

# GPGPU ACCELERATED SIMULATION AND PARAMETER TUNING FOR NEUROMORPHIC APPLICATIONS

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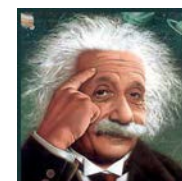
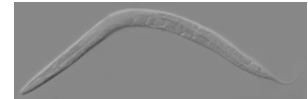
**Kris Carlson, Michael Beyeler,  
Nikil Dutt, Jeff Krichmar**

Department of Cognitive Sciences  
Department of Computer Science  
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# Brains by the Numbers

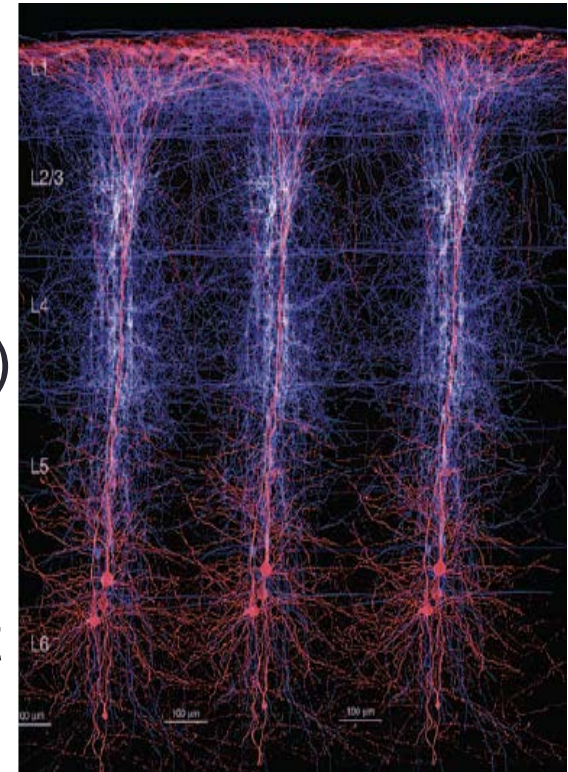
Species	Neurons	Synapses
Nematode	302	$10^3$
Fruit Fly	100,000	$10^7$
Honeybee	960,000	$10^9$
Mouse	75,000,000	$10^{11}$
Cat	1,000,000,000	$10^{13}$
Human	85,000,000,000	$10^{15}$



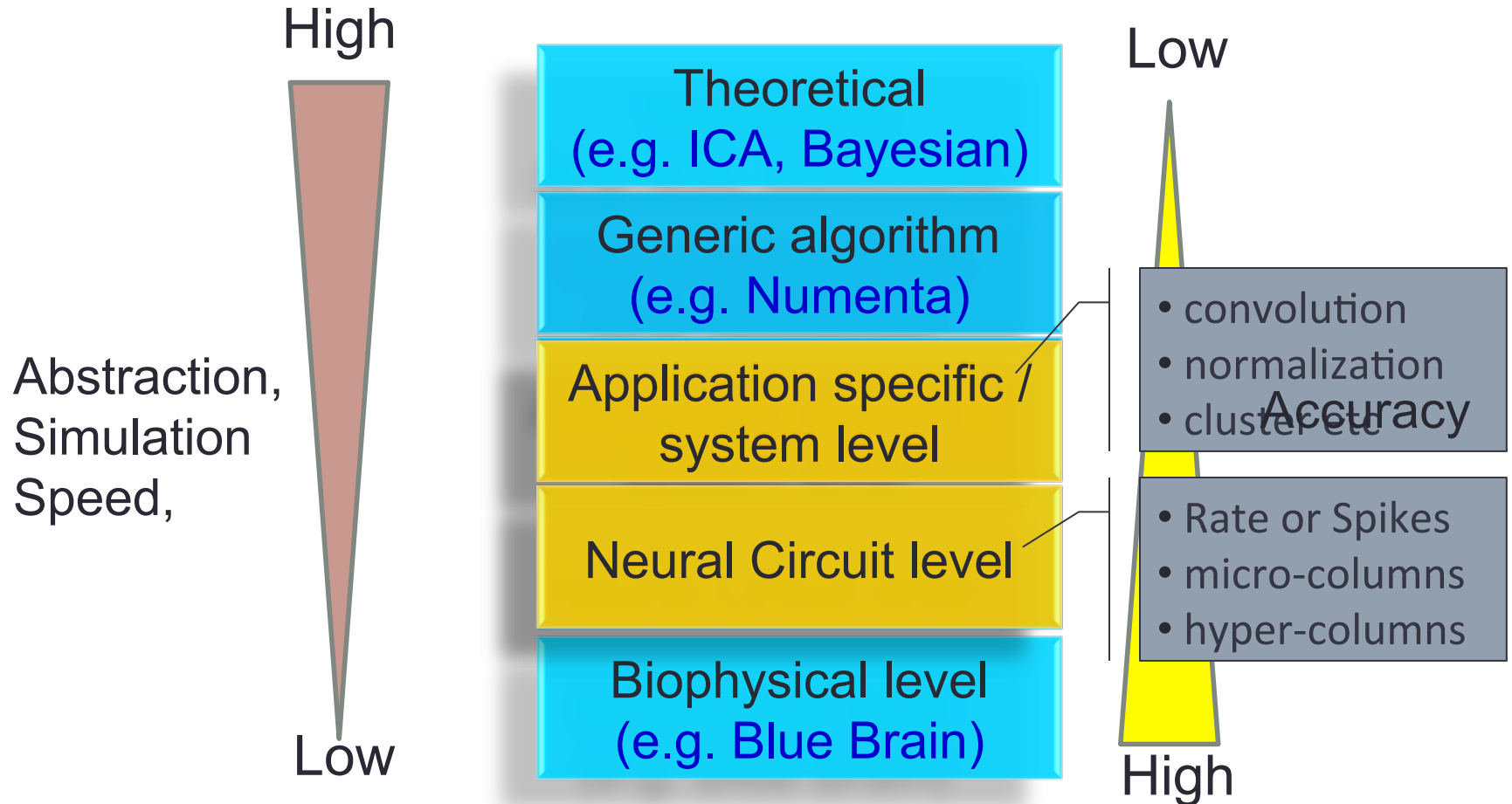
Source – [http://en.wikipedia.org/wiki/List\\_of\\_animals\\_by\\_number\\_of\\_neurons](http://en.wikipedia.org/wiki/List_of_animals_by_number_of_neurons)

# Brain Computations

- Massive parallelism ( $10^{11}$  neurons)
- Massive connectivity ( $10^{15}$  synapses)
- Excellent power-efficiency
  - $\sim 20$  W for  $10^{16}$  flops
- Low-performance components ( $\sim 100$  Hz)
- Low-speed comm. ( $\sim$ meters/sec)
- Low-precision synaptic connections
- Probabilistic responses and fault-tolerant
- Autonomous learning



# Hierarchy of Brain Model Abstractions



# Outline

- **What are SNNs?**
- **Neuromorphic Hardware and Simulation Tools**
- **CARLSim SNN Simulator and Applications**
- **Parameter Tuning of Large-Scale SNNs**

