

Compact Nonlinear Thermal Modeling of Packaged Microprocessors



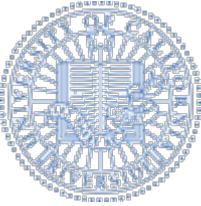
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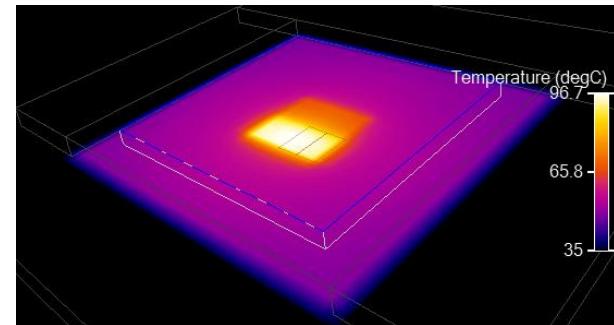
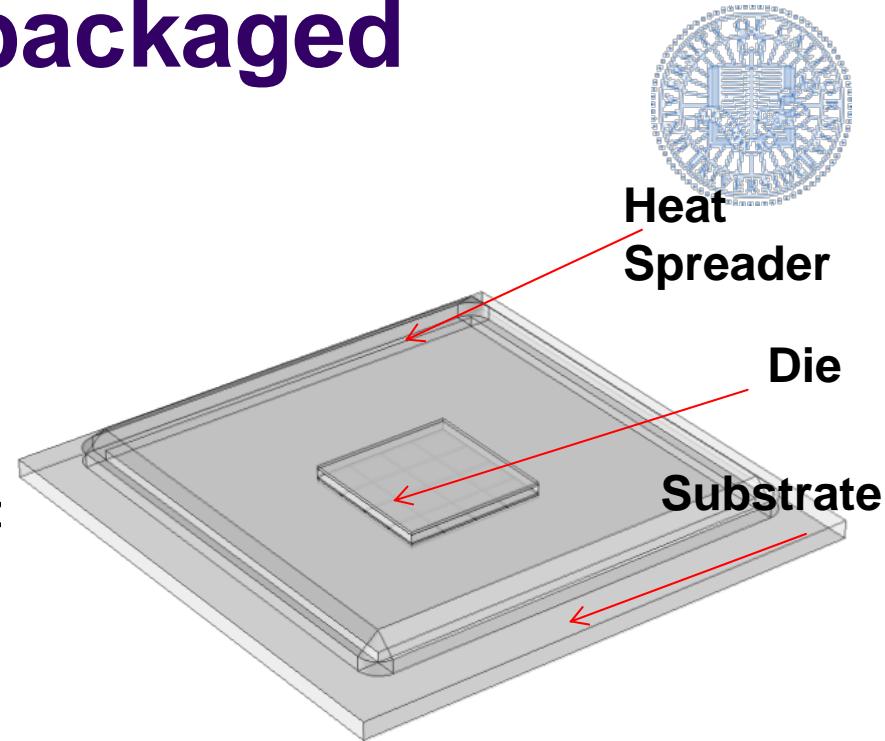


Content

- Introduction to thermal modeling
- Problem of subspace-based thermal modeling
- Proposed method
- Experimental result
- Conclusion

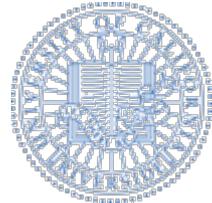
Thermal modeling of packaged microprocessor

- Temperature has become a major concern for high performance microprocessors
- Even for severe for multi/many core and emerging 3D stacked systems
 - Longer thermal paths
 - Loaded dependent hotspots
 - Large thermal gradients and dynamic thermal effect related reliability issues.
- Compact thermal model at package levels is vital for efficient thermal aware design and management.
 - Enable thermal-aware design flow
 - Enable accurate online thermal management and regulation



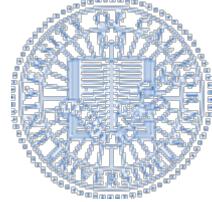
Simulated Temp distribution using Cu sink (390 W/m K)

Bottom-up thermal modeling methods



- FDM (finite difference)
- FEM (finite element) [Lasance:SEMITHERM'95, Christiaens:TCPMT'98]
 - Limitation:
 - Knowledge of detailed thermal structures is not easy to obtain
 - Impractical for large scale circuits
- HotSpot [Huang:DAC'04, Skadron:ISCA'03]
 - Mainly for architectural level design exploration
 - Limitation:
 - Accuracy losses in lumped model

Behavioral thermal modeling method

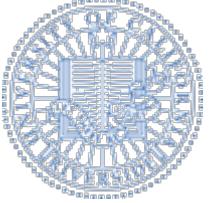


- Matrix pencil or subspace methods [Overschee:book'06] [Eguia and Tan: TVLSI'10]
 - Obtains thermal model through input/output information
 - No need for detailed thermal structures



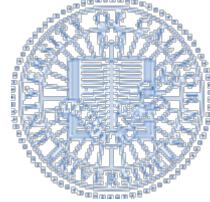
- Compact model suffers from accuracy losses due to non-linearity of the practical thermal system

Content

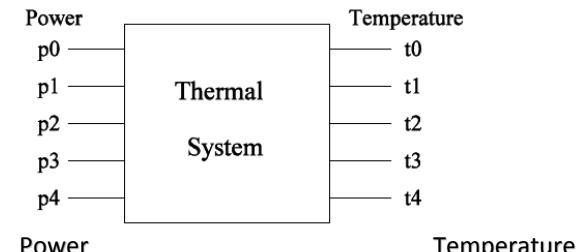
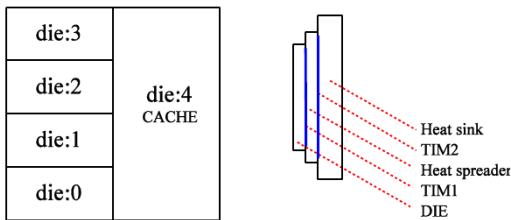


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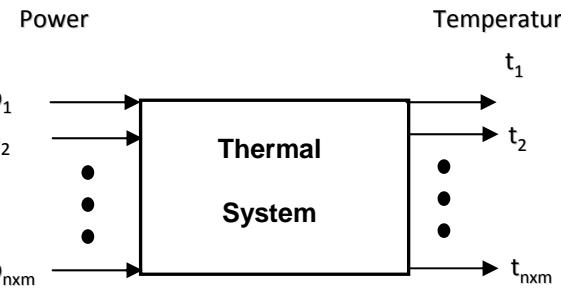
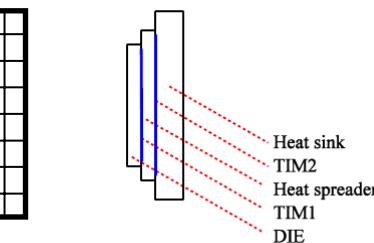
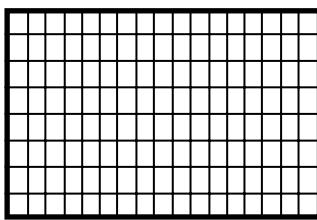
Thermal modeling for given power density under correlated power inputs



