

On Reliability Hardening in Cyber-Physical Digital-Microfluidic Biochips

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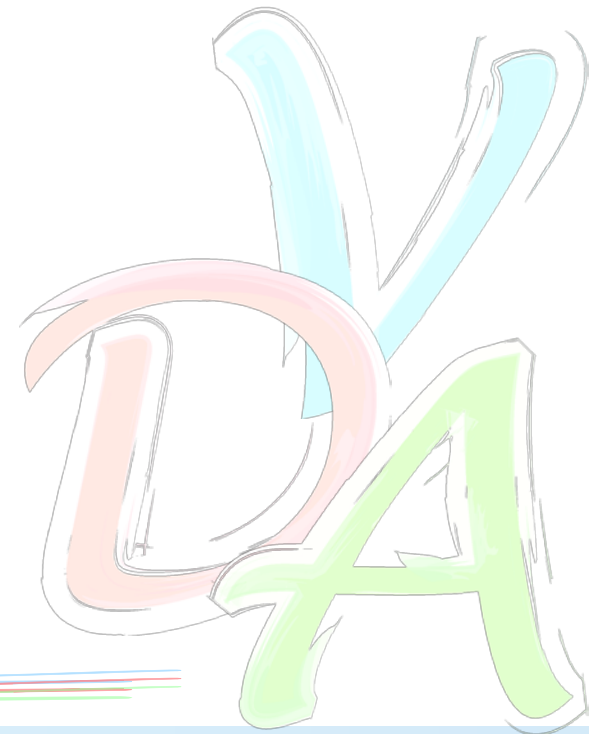
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Outline

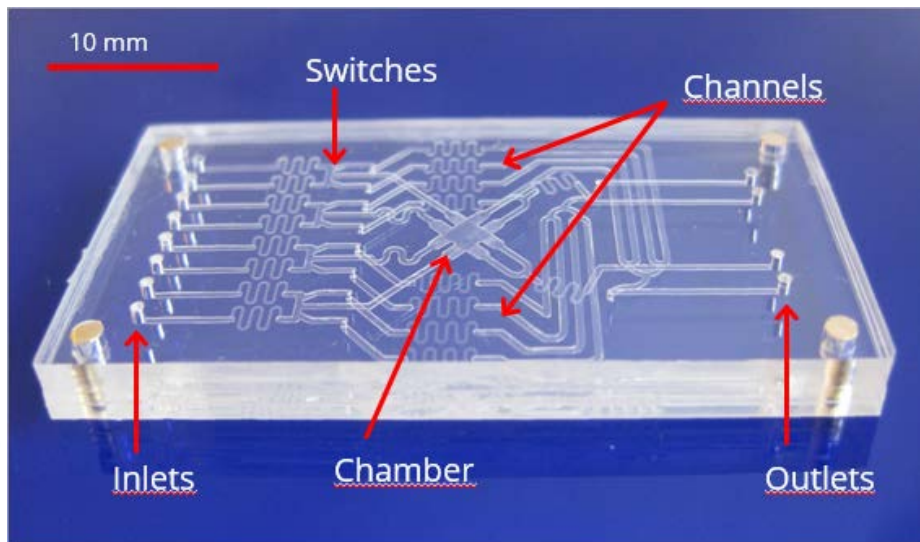
- Introduction
 - Microfluidic Biochip
 - Reliability Challenges
 - Cyber-Physical System (Self-Recovery & Checkpoints)
 - Summary of Checkpoint Problems
- Problem Formulations
- Proposed Algorithm
- Experimental Result