# Spiking Neural Networks (SNNs)

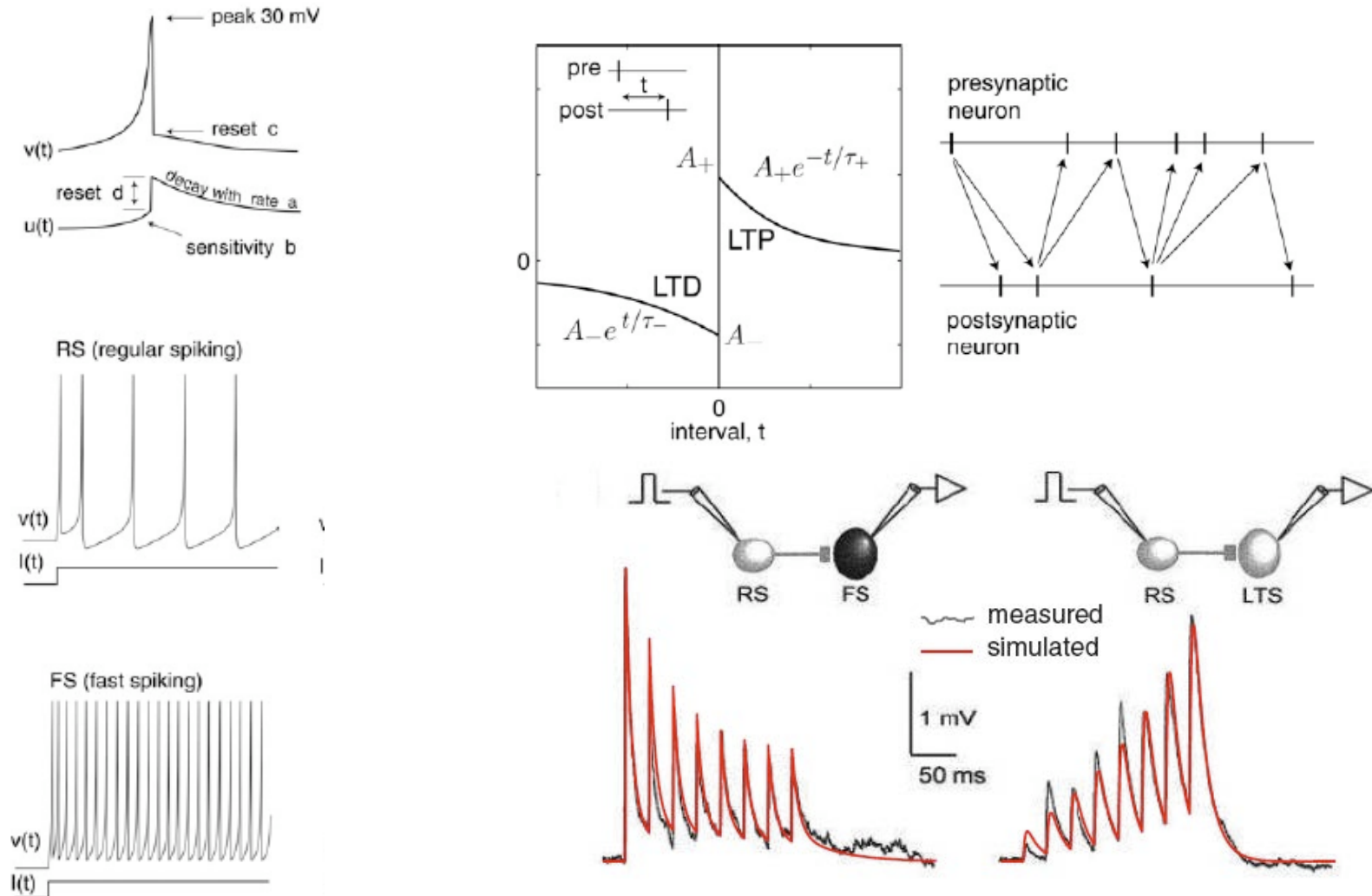
- **What are SNNs?**

- Neural Networks that model neuronal/synaptic temporal dynamics
- Spike only when the membrane voltage exceeds a threshold

- **Why use SNNs?**

- Speed of processing hypothesis
  - processing with a wave of spikes
- Spikes are rare: average brain activity  $< 1\text{Hz}$ 
  - “rates” are not energy efficient
- SNNs use temporal coding but can still use rate coding
- Event-driven nature of SNNs fits well with neuromorphic hardware
  - Use “**Address Event Representation**” (AER) to minimize communication
- SNNs model important unsupervised learning algorithm: Spike Timing-Dependent Plasticity (STDP)
  - Precise spike firing has been found at almost all levels of the mammalian visual pathway
  - The exact timing of spike changes plasticity

# Modeling Components at the Neural Circuit Level



Many Parameters!

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# Neuromorphic Hardware Devices

Hardware Project: Hardware Group	Hardware Description	Neuron Models	Synaptic Plasticity	Max Neurons	Max Synapses
<b>SpiNNaker:</b> Industry and UK universities	<ul style="list-style-type: none"> <li>- Completely digital</li> <li>- Consists of array of nodes</li> <li>- Each node has 18 ARM9 cores</li> <li>- Final goal: 1,036,800 cores</li> </ul>	Spiking: Izhikevich and non- spiking	Yes: STDP	1,000 neurons per ARM9 core*	10k synapses per ARM9 core*
<b>Neurogrid:</b> Stanford University	<ul style="list-style-type: none"> <li>- Analog/digital hybrid</li> <li>- Full board has 16 neurochips</li> <li>- Operates on only 5 W</li> </ul>	Spiking: Two- compartment neurons	No	65,536 neurons per neurochip	375M synapses per neurochip
<b>True North</b> Cog. Architecture: IBM SyNAPSE Team	<ul style="list-style-type: none"> <li>- Completely digital</li> <li>- Consists of hierarchical design</li> <li>- Neurosynaptic core is basic building block</li> </ul>	Spiking: many behaviors including LIF	No	256 neurons per neuro- synaptic core	256K binary synapses per neuro- synaptic core
<b>HRL neural chip:</b> HRL Labs, LLC SyNAPSE Team	<ul style="list-style-type: none"> <li>- Analog/digital hybrid</li> <li>- Synaptic weights stored in memristors</li> </ul>	Spiking: Izhikevich	Yes: STDP	576 neurons per chip	70k virtual synapses per chip
<b>HiCANN:</b> BrainScaleS Team	<ul style="list-style-type: none"> <li>- Analog/digital hybrid</li> <li>- Each wafer has 384 chips</li> <li>- Neurons are analog</li> <li>- Synapses are digital</li> </ul>	Spiking: AdExp and I&F	Yes: STDP	512 neurons per chip*	16k synapses per chip*

\* Indicates the max. number of neurons are synapses are not independent

# Neuromorphic Software Tools: SNN Simulators

Software Project	Features	Parallelized Implementations	Implementation Language	Parameter Tuning Tools
<b>NENGO</b>	<ul style="list-style-type: none"> <li>- Uses neural engineering framework (NEF)</li> <li>- Set weights to perform specific computations</li> <li>- Uses both rate-based and spiking neurons</li> <li>- Uses neural plasticity rules (STDP) as well</li> </ul>	None	<ul style="list-style-type: none"> <li>- Core: Java</li> <li>- Python scripting</li> </ul>	NEF
<b>NEST</b>	<ul style="list-style-type: none"> <li>- Mature codebase for multiple platforms</li> <li>- Includes many neuron and plasticity models</li> <li>- Built-in simulation language interpreter</li> <li>- Module for creating complex networks</li> </ul>	Parallelized MPI CPU implementation	<ul style="list-style-type: none"> <li>- Core: C++</li> <li>- Interface: Python</li> <li>- PyNN support</li> </ul>	None
<b>Brian</b>	<ul style="list-style-type: none"> <li>- Multiple integration methods</li> <li>- Multiple neuron and plasticity models</li> <li>- Uses Python plotting packages</li> <li>- Good documentation</li> </ul>	Parallelized CPU support Parallelized GPU support only for tuning component	<ul style="list-style-type: none"> <li>- Core: Python</li> <li>- PyNN support</li> </ul>	Support for tuning neuron models
<b>CARLsim</b>	<ul style="list-style-type: none"> <li>- Fast and efficient CUDA GPU implementation</li> <li>- Support for key ion channels</li> <li>- GPU parallelized general tuning framework</li> <li>- Includes highly optimized CUDA vision frontend</li> </ul>	Parallelized CUDA GPU implementation	<ul style="list-style-type: none"> <li>- Core: C++ and CUDA</li> <li>- Syntax similar to PyNN</li> </ul>	General tuning framework using EAs

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# CARLsim

frontiers in  
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**ORIGINAL RESEARCH ARTICLE**

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## An efficient simulation environment for modeling large-scale cortical processing

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We have developed a spiking neural network simulator, which is both easy to use and computationally efficient, for the generation of large-scale computational neuroscience models. The simulator implements current or conductance based Izhikevich neuron networks, having spike-timing dependent plasticity and short-term plasticity. It uses a standard network construction interface. The simulator allows for execution on either GPUs or CPUs. The simulator, which is written in C/C++, allows for both fine grain and coarse grain specificity of a host of parameters. We demonstrate the ease of use and computational efficiency of this model by implementing a large-scale model of cortical areas V1, V4, and area MT. The complete model, which has 138,240 neurons and approximately 30 million synapses, runs in real-time on an off-the-shelf GPU. The simulator source code, as well as the source code for the cortical model examples is publicly available.