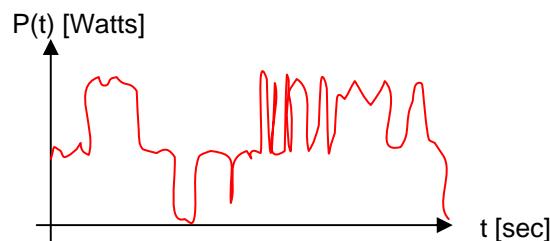
- Current:



$n \times m$ sections

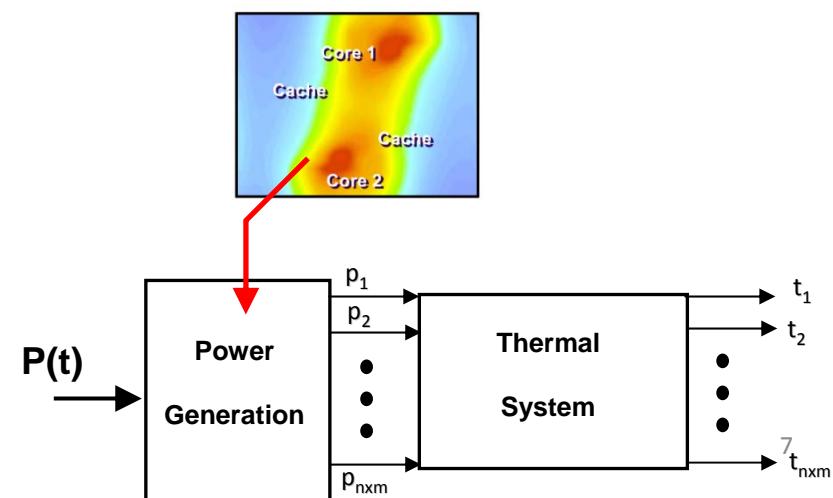


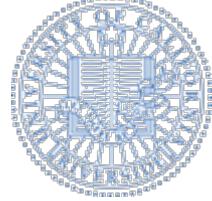
$p_1, p_2, \dots, p_{n \times m}$ generated from a power map and are highly correlated & overall processor power $P(t)$



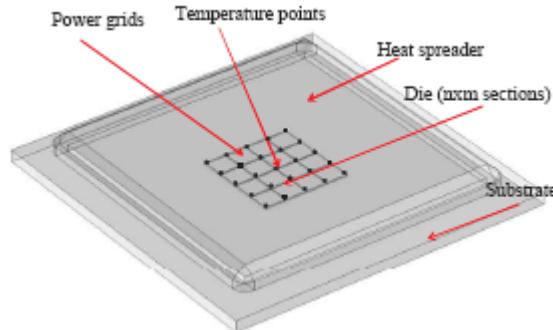
- Desired : Stand Alone Application

- Inputs: $P(t)$, Power Map, Identification method (POF or Subspace ID), $t_1, t_2, \dots, t_{n \times m}$
- Output: $H(s) \rightarrow n \times m$ transfer function matrix

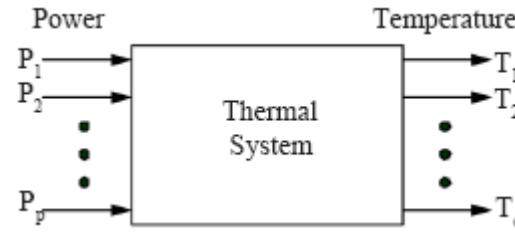
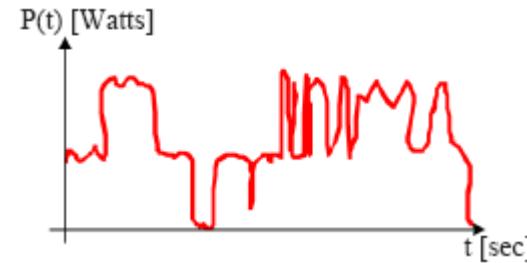




State space model of thermal system



chip partition



The abstracted model with power as input

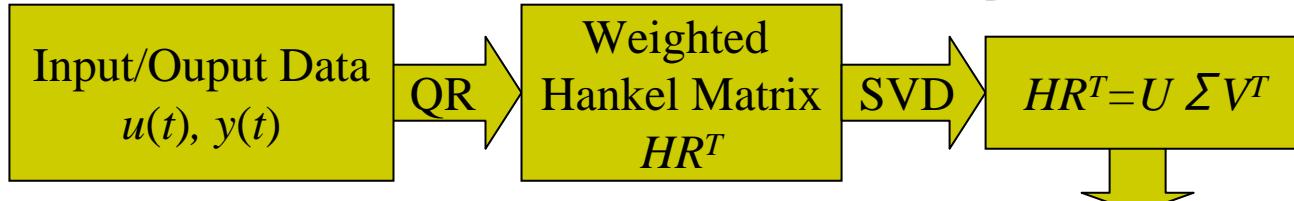
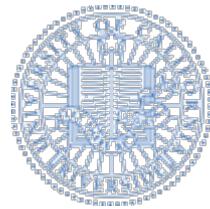
The linear model of the thermal system can be described by state space equation:

$$x(t+1) = Ax(t) + Bu(t)$$

$$y(t) = Cx(t)$$

Given input $u(t)$ and output $y(t)$, the state matrices A , B , C can be identified by subspace method.

Subspace based modeling flow



$$W = \begin{bmatrix} U_{future} & W_{past} & Y_{future} \end{bmatrix}$$

$$= [Q_1 \quad Q_2 \quad Q_3] \begin{bmatrix} R_{11} & R_{12} & R_{13} \\ 0 & R_{22} & R_{23} \\ 0 & 0 & R_{33} \end{bmatrix}$$

R_{23}^T is the weighted Hankel matrix HR^T

R_{22} is the weight matrix R

$$H(N,M) = \begin{bmatrix} h_1(N,1) & h_1(N,2) & \dots & h_1(N,N) \\ h_2(N,1) & h_2(N,2) & \dots & h_2(N,N) \\ \vdots & \vdots & \ddots & \vdots \\ h_M(N,1) & h_M(N,2) & \dots & h_M(N,N) \end{bmatrix}$$

$$= \begin{bmatrix} C \\ CA \\ \vdots \\ CA^{M-1} \end{bmatrix} \begin{bmatrix} B & SB & \dots & S^{N-1}B \end{bmatrix} = O(M)C(N)$$

$$\text{Reduced SVD}$$

$$HR^T = U_r \Sigma_r V_r^T$$

$$\text{Extended Observability /Controllability Matrix}$$

$$O(M) = U_r \Sigma_r^{1/2}$$

$$C(N) = \Sigma_r^{1/2} V_r^T (R^T)^{-1}$$

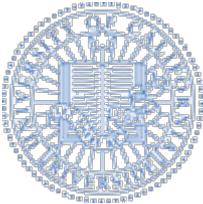
$$C = \text{first top block row of } O(M)$$

