

Path Criticality Computation in Parameterized Statistical Timing Analysis

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Outline

- Introduction
- Path criticality formulation
 - $P\left(\bigcap_{i=1}^m A_k < B_k\right)$
- A novel method to compute a joint probability in SSTA
- Conclusions

Introduction


- In SSTA, criticality is a representative metric to gauge how important a given edge or path is in terms of timing
- The *criticality* of a path is defined as the probability that the path becomes the critical path
- The *criticality* of an edge is defined as the probability that the edge is on the critical path

Introduction

- Criticality is used in timing/yield optimization
 - Gate sizing, buffer insertion, Vth assignment
 - Transistor sizing
- Criticality is also very useful in testing
 - Timing critical paths (i.e., paths with high path criticality values) can be selected using SSTA
 - An ATPG tool takes these paths and generates test patterns sensitizing them
 - These patterns can be employed in performance testing, SDD testing, and speed-binning

Previous Work

- Run SSTA
- Obtain the circuit slack S_c
- Obtain the slack $S(p_1)$ of a given path p_1
- Compute $P(S(p_1) < S_c)$

$$S_c = \min\{S(p_1), S(p_2), S(p_3), \dots\}$$


Previous Work

- The complement slack of a path is the minimum of all path slacks in the circuit excluding the path slack
- Obtain the complement slack $\overline{S}(p_1)$ from $S(p_1), S_c$
- Compute

$$P(S(p_1) < \overline{S}(p_1))$$

$$\overline{S}(p_1) = \min\{S(p_2), S(p_3), \dots\}$$

Lots of information is captured by
a too simple linear form

General path criticality formulation

- Partition the set of all paths in the circuit into m groups
- Compute the minimum path slack of each group
- Path criticality of p_1 can be written as

$$P\left(\bigcap_{i=1}^m S(p_1) < S_i\right)$$

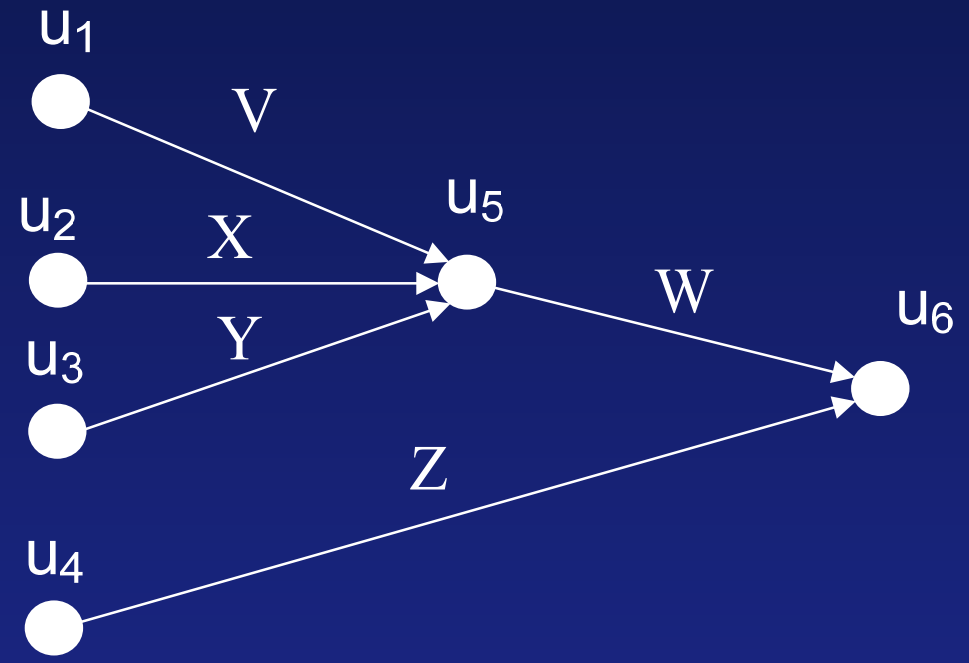
1. Various ways to formulate path criticality
2. Smart formulation considering non-idealities of SSTA can reduce errors

Partitioning

group 1 $p_1 : u_1 \rightarrow u_5 \rightarrow u_6$

group 2 $p_2 : u_2 \rightarrow u_5 \rightarrow u_6$
 $p_3 : u_3 \rightarrow u_5 \rightarrow u_6$