Microfluidic Biochips

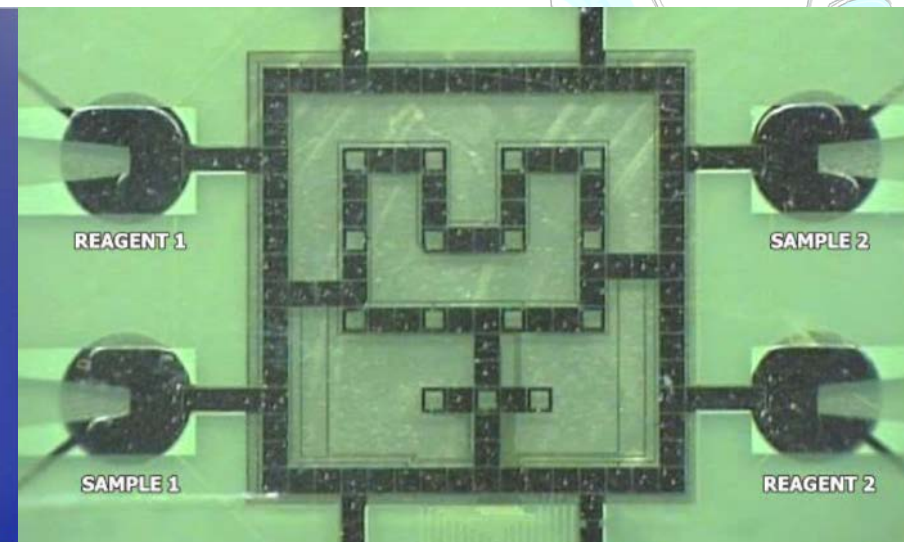
● Flow-based biochips

- Manipulation of continuous liquid through permanently-etched micro-channels



● Digital Biochips (DMFBs)

- Manipulation of discrete droplets on an array of electrodes



Digital Microfluidic Biochips (DMFBs)

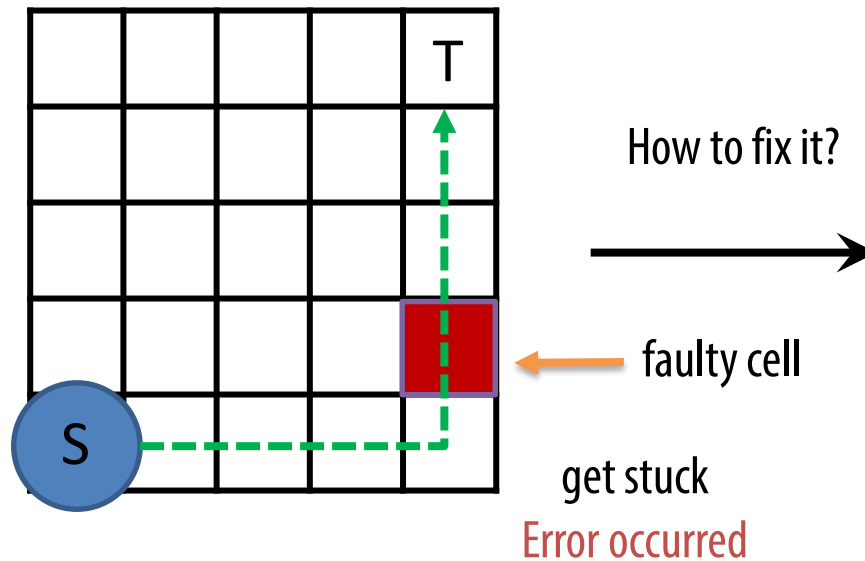
- Two design types of digital microfluidic biochips
 - Application-specific biochips
 - General-purpose biochips

	Application-Specific	General-Purpose
*Hardware Resource (detector, heater, . . . so on)	<u>User-defined</u> (Customized)	<u>Pre-defined</u> , limited
Advantages	High performance, unit cost	Short design cycle, reusability, short time-to-market
Disadvantages	More complex design flow, long time-to-market	Performance, unit cost

Reliability Issues on DMFBs

- Unexpected errors on DMFBs

- If an unexpected error occurs during the experiment, the outcome of the entire experiment will be incorrect.



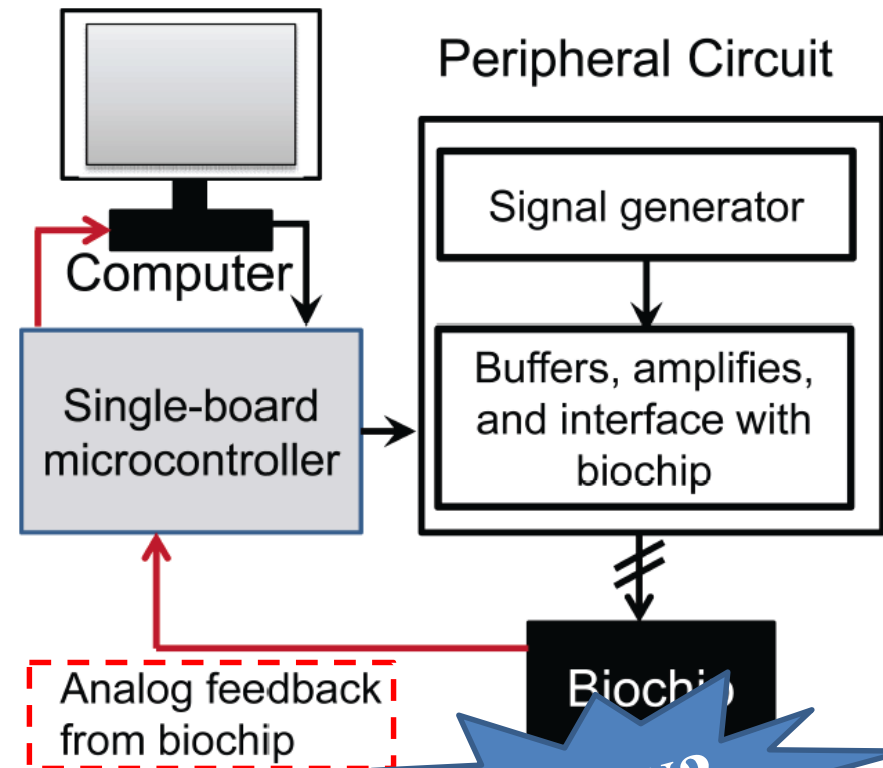
Cyber-physical system has been presented to fix this issue.