$$[F(t) \ B^u] = \text{first left block column of } C(N)$$

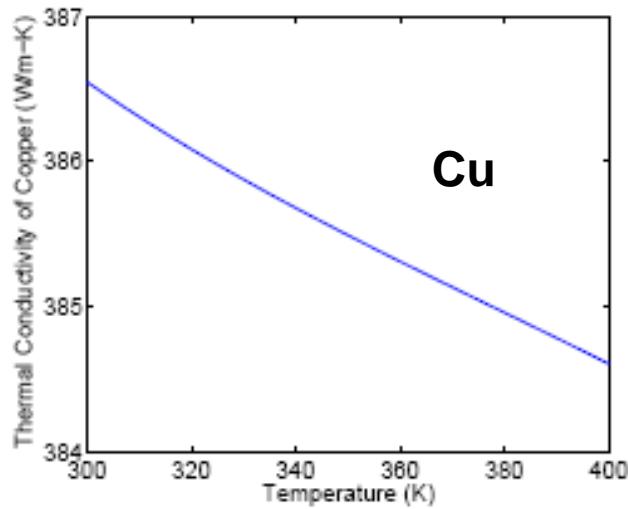
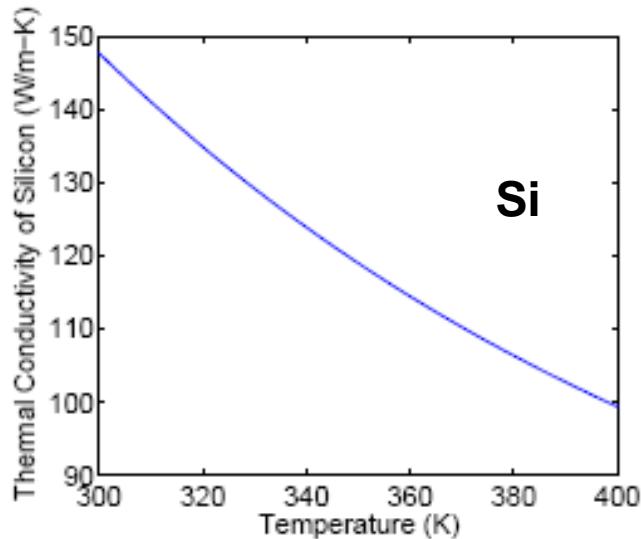
$$A = O_{\downarrow}(M)^\dagger O_{\uparrow}(M)$$

$$O_{\uparrow}(M) = \begin{bmatrix} CA \\ CA^2 \\ \vdots \\ CA^{M-1} \end{bmatrix}, \quad O_{\downarrow}(M) = \begin{bmatrix} C \\ CA \\ \vdots \\ CA^{M-2} \end{bmatrix}$$

Thermal systems are actual nonlinear!

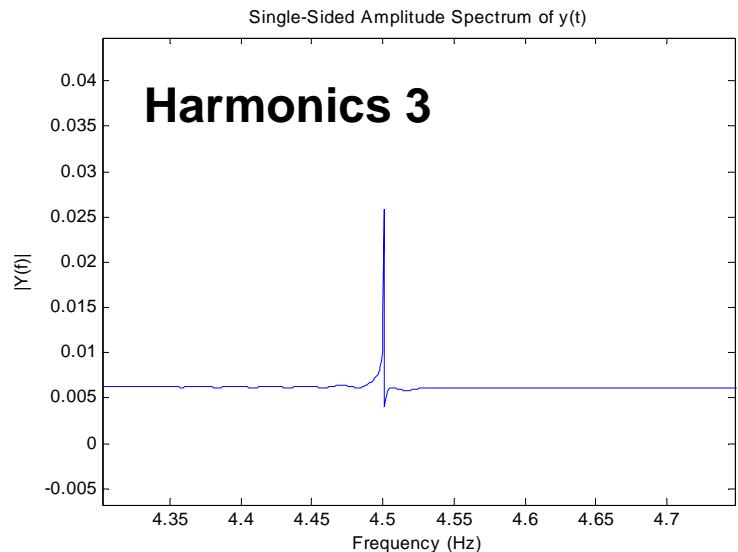
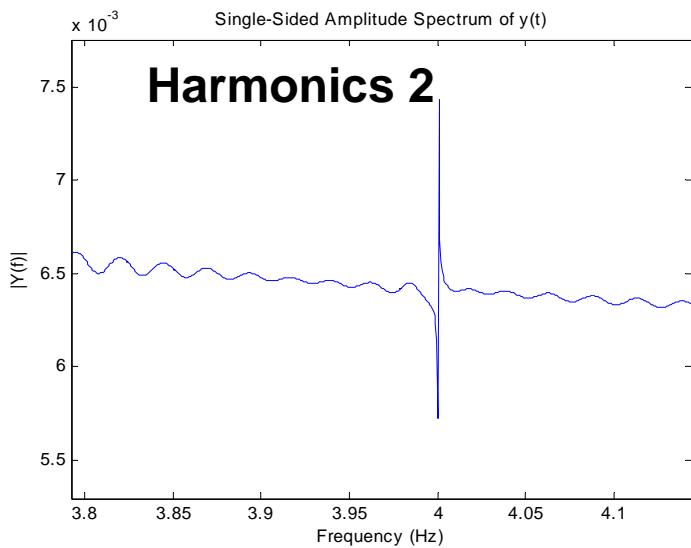
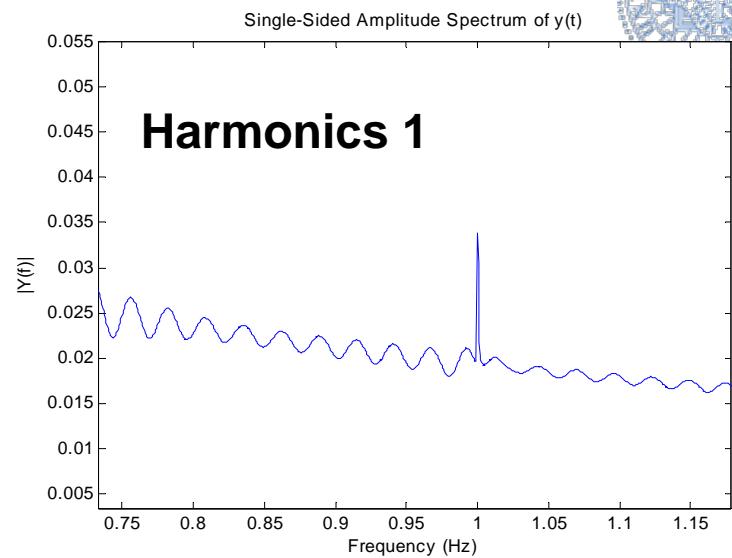
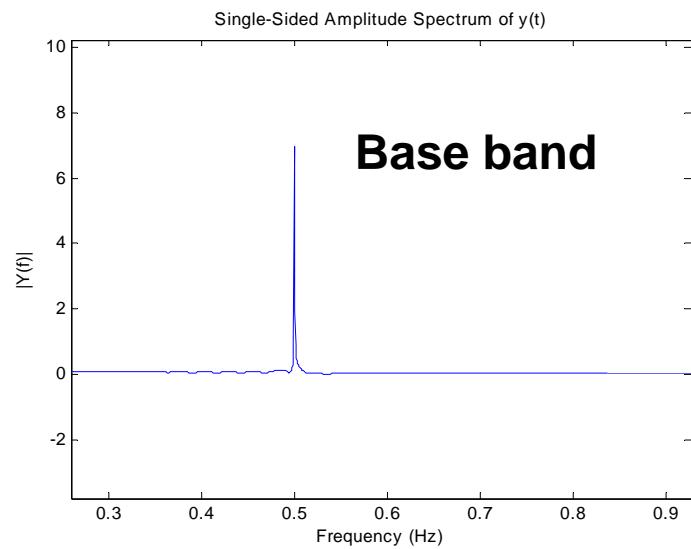
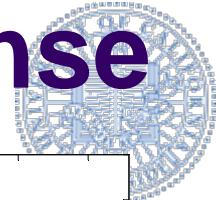


- Nonlinearity is caused by the temperature dependent properties of the package materials.