group 3 $p_4 : u_4 \rightarrow u_6$



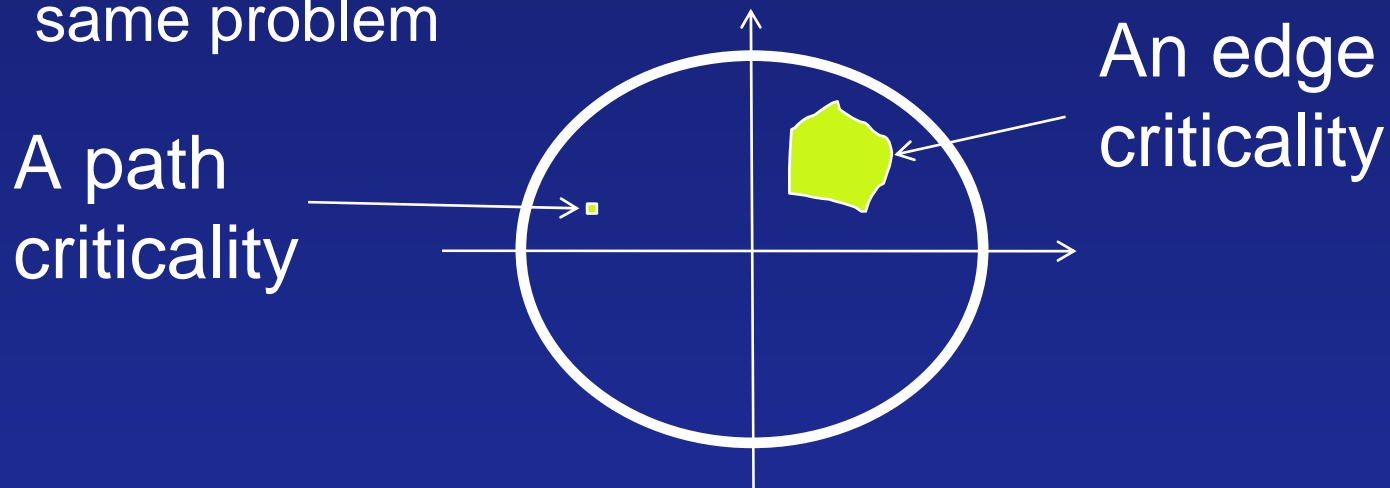
$$\begin{aligned}
 & P((V + W > \max\{X + W, Y + W\}) \cap (V + W > Z)) \\
 &= P((V + W > \max\{X, Y\} + W) \cap (V + W > Z)) \quad \text{distributivity} \\
 &= P((V > \max\{X, Y\}) \cap (V + W > Z))
 \end{aligned}$$

Computing a joint probability

- Path criticality computation is reduced to evaluating the multivariate normal CDF

$$\begin{aligned} P\left(\bigcap_{i=1}^m A_k < B_k\right) &= P\left(\bigcap_{i=1}^m A_k - B_k < 0\right) \\ &= \Phi(x_1, x_2, \dots, x_m) \end{aligned}$$

- Edge criticality computation is also reduced to the same problem



A new way to evaluate the CDF

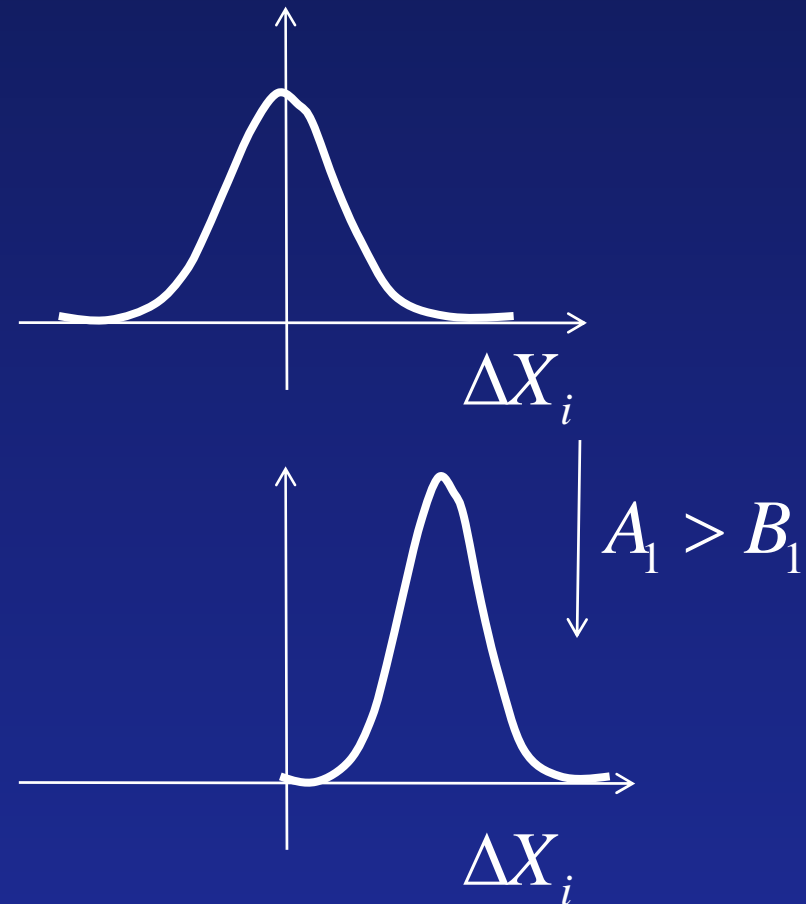
- Previous approaches to evaluate the CDF
 - Numerical Integration (e.g., `mvncdf` in matlab)
 - Accurate but **extremely slow**
 - Monte Carlo sampling (**slow**)
 - Using the max operation provided by SSTA
 - Very fast but **poor accuracy**
- We propose a novel, analytic conditioning operation
 - 1000x faster than Monte Carlo sampling at the same accuracy
 - 2~3x accurate at the cost of 3~4x runtime compared to max operation