A case about unexpected error

Cyber-Physical System

- What can it do?
 - Real-time **monitoring**
 - Real-time **recovering errors**

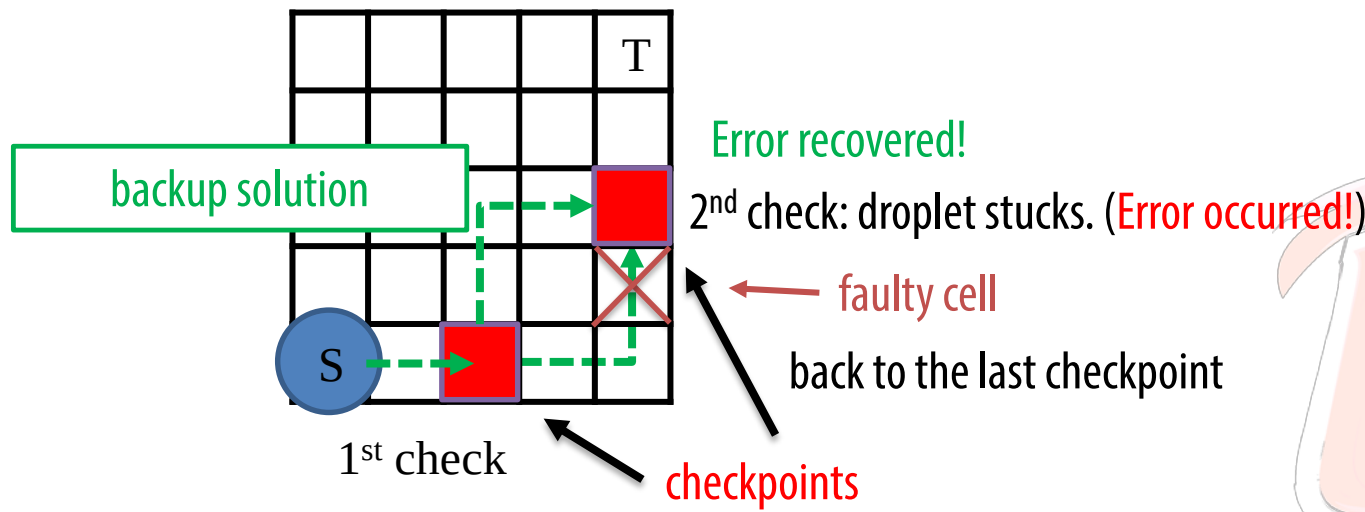
It can recovery the error by referring the feedback signal from the sensor on biochip (checkpoint).



The schematic of cyber-physical

Checkpoint and Self-Recovery

- **Checkpoint** is a specific electrode on biochip, which can provide sensor data (size, concentration, ...etc).
- **Self-recovery** is to provide a backup plan to bypass the faulty cells.
 - Increase the **reliability** of bioassays



-

[illegible]