**Keywords:** visual cortex, spiking neurons, STDP, short-term plasticity, simulation, computational neuroscience, software, GPU

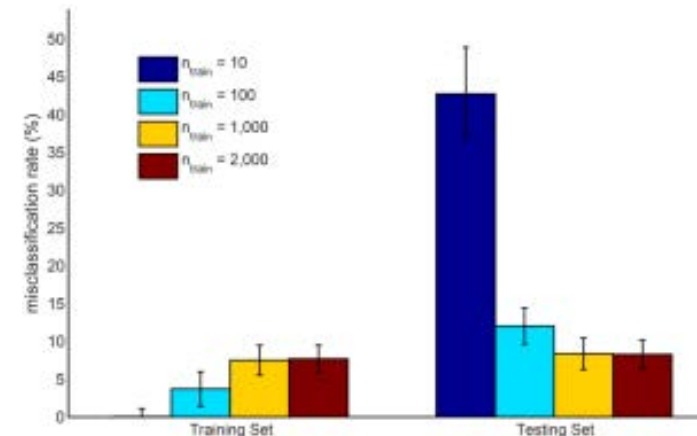
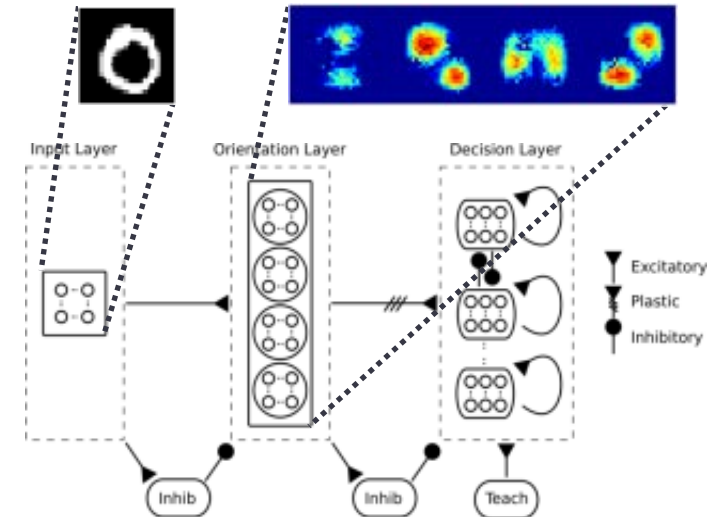
Code available at: <http://www.socsci.uci.edu/~jkrichma/CARLsim>

# CARLsim Applications

- Used to create large-scale simulations of cognitive processes
  - 10k – 100K neurons with millions of synapses
- Sample Applications
  - Visual Processing
    - Large-scale model of cortical areas V1, V4, and area MT [*Richert et al. 2011*]
  - Neuromodulation
    - Top-down and bottom-up attention [*Avery et al. 2013a*]
    - Working memory and behavior [*Avery et al. 2013b*]
  - Object Categorization
    - Classifying handwritten digits [*Beyeler et al. 2013*]
  - Neural Plasticity
    - Biologically plausible STDP and Homeostasis [*Carlson et al. 2013*]

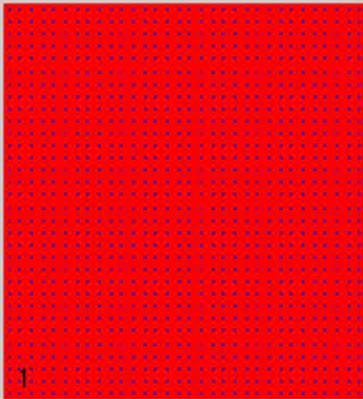
# CARLsim Example: MNIST Classification

- MNIST database of handwritten digits
  - 60,000 training / 10,000 test patterns
- Neurofidelity
  - Network: spiking neurons, ion channels
  - Training: Calcium-based learning rule (STDP-like)
  - Classification: decision-making (drift-diffusion / race model)
- Accuracy
  - 92 % correct classifications
  - Biologically plausible reaction times
- Efficiency
  - 71,026 neurons, ~133 million synapses
  - Real-time processing on a single NVIDIA Tesla M2090
- Scalability
  - Modular approach
  - Extend to more general neuromorphic implementation





# CARLsim Example: Vision Processing System



- Implemented motion selectivity in spiking model of Area MT
- 32x32 Resolution, 138,240 neurons; ~30 million synapses (shown on the left)
  - Running in real-time on single GPU card.
- Higher resolution, ~550K neurons; ~120M synapses (shown below)





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- What are SNNs?
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- **Parameter Tuning of Large-Scale SNNs**

# Parameter Tuning of Neurobiologically Inspired Networks: Time Consuming!

- **Example 1\***: Tuning a small, lobster pyloric circuit:
  - Tuned 3-neuron, 5 synapse circuit
  - Database of 20M configurations was generated, with only 20% functional
- **Example 2<sup>†</sup>**: Tuning small SNN:
  - 5 parameters with 10 values, each needs  $10^5$  simulations
  - Simulation Time: ~15 days for 1K network with 5 parameters
- **Lesson:**
  - Even for small networks, search space is extremely large with many solutions!
- **Biology provides some constraints, *BUT***
  - designer must choose many parameter values *manually* to achieve appropriate neuronal dynamics.
- ***Our Solution: Automated Parameter Tuning using GPUs and EAs***

\* From Prinz, A.A., Bucher, D., and Marder, E. (2004). Similar network activity from disparate circuit parameters. Nat Neurosci 7, 1345-1352

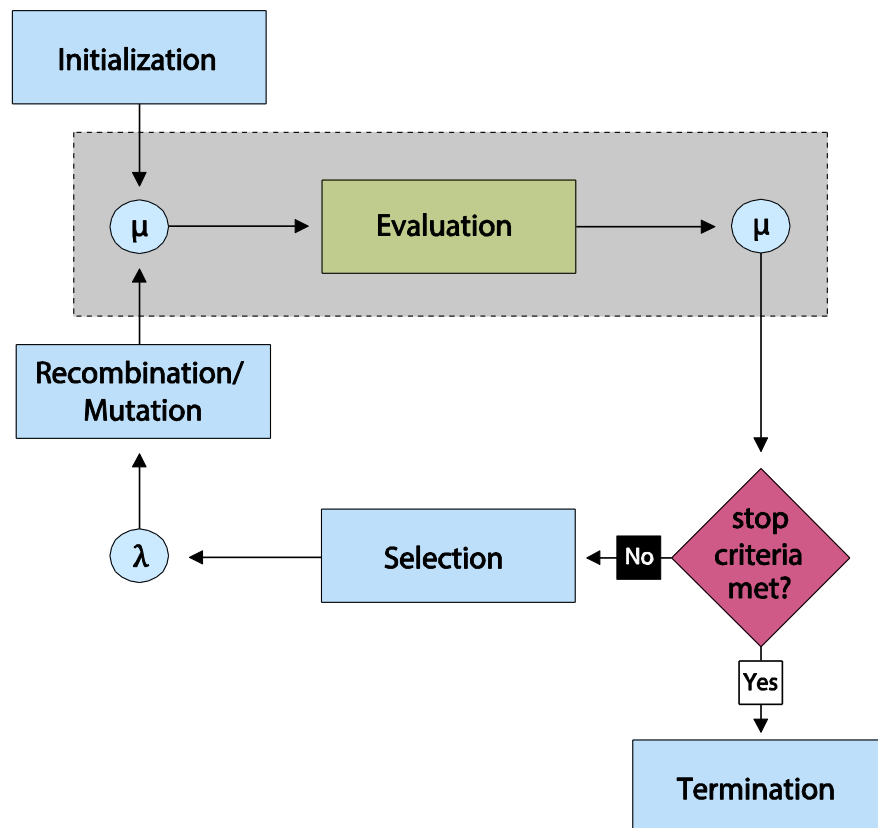
† From Jayram Moorkanikara's PhD Dissertation at UCI, 2010