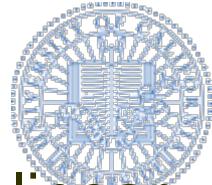
Example: Temperature dependence of thermal conductivity

Harmonics of the thermal response

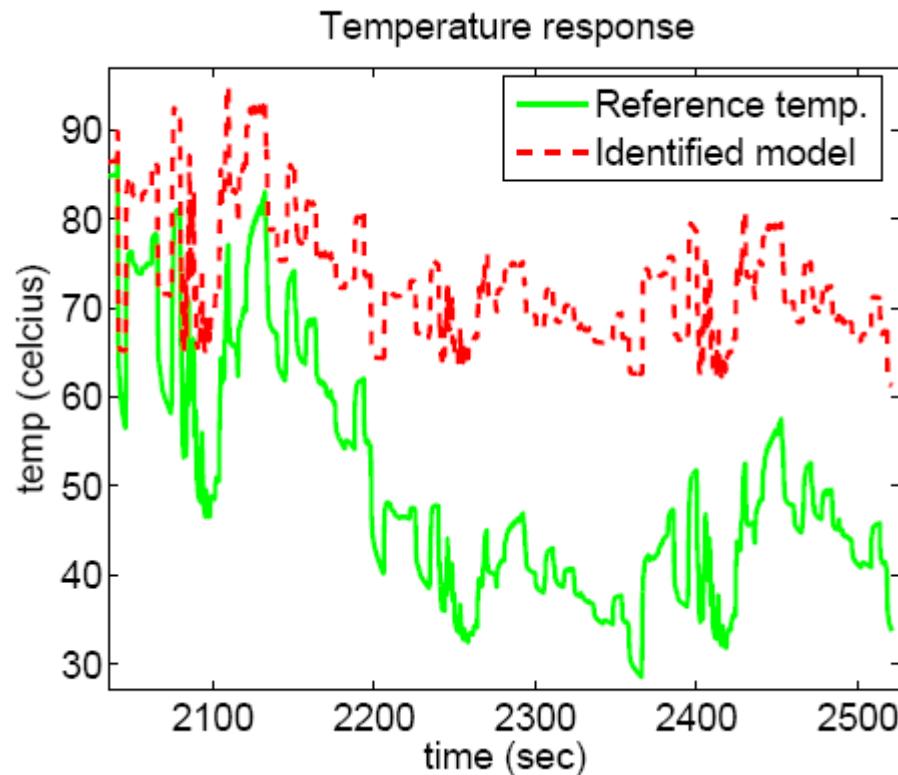


- The output frequencies (The input signal is $P_{in}=P\sin(\pi t)$, $t=0:0.1:1599.9$)

Accuracy loss of linear model

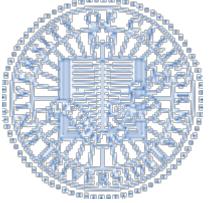


- Nonlinearity results in accuracy losses of the compact linear state space model (order=4).

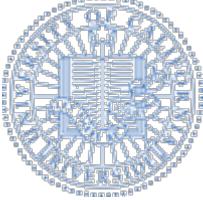


Temperature output of the identified model (linear)

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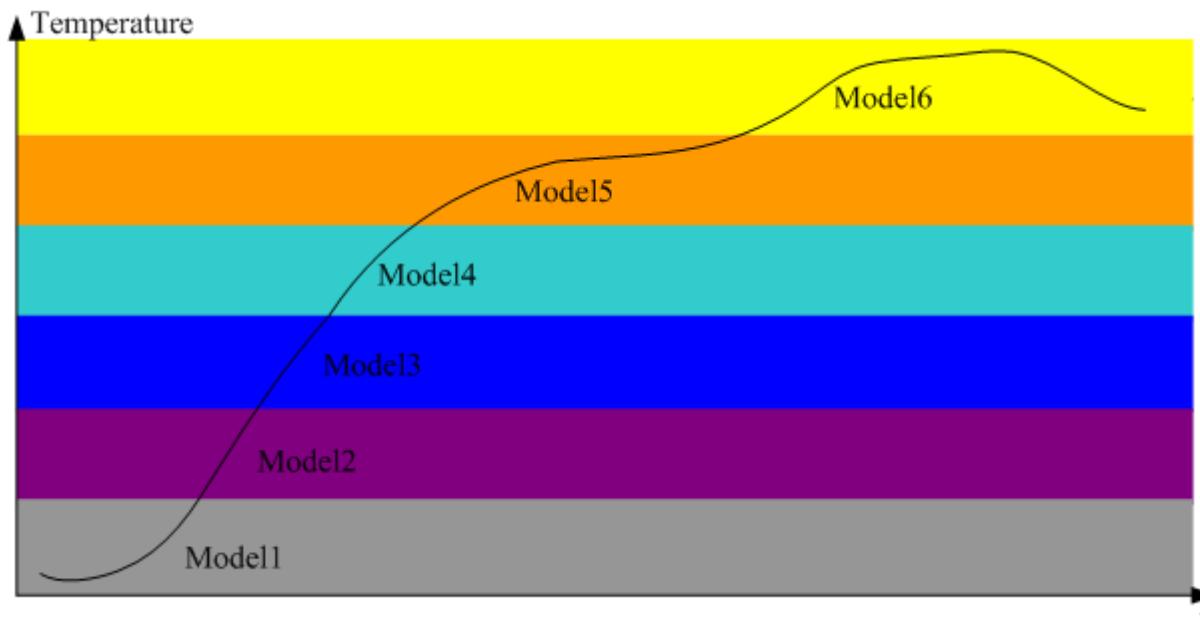


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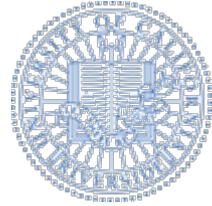