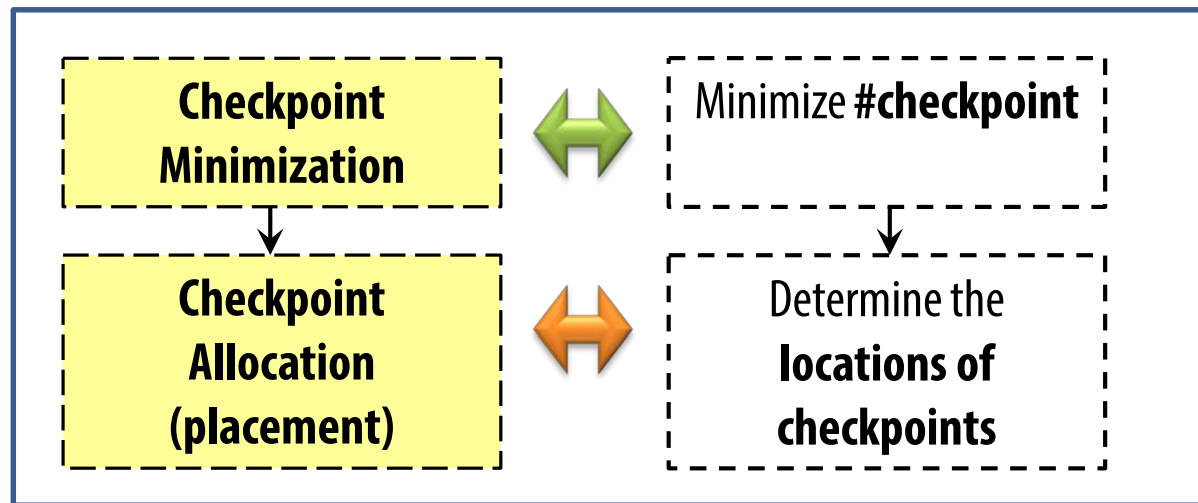
Reliability of bioassays

HOW?

Checkpoint Problems on Application-Specific DMFBs (AS-DMFBs)

- More checkpoints lead to more cost.
 - How to minimize the number of checkpoints?
 - How to decide the location of checkpoints?

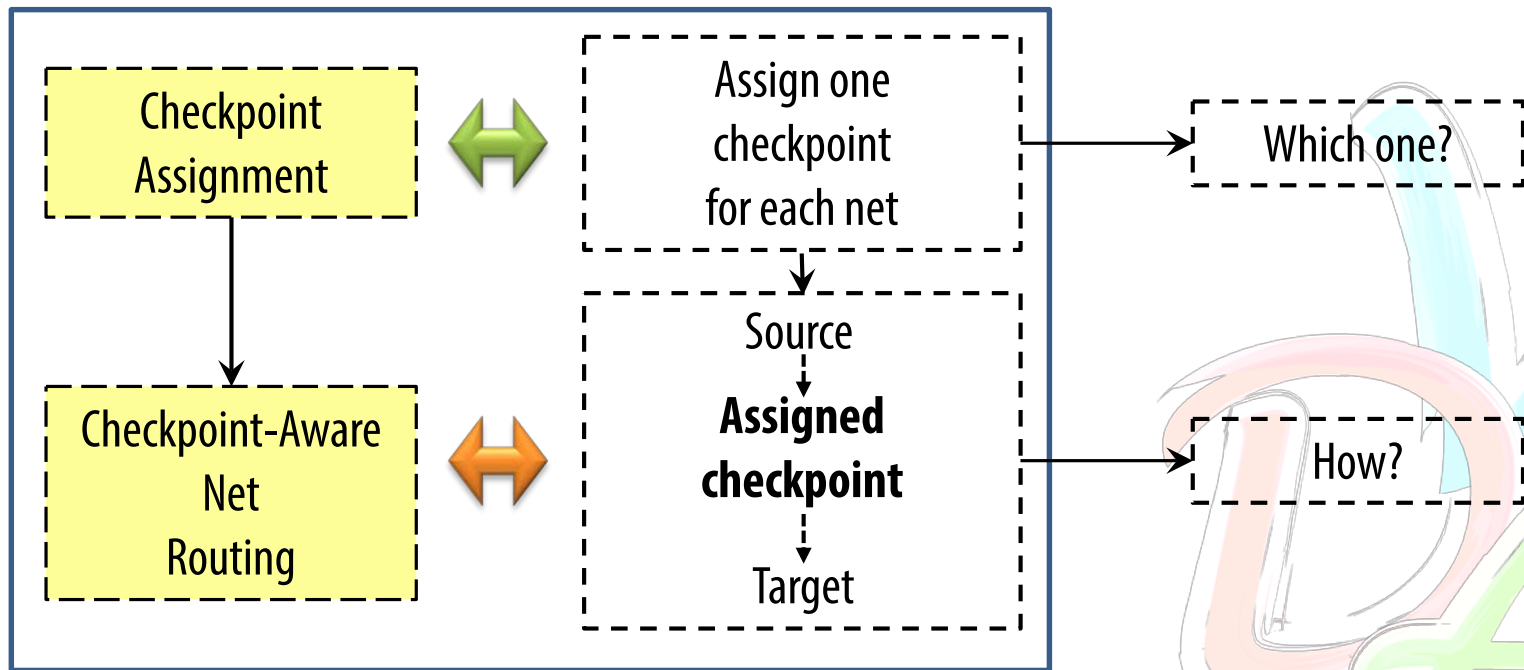
Design Flow



Checkpoint Problems on General-Purpose DMFBs (GP-DMFBs)

- There is a limited number/pre-located checkpoint.