# Automated Parameter Tuning Framework

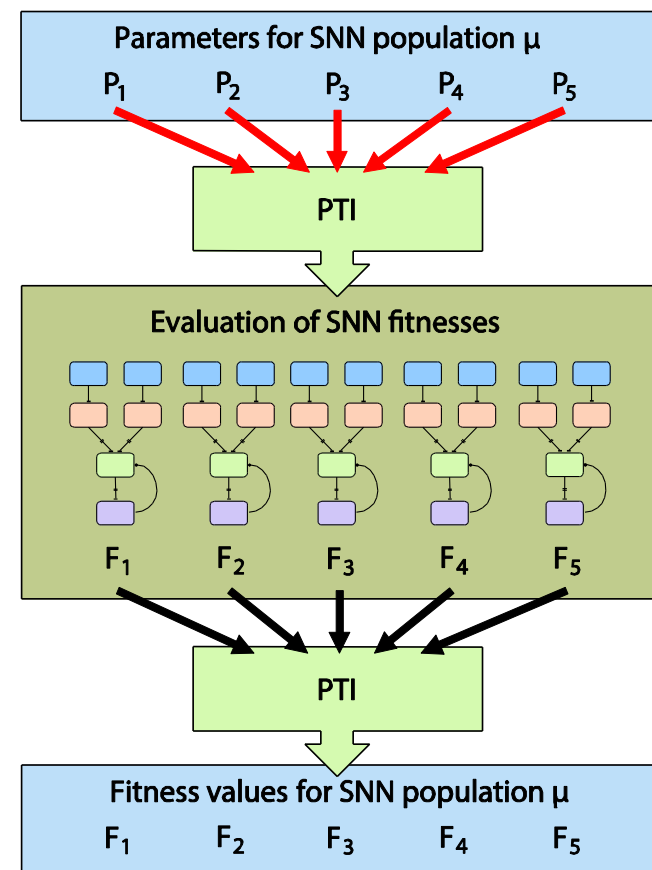
- Automated parameter-tuning framework can quickly and efficiently tune large-scale spiking neural networks
- Leverage
  - Recent progress in evolutionary algorithms.
  - Optimization with off-the-shelf graphics processing units (GPUs)
- The parameter search guided by principles of neuroscience
  - Biological networks adapt their responses to
    - increase the amount of transmitted information, reduce redundancies, and span the stimulus space

# Automated Parameter Framework for Tuning Spiking Neural Networks (SNNs)

a)

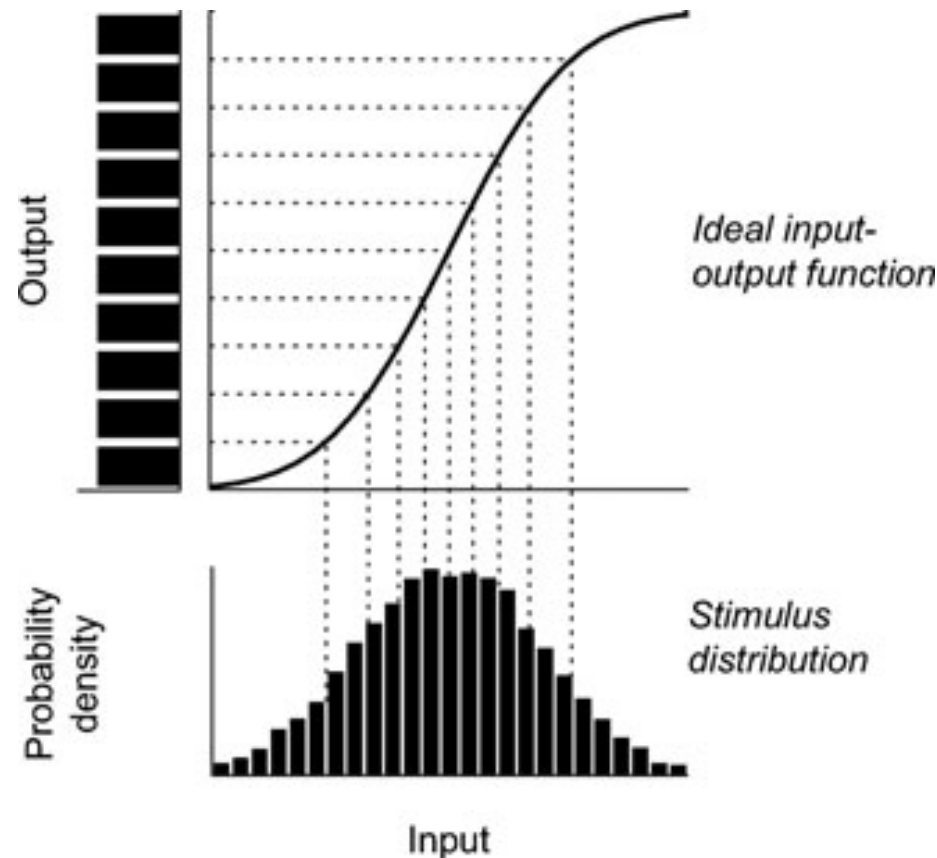
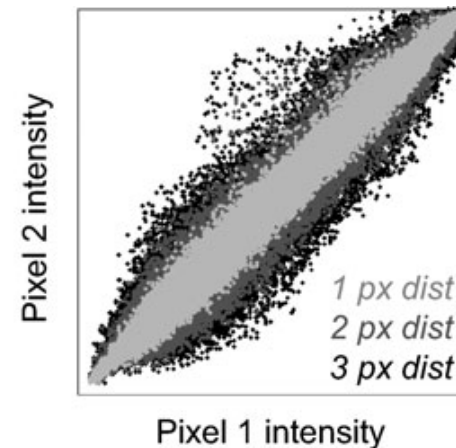


b)



# Efficient Coding Hypothesis

- Fundamental idea:
    - Sensory systems adapt their responses to the regularities of their input
    - Increase the amount of transmitted information at any given time
1. Maximize efficiency (*reduce redundancy*)
  2. Responses should be independent of one another (*decorrelation*)
  3. A stimulus should involve only a small fraction of the available neurons (*sparse*)