Proposed PWL modeling method

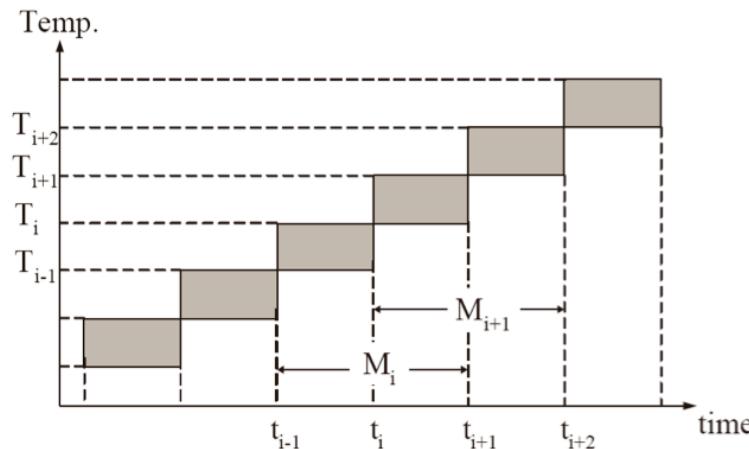
- Use piecewise linear model to approximate the thermal response of the chip for different temperature ranges



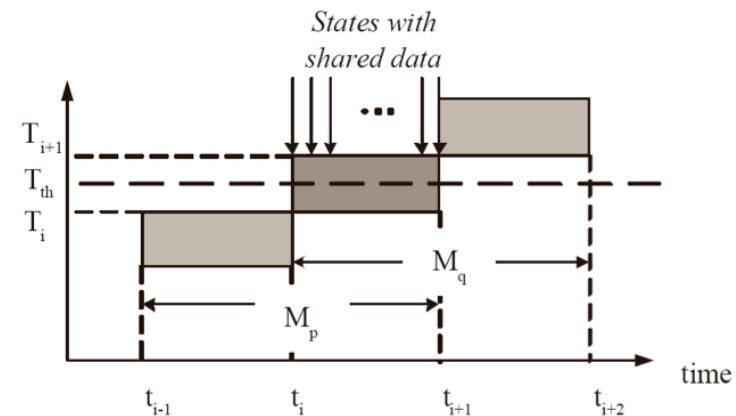
Outline of the proposed method



- Preparing training data sets for model identification in different temperature ranges
- Improved subspace method is used to identify the sub-models for each temperature range
- Linear transformation is used to build the piecewise linear model

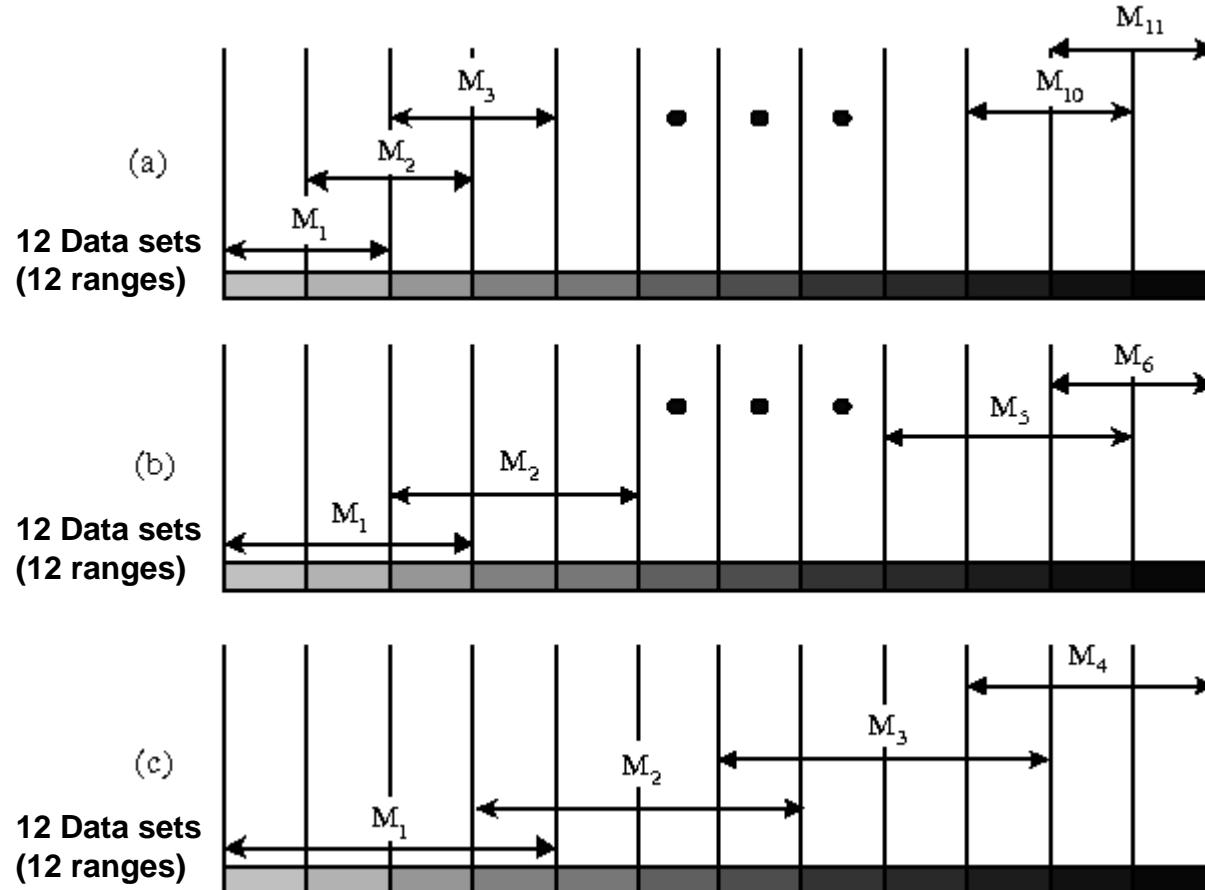
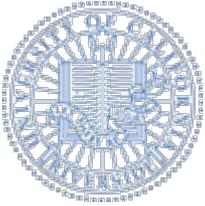


Identification of different models at different temp ranges

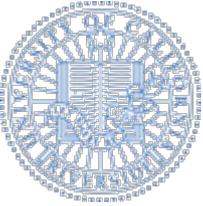


Modeling transition from M_p to M_q

Data partition for model identification

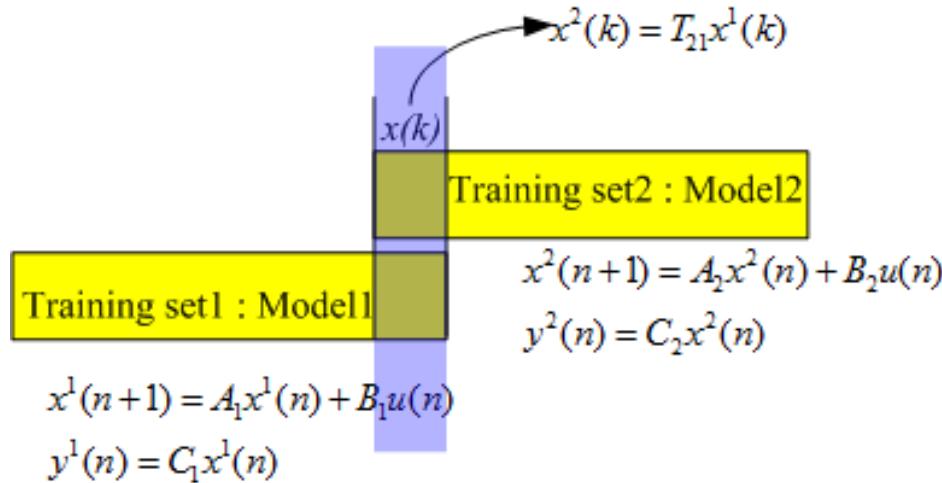


Data partition scheme to build piecewise linear model
(a) use 11 sub-models (b) use 6 sub-models (c) use 4 sub-models