Conditioning operation

$$P\left(\bigcap_{i=1}^2 A_k < B_k\right) = P(A_1 < B_1)P(A_2 < B_2 \mid A_1 < B_1)$$

$$A_2 = a_0 + \sum_{i=1}^n a_i \Delta X_i + a_{n+1} \Delta R_a$$

$$A_2 \mid_{A_1 > B_1} = a_0 + \sum_{i=1}^n a_i \Delta X_i + a_{n+1} \Delta R_a$$



Conditioning operation

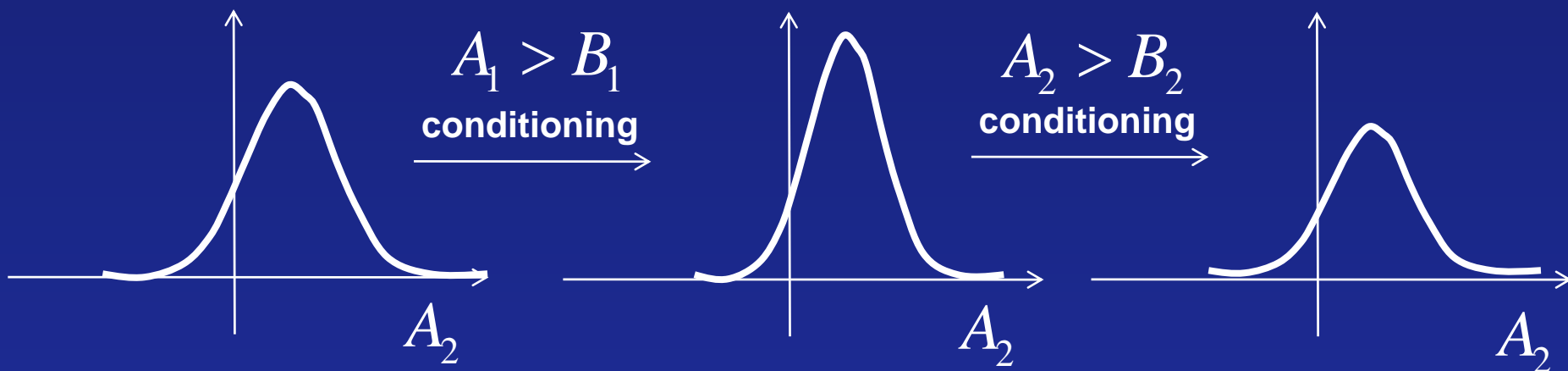
- Theorem 1. Let A and B be normal R.V.s.

$$E[\Delta X_i | A > B] = E[\Delta X_i] + \beta(\text{cov}[A, \Delta X_i] - \text{cov}[B, \Delta X_i]) / a$$

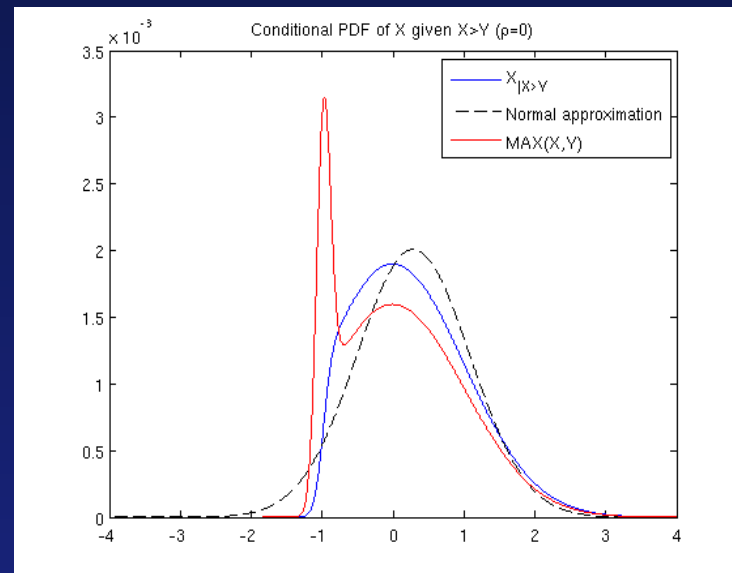
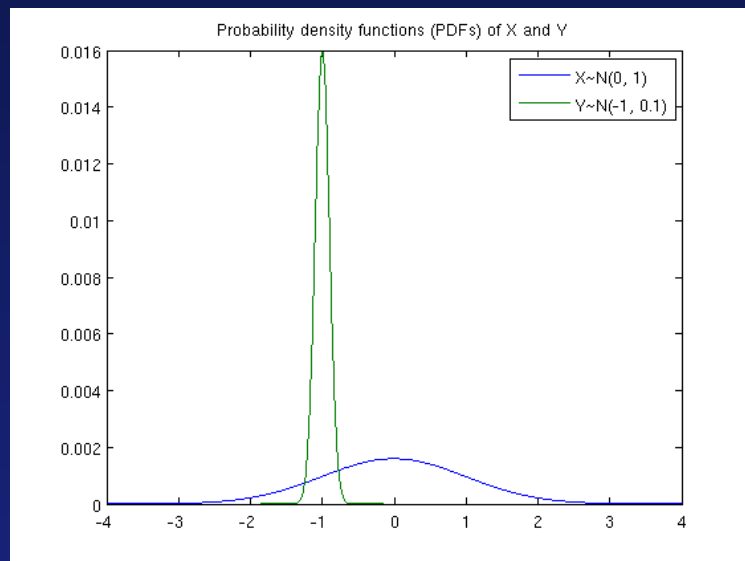
$$\text{cov}(\Delta X_i, \Delta X_j | A > B) = \text{cov}[\Delta X_i, \Delta X_j] - (\beta^2 + \alpha\beta)$$