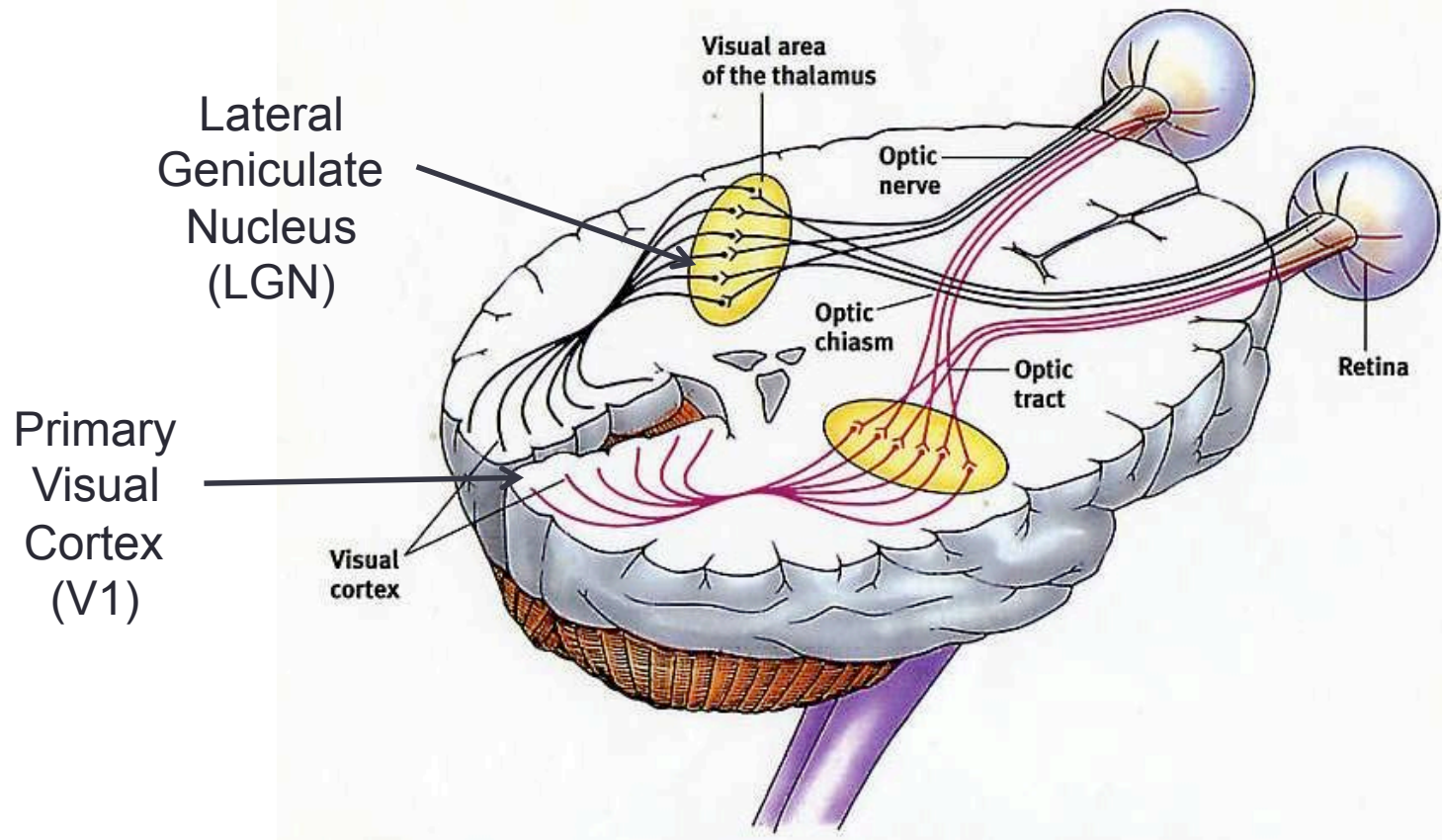


# Fitness Function Based on the Efficient Coding Hypothesis

$$Fitness_{total} = \frac{1}{Fitness_{decorr} + Fitness_{Gauss} + K_{scaling\ factor} \cdot Fitness_{maxRate}}$$

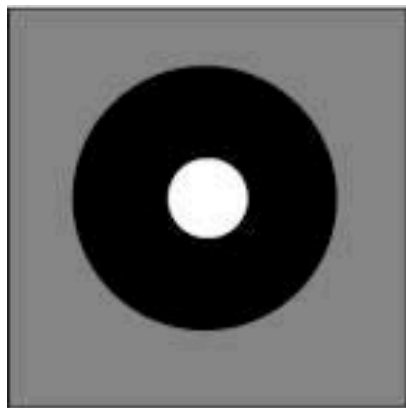
- $Fitness_{decorr}$  ensured decorrelation by forcing each neuron to respond maximally to different stimuli
- $Fitness_{Gauss}$  required Gaussian tuning curves. Also lead neurons to employ their full response range to describe the stimulus
- $Fitness_{maxRate}$  limited the maximum firing rate of each neuron which contributes to sparsity

# Visual Pathway in the Brain

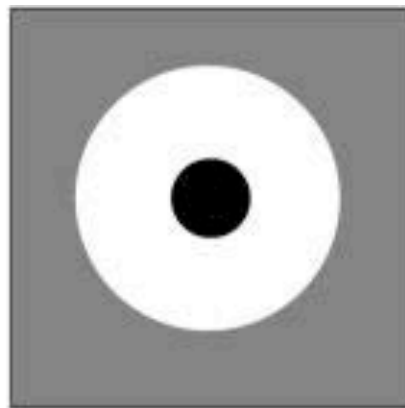


- Sample Parameter Tuning Example for Homeostasis and STDP:
  - Unsupervised learning of V1 simple cell receptive fields in response to patterned inputs.