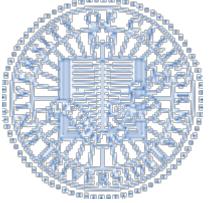


Build PWL model from sub-models

- To build PWL model, it is necessary to convert the state vectors of different sub-models to the same basis
- The identified sub-models are not on the same basis.
- At the transition region, the states in Model1 and Model2 differ by a linear transformation T_{21} : $x^2(k_1 : k_N) = T_{21}x^1(k_1 : k_N)$
- T_{21} could be determined using least square method.
- $x^2(k) = T_{21}x^1(k)$ transforms Model2 to the basis of Model1

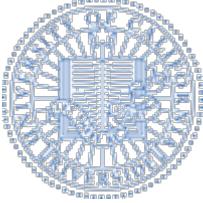


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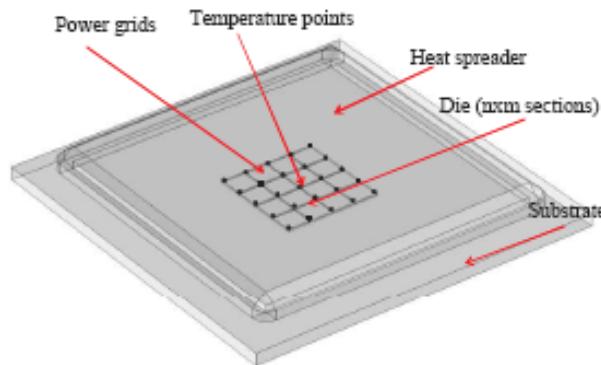


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Experimental setup

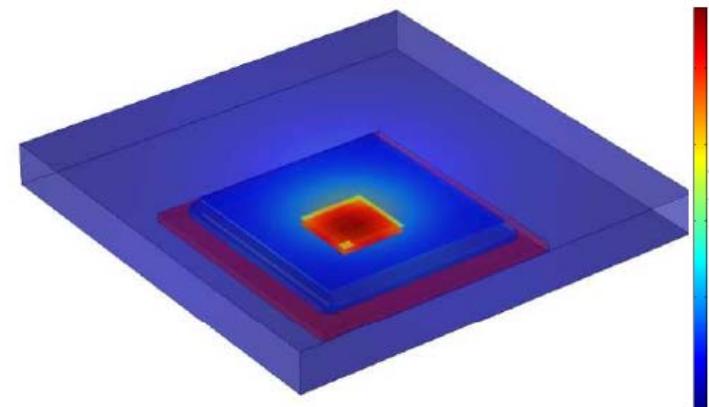


- Treat the meshed thermal chip package as a 16-input (power) and 25-output (temperature) system.



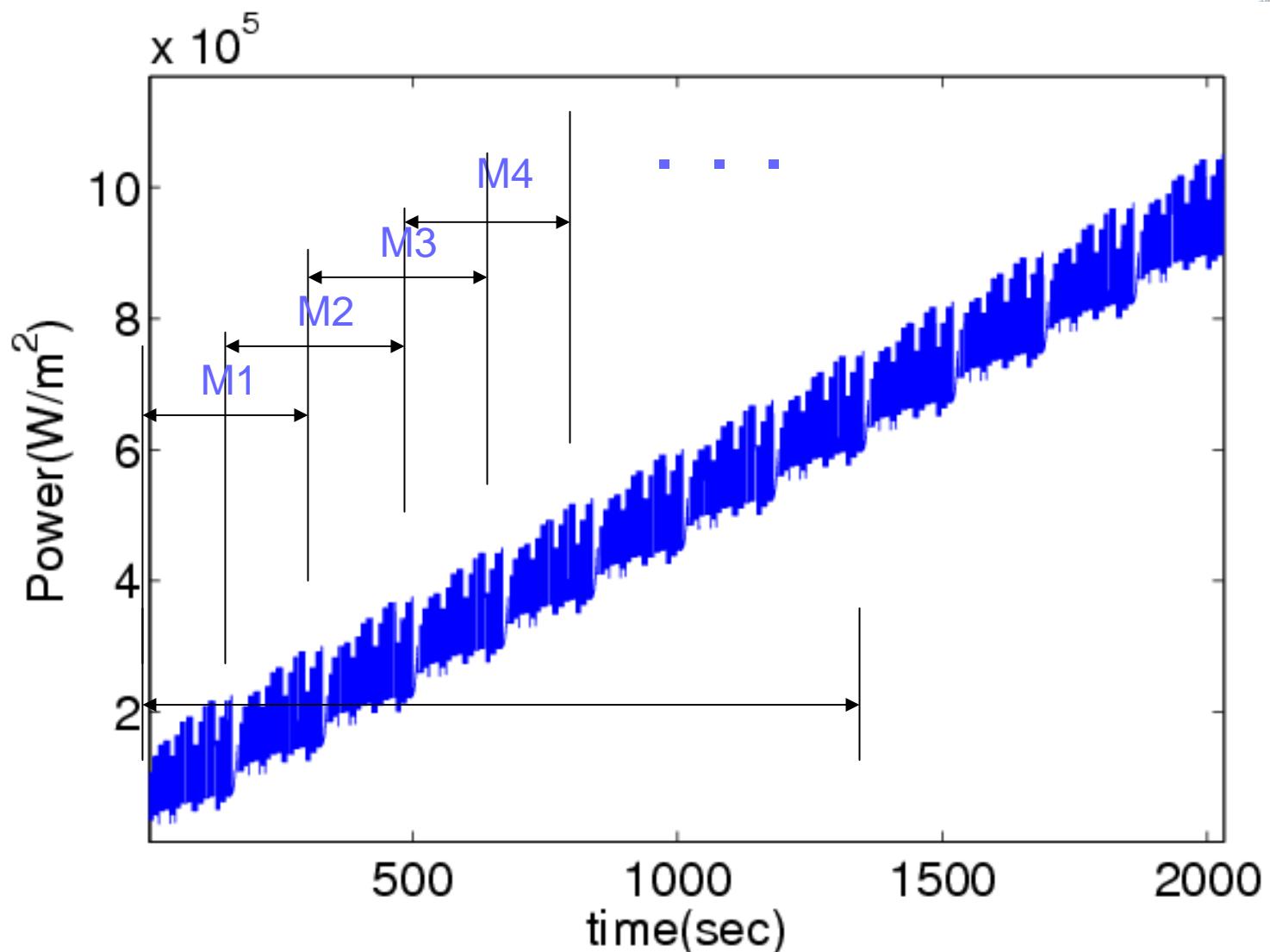
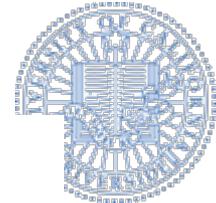
Chip partition

- Use COMSOL to simulate its transient temperature response to obtain the temperature data for piecewise linear system identification
- Full simulation time steps: 20412