$$(\text{cov}[A, \Delta X_i] - \text{cov}[B, \Delta X_i])(\text{cov}[A, \Delta X_j] - \text{cov}[B, \Delta X_j]) / a^2$$

$$A_2 |_{A_1 > B_1} = a_0 + \sum_{i=1}^n a_i \Delta X_i + a_{n+1} \Delta R_a \quad \mu = [\dots], \Sigma = [\dots]$$



Conditioning operation

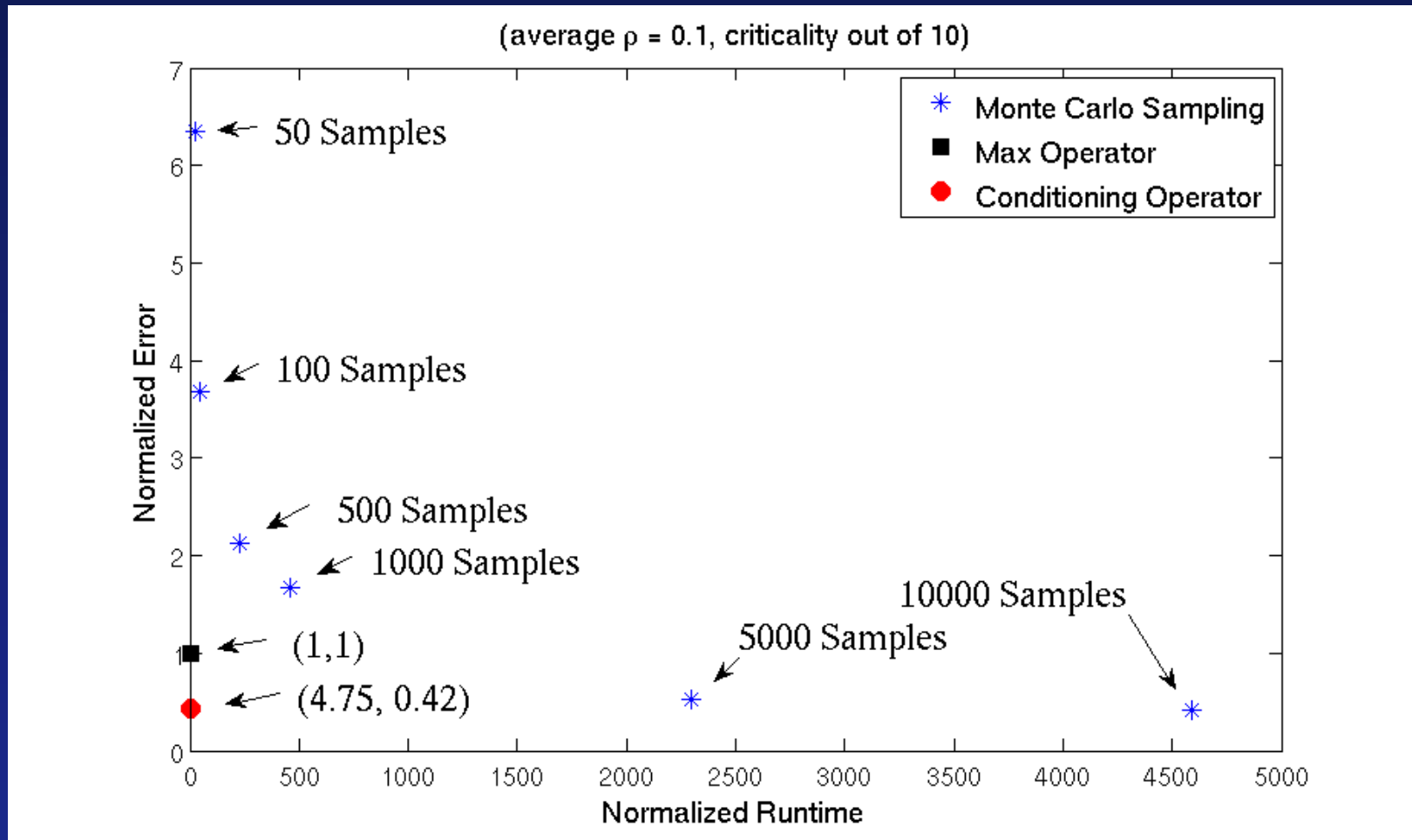


- Error analysis of normal approximation in max operation [D. Sinha et. al. TCAD 2007]
- The same analysis was done for conditioning operation
 - More than 2x less error
 - Error is much less for positively correlated timing quantities

