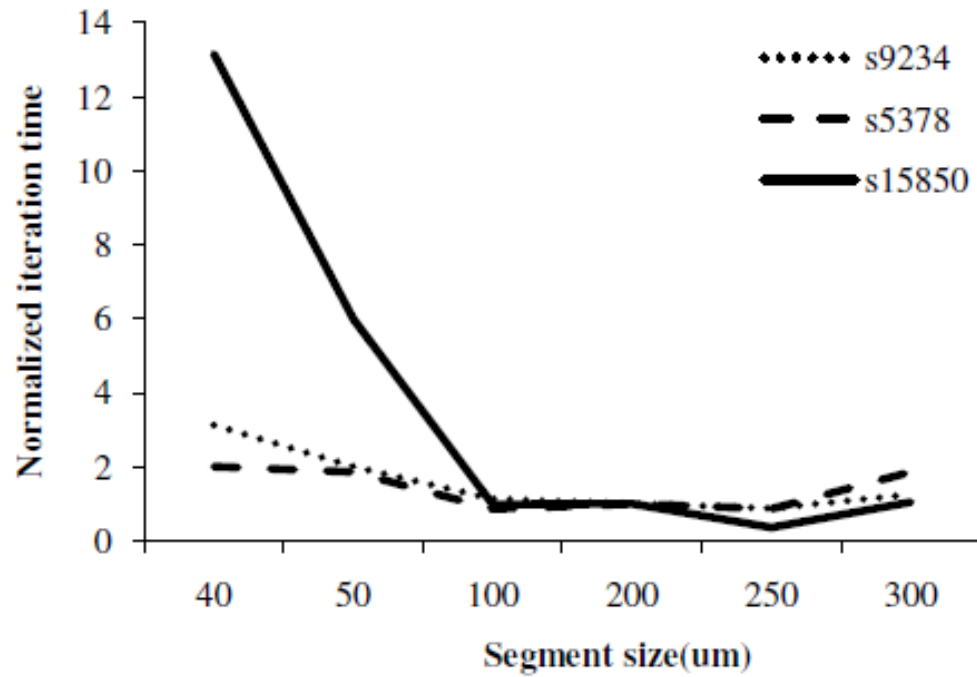
Slew distribution

24



Segment size

25



Conclusions

26

- Comprehensive analysis of EMI in clock tree
- A solution for EMI reduction
- Consider both maximum and minimum buffer slew rate
- An incremental dynamic programming in CTS

THANKS !