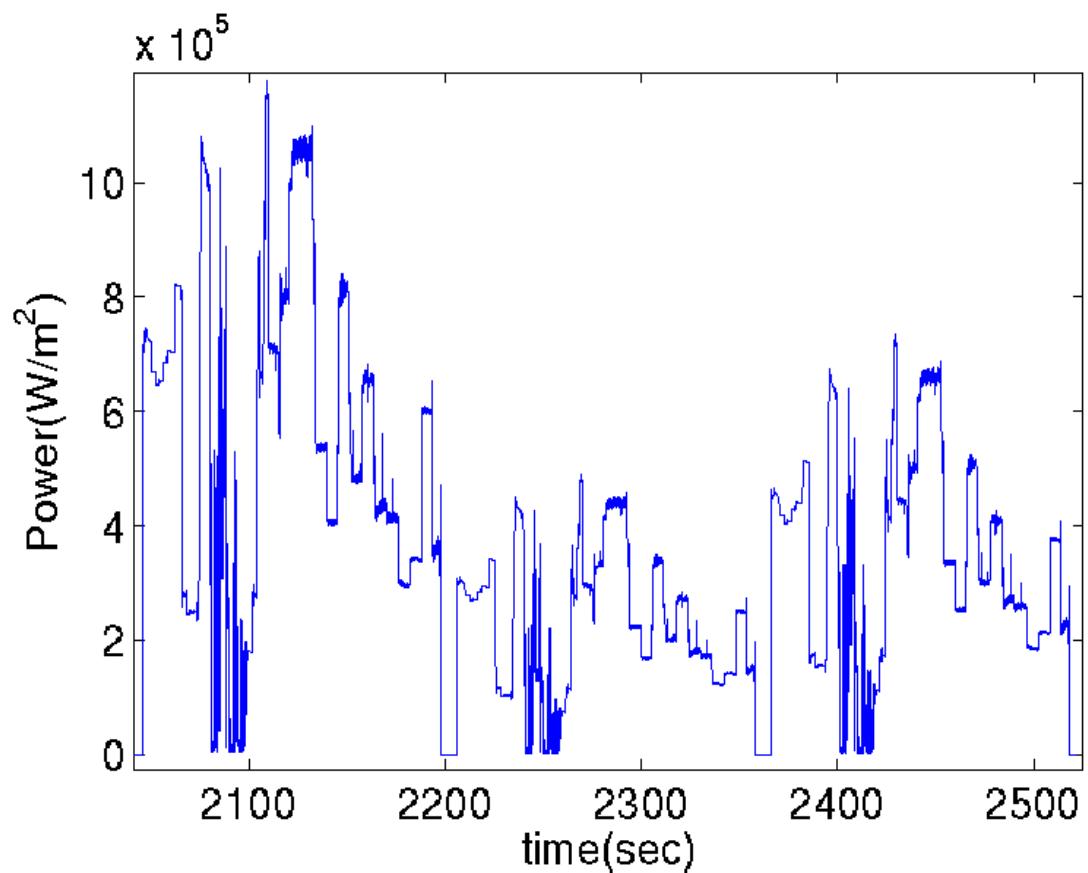
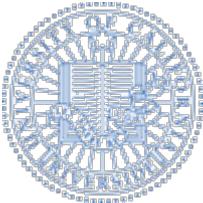
Steady state temperature distribution

Input power waveform (I)

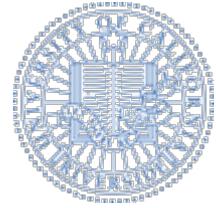


Input waveform used for model identification
(PRBS signals with stairs-like envelop)

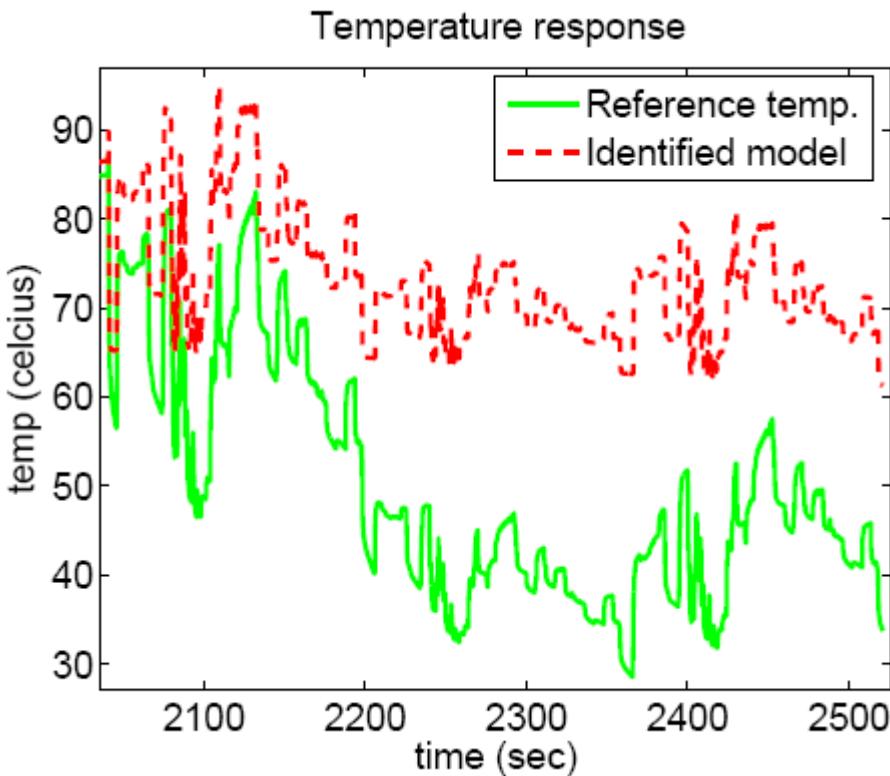
Input power waveform (II)



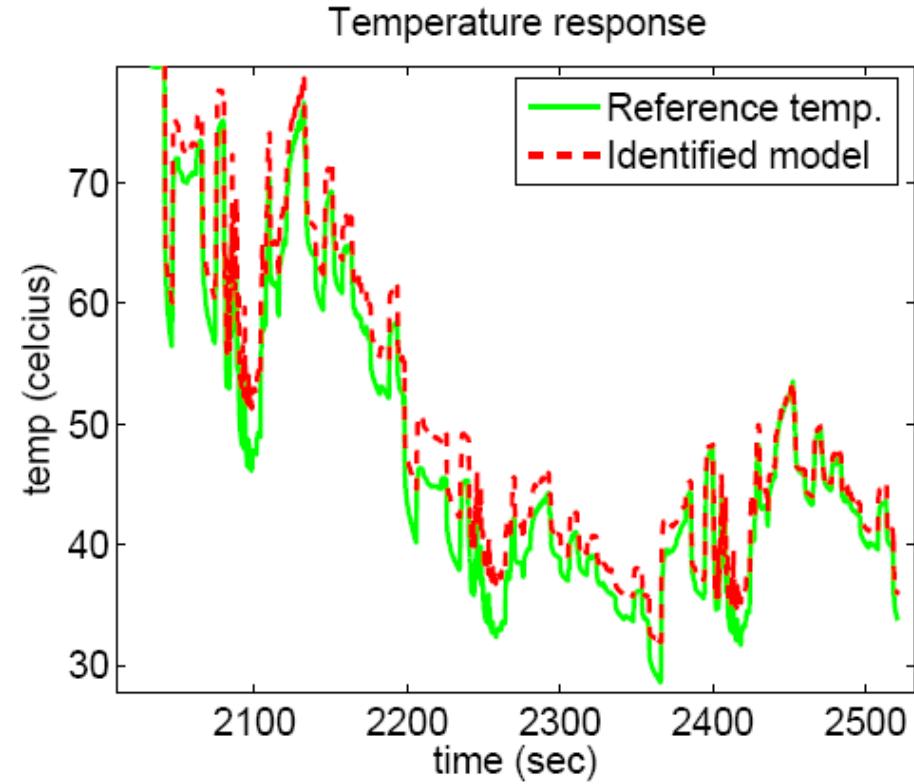
Input waveform used for model validation (Intel's signal)