# Receptive Fields in LGN and V1



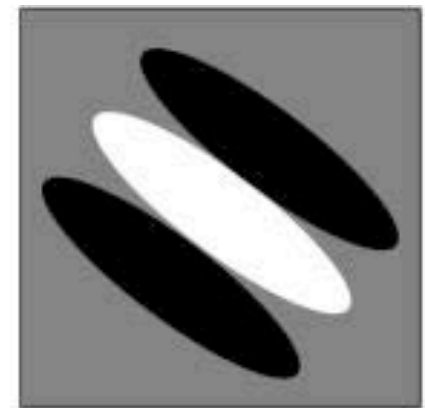
(a) ON cell in  
retina or LGN



(b) OFF cell in  
retina or LGN



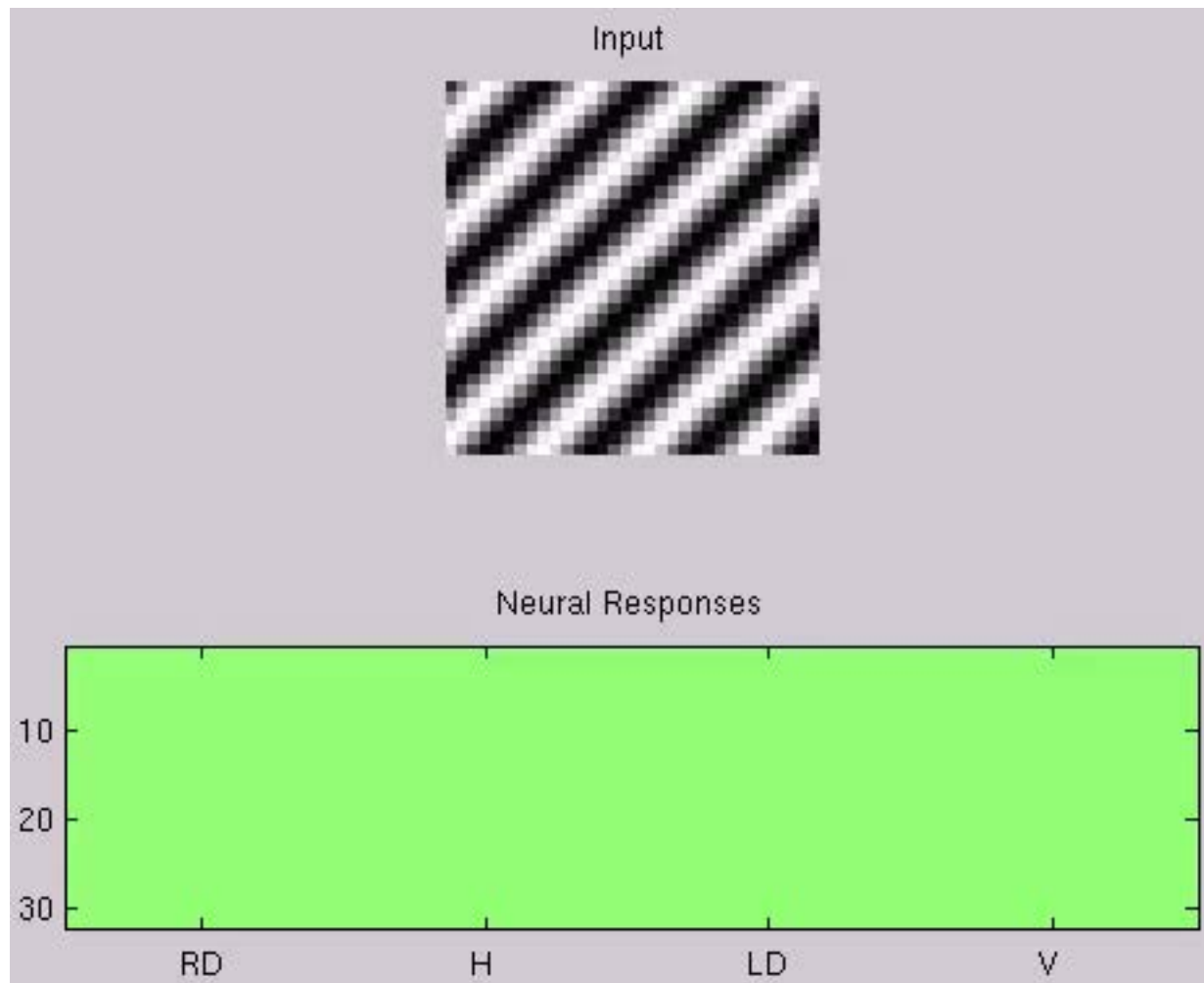
(c) 2-lobe V1  
simple cell



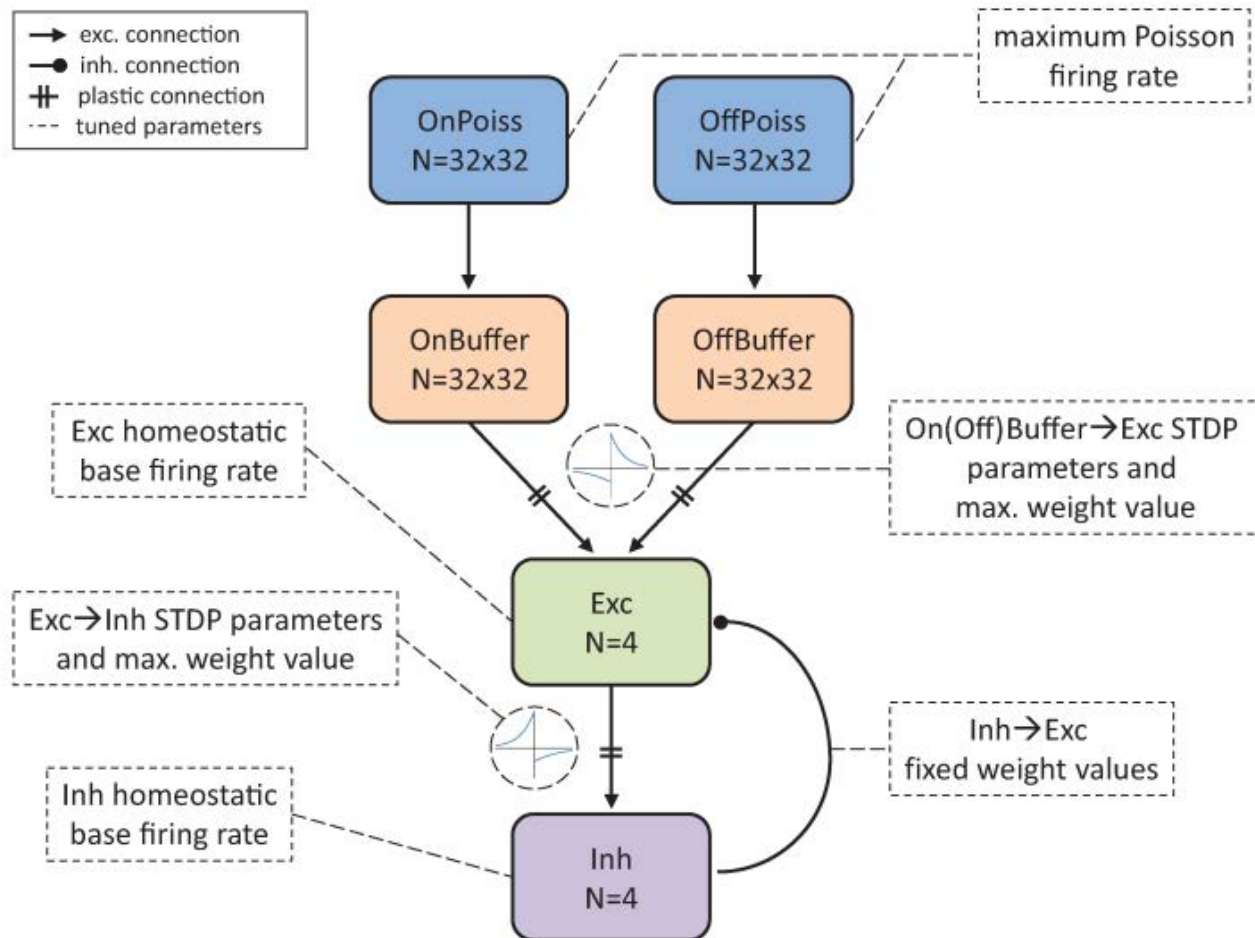
(d) 3-lobe V1  
simple cell



# Simulated Visual Cortex Responses to Sinusoidal Gratings

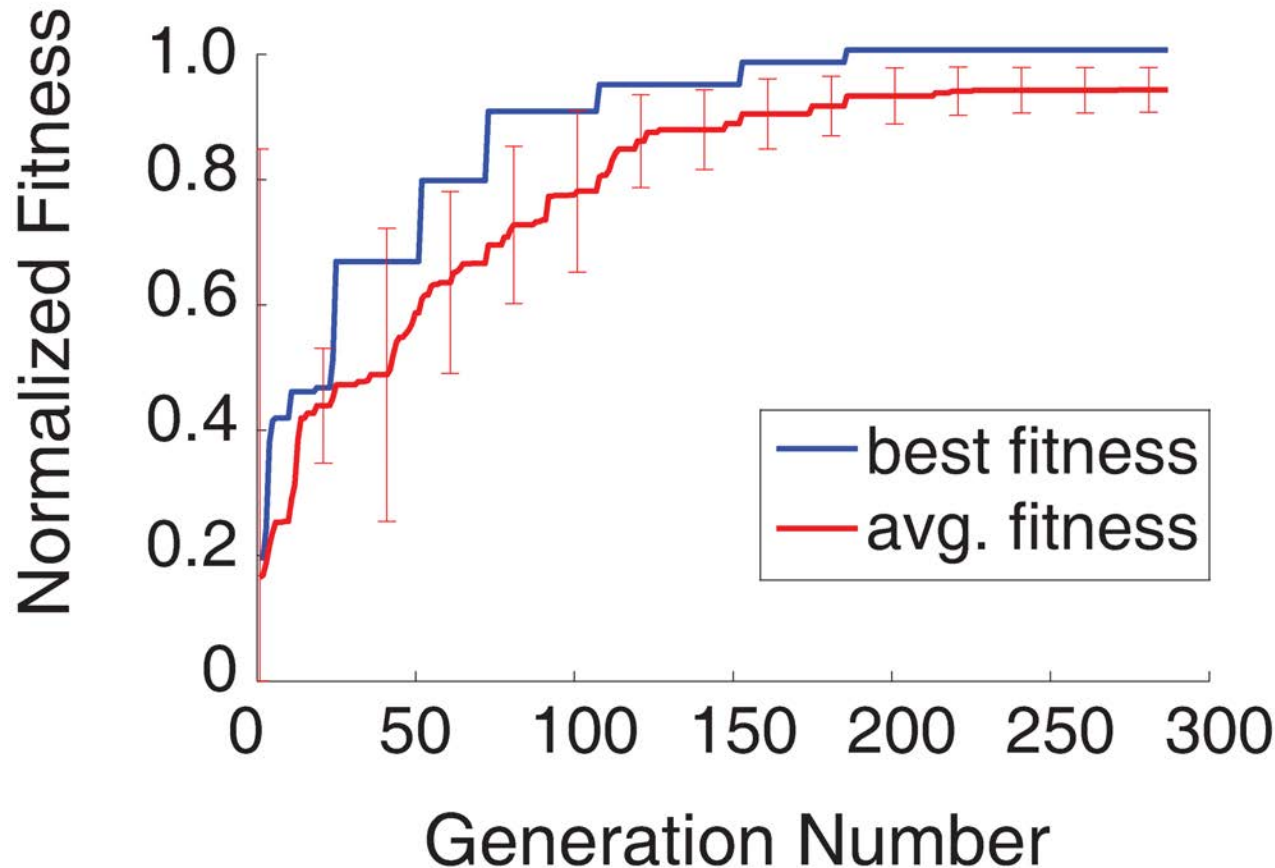


# Tuning SNNs that Generate Self Organizing Receptive Fields (SORF)



- Network size
  - 4104 neurons
- Indirect encoding
  - 14 parameters to search
- Training phase
  - 40 sinusoidal orientations presented
  - 2400 presentations