Experimental Results

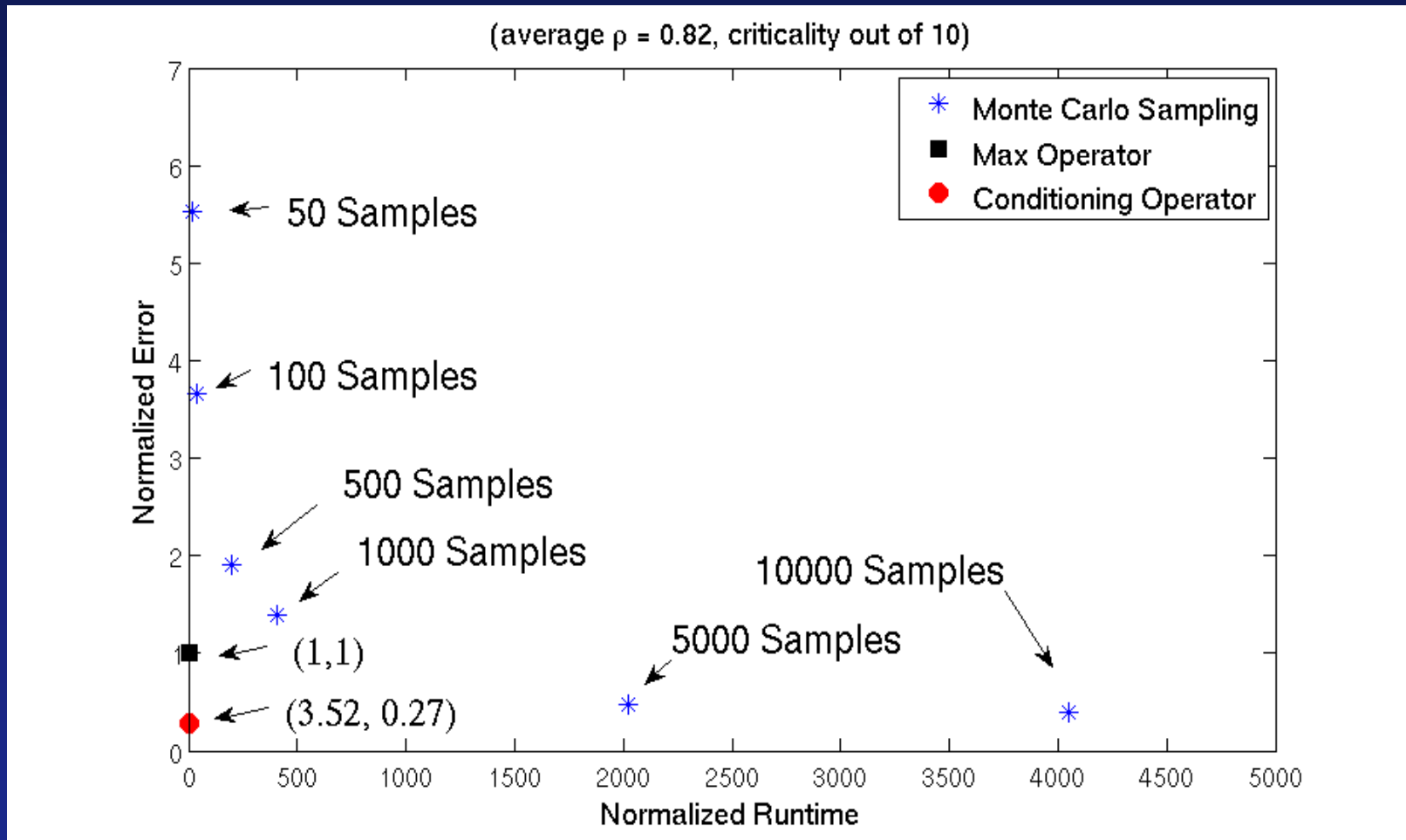
- Randomly generated 10 timing quantities represented in the canonical form with 21 global sources of variation
 - Mean: within a range of [1.0, 3.0]
 - Std.: from 10% to 20% of the mean
 - Sensitivity values:
 - Case 1) chosen within a range of [-1.0,1.0] and then normalized in order to meet the std. value
 - Case 2) chosen within a range of [0,1.0] and normalized
- Compute criticality of randomly chosen one out of the 10 timing quantities