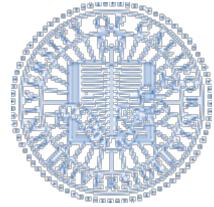
Transient response of 16-input and 25 output system at section(1,1)



Use 1 linear model:
Order = 4

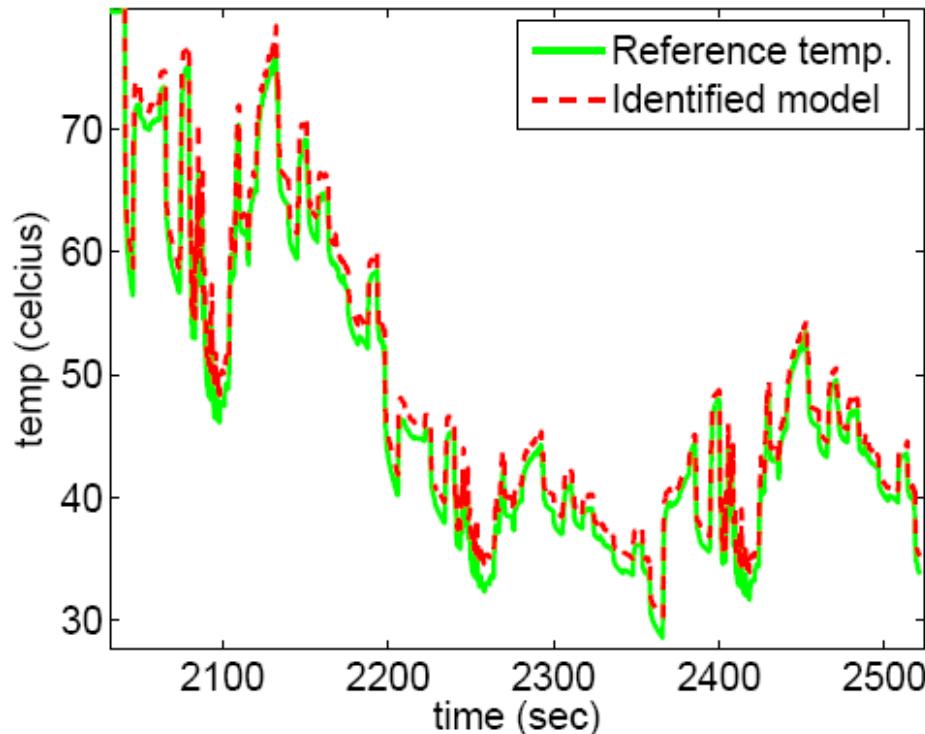


Use piecewise linear model:
Number of sub-model used: 4
Order =4

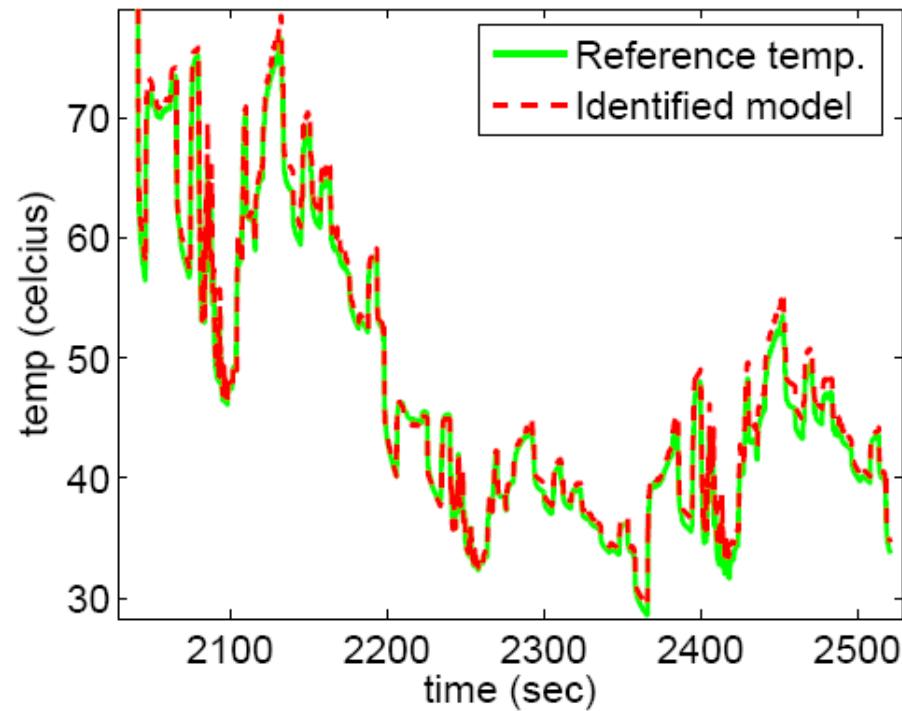


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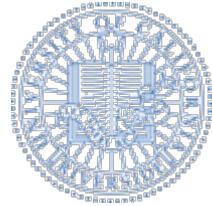
Temperured response



Temperature response



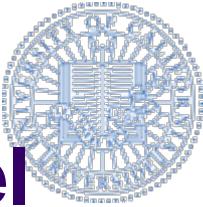
Summary of errors of 16-temperature output of the piecewise linear models



Error with PWL models (order:4)

Num. of linear models in use	11	6	4
Maximum of mean errors	2.1%	3.9%	5.9%

Mean errors are calculated during the entire transient simulation

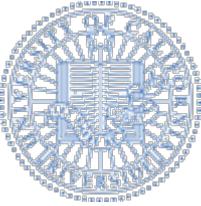


Performance comparison with linear model

Comparison items	Error	Identification time	Simulation time
PLM(order:4)	2.1%	63.8 sec	7.88 sec
LM (order:15)	2.3%	627.1 sec	22.2 sec

PLM – Piecewise linear model

LM – Linear model



Conclusion

- Piecewise linear model scheme has been proposed to consider nonlinear effects in thermal systems.
- Linear sub-models are identified for different temperature ranges using subspace identification method.
- A linear transformation method has been proposed to build piecewise linear model.
- Our experiment results show that Piecewise linear model is more efficient for fast thermal modeling and simulation of packaged microprocessor.