- Testing phase
  - 8 sinusoidal orientations presented to the network
  - Responses of the Exc neurons were evaluated using the ECH fitness function

## Best and Average Normalized Fitness vs. Generation Number



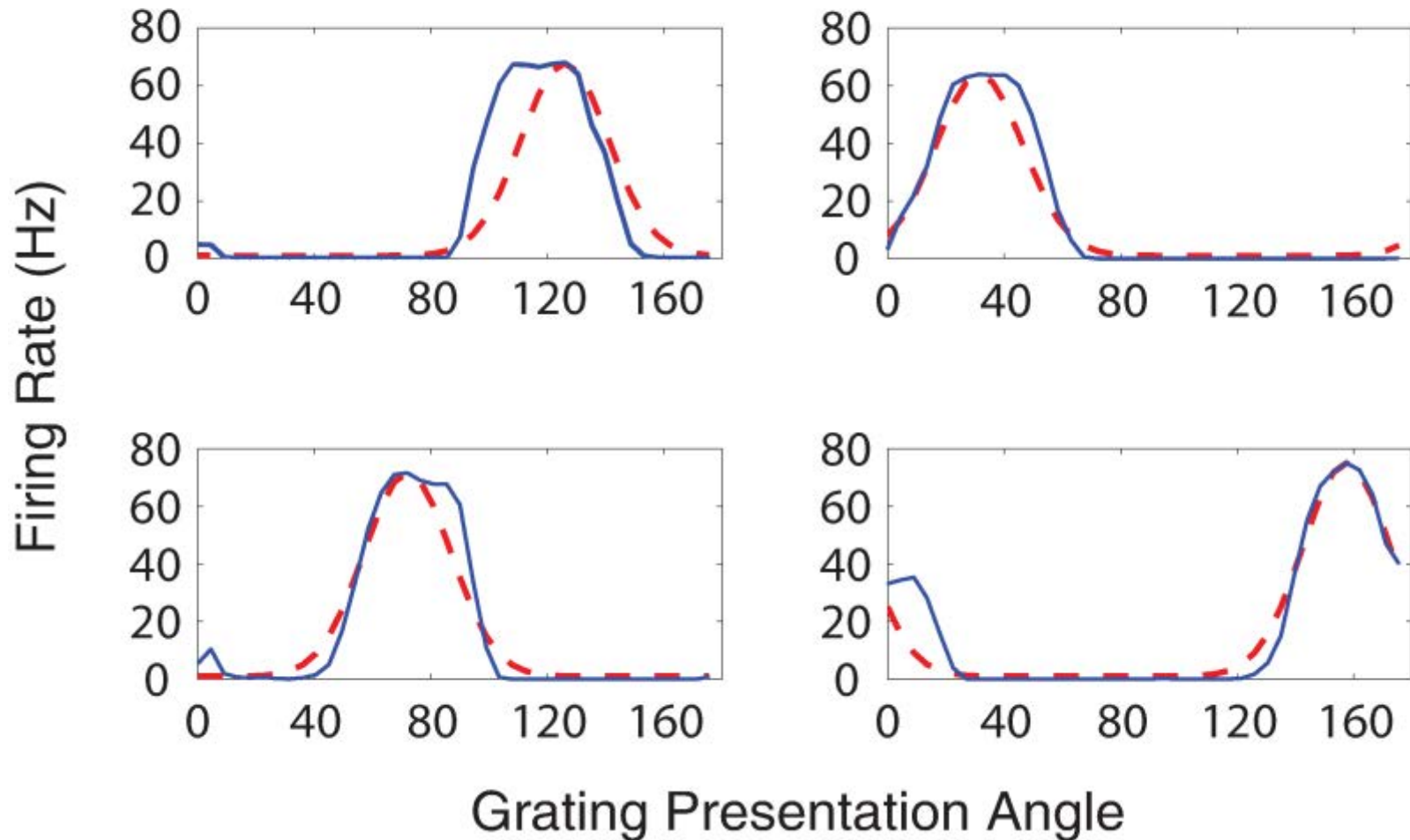
- 10 SNNs in parallel
  - Up to 40.
- 287 EA generations in 127 hours.
- Run on a single NVIDIA Tesla M2090

# Synaptic Weight Progression During Training for a High Fitness Individual



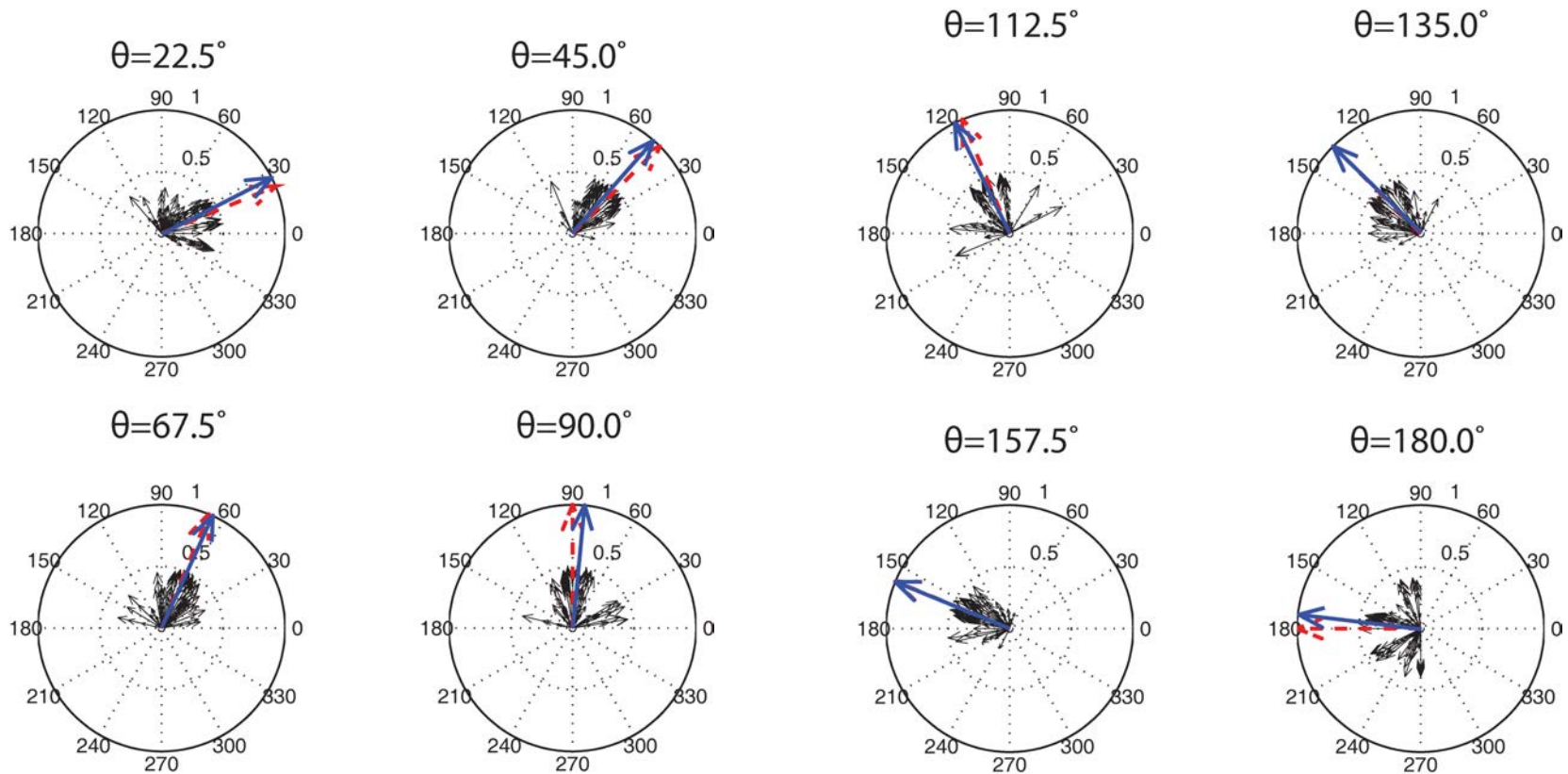
- Synaptic weights for the On(Off)Buffer→Exc connections
  - Light regions denote strong weights, dark regions denote weak weights