Experimental Results



Case 1 $\rho = 0.1$

Experimental Results

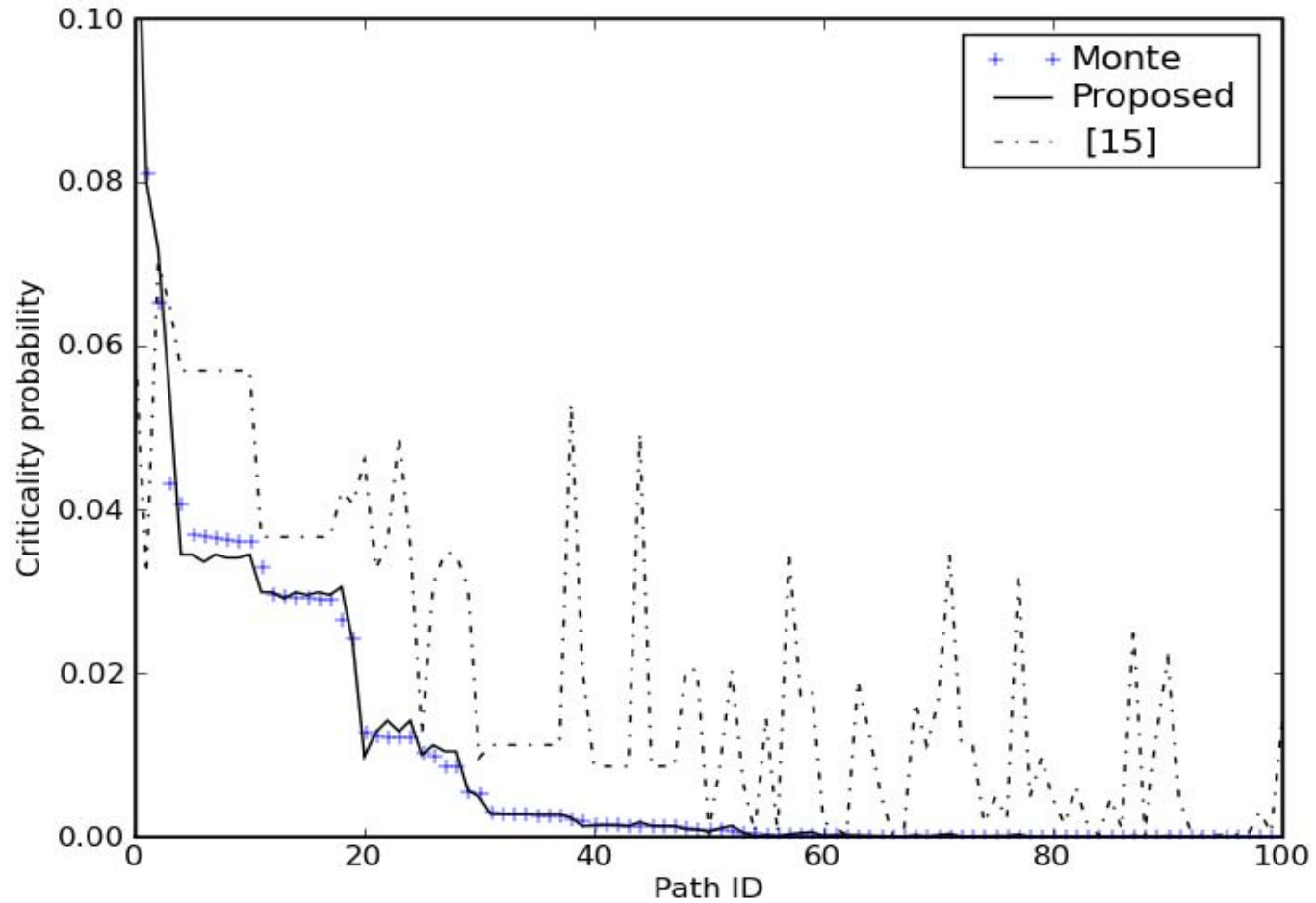


Case 2 $\rho = 0.82$

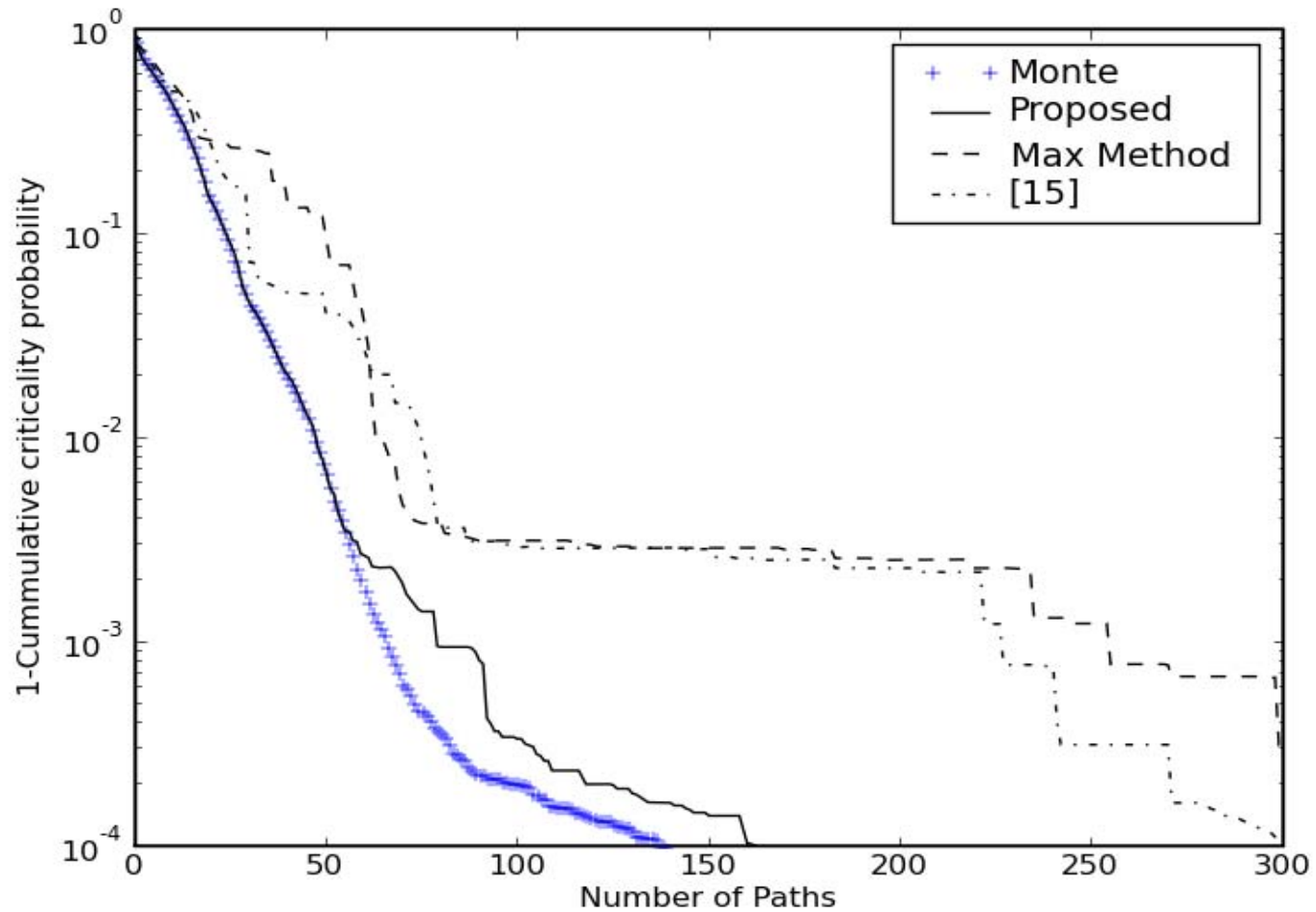
Experimental Results

- SSTA algorithm used: [Visweswariah DAC 2004]
- Refactoring is employed: [Chung et al ICCAD 2009]
 - Capture topological (structural) correlation
 - Improve the accuracy of the arrival times
- Spatial correlation model: A quad tree with 3 levels
 - 4%, 5%, and 6% variation at 1st, 2nd, and 3rd level
 - 21 global sources of variation
- 5% random independent variation