# Response Of Neurons To Sinusoidal Gratings



- **Blue line:** firing rate of simulated individual Exc group neuron
- **Red line:** ideal Gaussian tuning curve firing rate response for V1

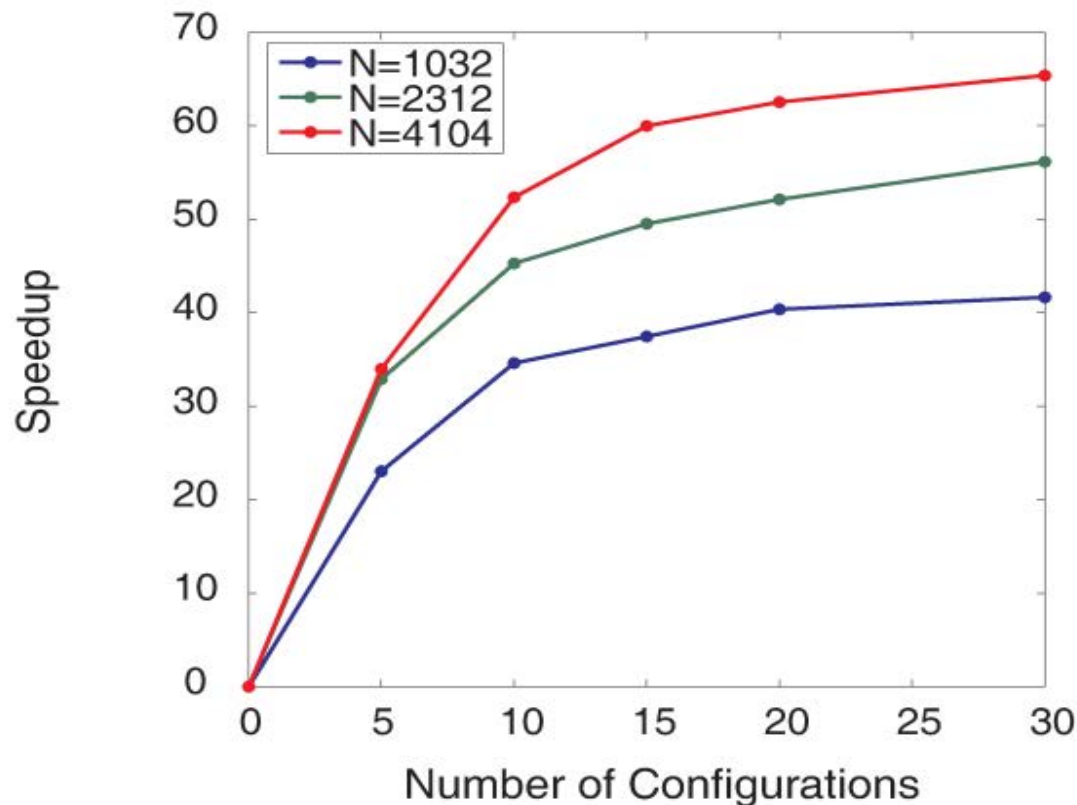
# Population Response After Evolution



- **Population decoding for diff presentation angles (70 sets of 4 exc neurons):**
  - Small black arrows: component vectors for individual neurons
  - **Blue arrow: normalized decoded population vector**
  - **Red arrow: normalized ideal grating presentation vector**

# Automated Parameter Tuning Framework Performance

GPU Speedup Over CPU vs. Number of Networks Run in Parallel  
For Networks of Size  $N=1032$ ,  $2312$ , and  $4104$





# Conclusions

- Large-scale, complex, realistic brain simulations are necessary:
  - For the field of neuromorphic engineering to produce results and applications of practical value
  - To help computational neuroscientists develop new theories of neural function
- To address this challenge:
  - our approach leverages
    - the optimization capabilities of evolutionary computation
    - exploits graphical processing unit (GPU) parallelism
- The efficient coding hypothesis
  - May provide a metric for tuning networks of simulated spiking neurons
  - May also given insights into how real brain networks process information and achieve homeostasis



# Thanks to...

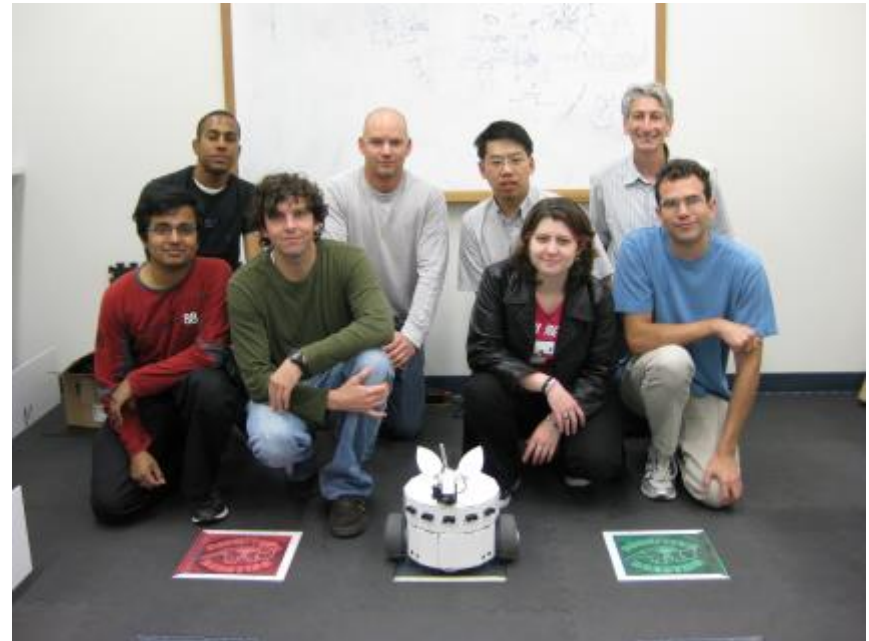
Team CARL Now (2014) – UC Irvine



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Back row – Feng Rong, Andrew Zaldivar, Nicolas Oros, Jeff Krichmar, Derrik Asher, Michael Beyeler, Nik Dutt

Team CARL Then (2009) – UC Irvine



Front row – Jay Nageswaran, Mike Avery, Chelsea Guthrie, Micah Richert

Back row – Andrew Zaldivar, Brian Cox, Michael Wei, Jeff Krichmar

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Thanks!

Questions or Comments???