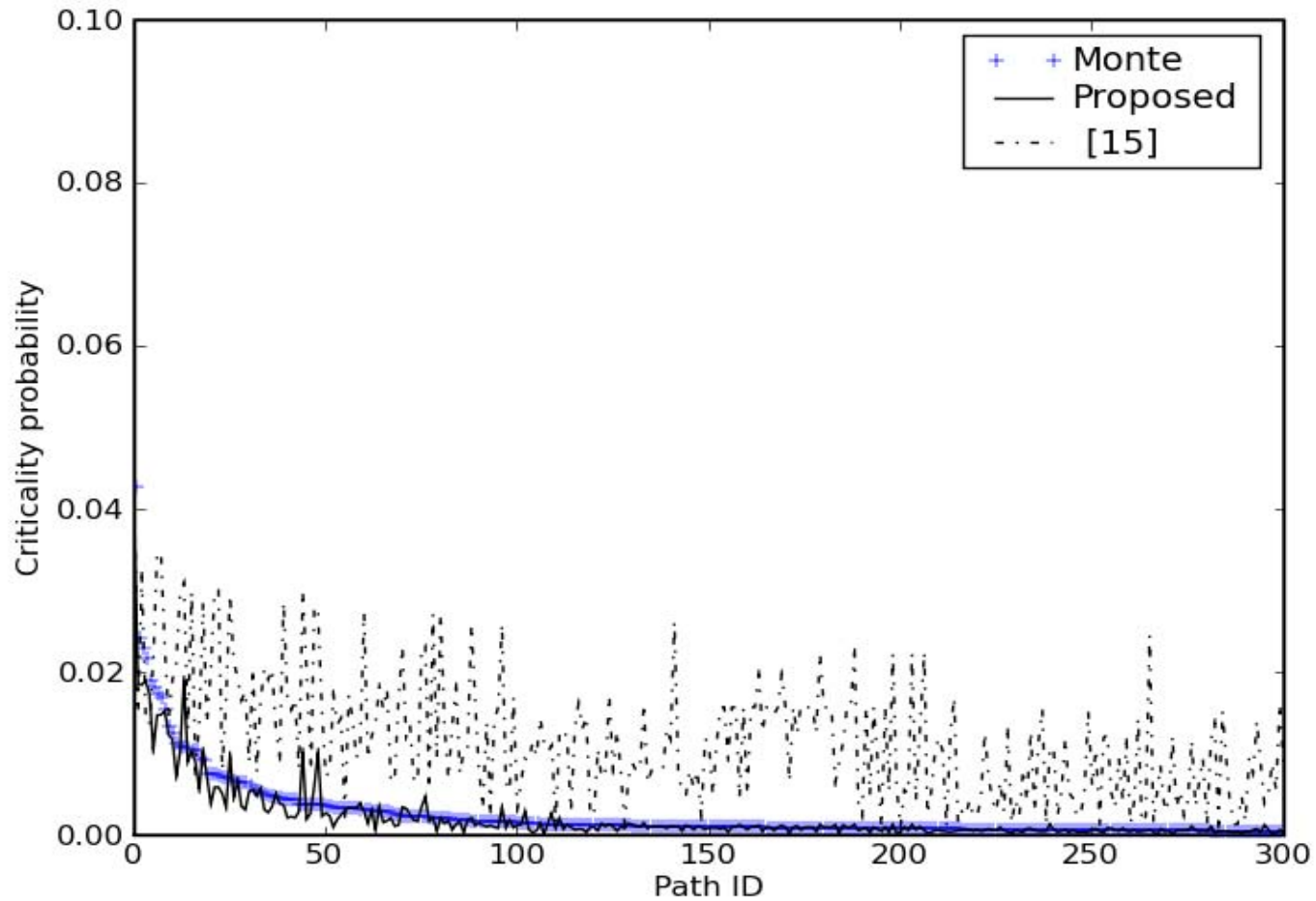
Experimental Results



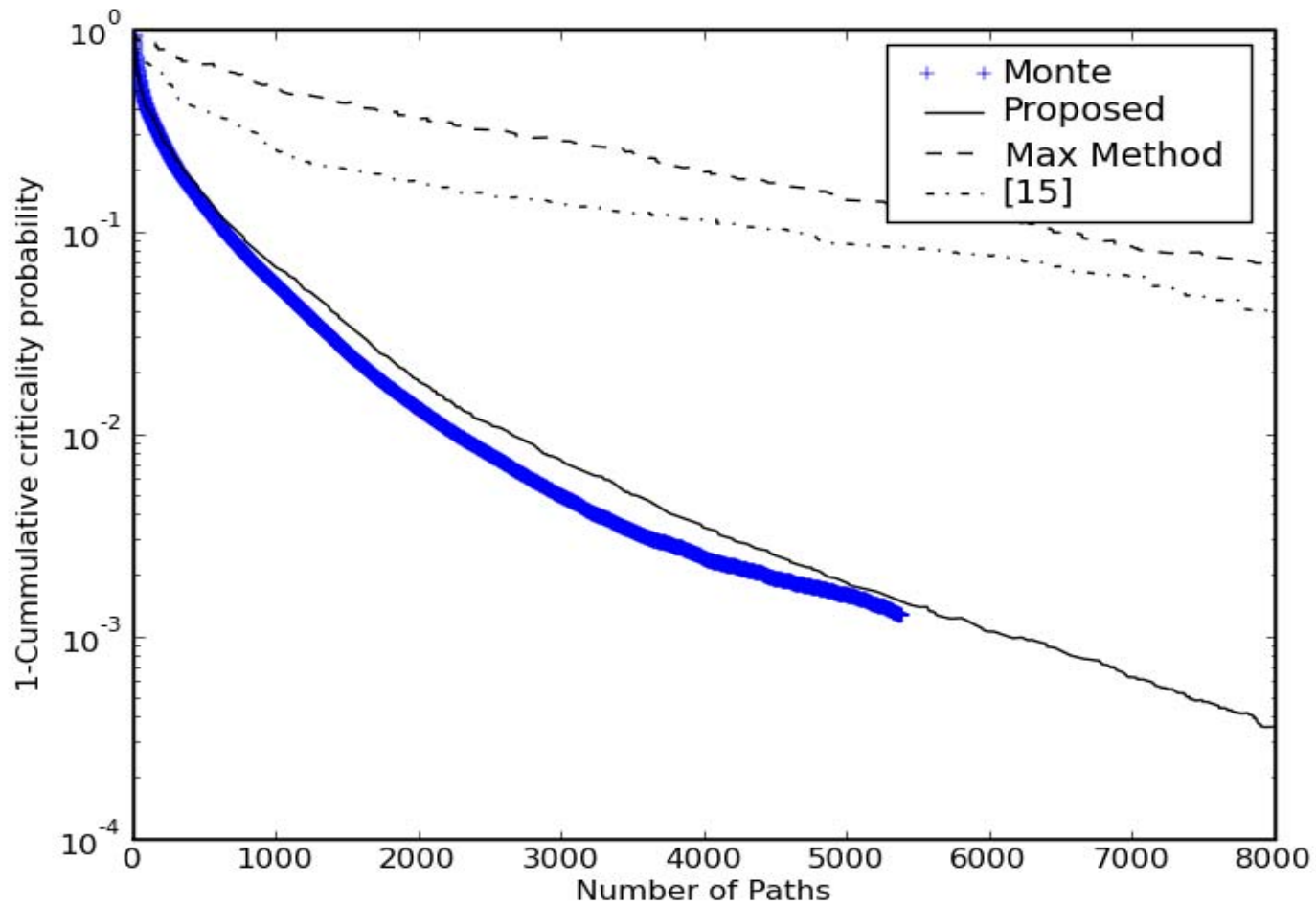
Experimental Results



Experimental Results



Experimental Results



Conclusions

- If you develop a statistical algorithm on top of SSTA, and our conditioning operation is employed to compute a certain joint probability,
 - Compared to the max operation
 - The quality of results can be improved significantly
 - The algorithm can become more stable
 - Compared to Monte Carlo sampling
 - Significant speed-up can be achieved
- This is demonstrated in path criticality computation

Conclusions

- Path criticality values are difficult to be computed accurately
- If you use the max operation, the accuracy change depending on the number of near-critical paths
- The combination of the conditioning operation and refactoring
 - allow us to compute it as accurate as Monte Carlo simulation unless your design is like c6288
 - is important when your design has many near-critical paths

Partitioning