Design Flow



Comparison between Two Types of Biochip Design

- Our contribution
 - Checkpoint minimization & checkpoint allocation.
 - Checkpoint assignment & checkpoint routing

		Application-Specific	General-Purposed
Checkpoint Resource		Customized	Pre-defined
Goals	#Checkpoints Minimization	V	
	Checkpoint Allocation (Placement)	V	
	Checkpoint Assignment		V
	Checkpoint Routing		V



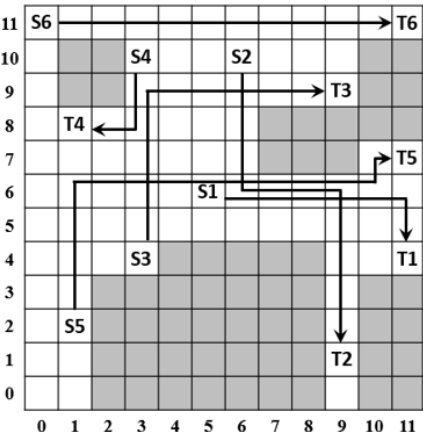
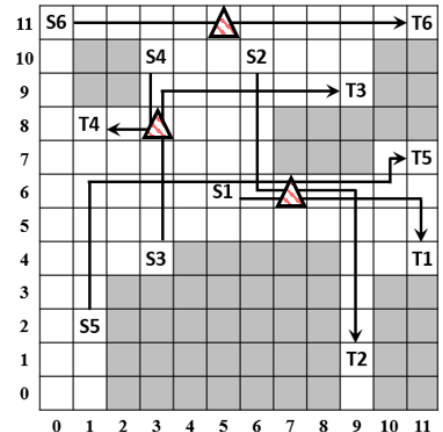
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 - Application-Specific DMFBs
 - General-Purpose DMFBs
- Proposed Algorithm
- Experimental Result



Problems in Application-Specific DMFBs

- **Features:** Checkpoints can be arranged.
- **Objective:** Minimize the number of required checkpoints.
- **Constraint:** Each sensitive droplet needs to cross at least one checkpoint.

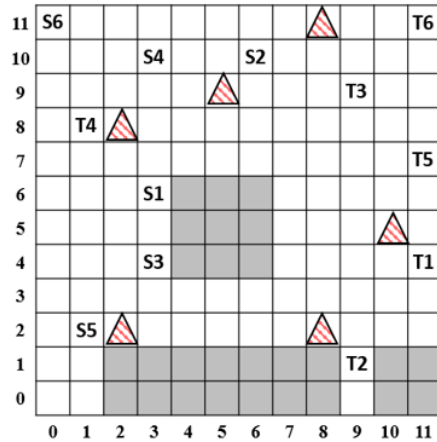
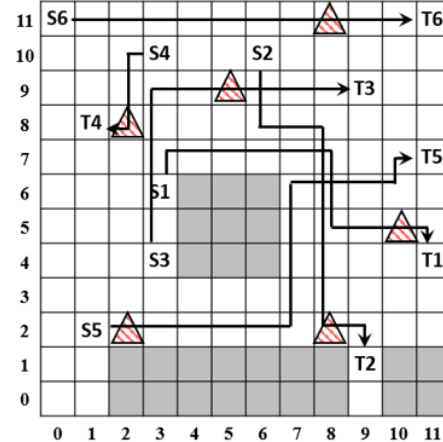
Input	Output
Routing solution	#Checkpoints & Locations of checkpoints
	



checkpoint

Problems in General-Purpose DMFBs

- **Features:**
Checkpoints are pre-located.
- **Objective:** Minimize the Max. arrival time $T_{\max}$.
- **Constraint:** Each sensitive droplet needs to cross at least one checkpoint.

Input	Output
Locations of checkpoints & Netlist	Routing solution
	



checkpoint



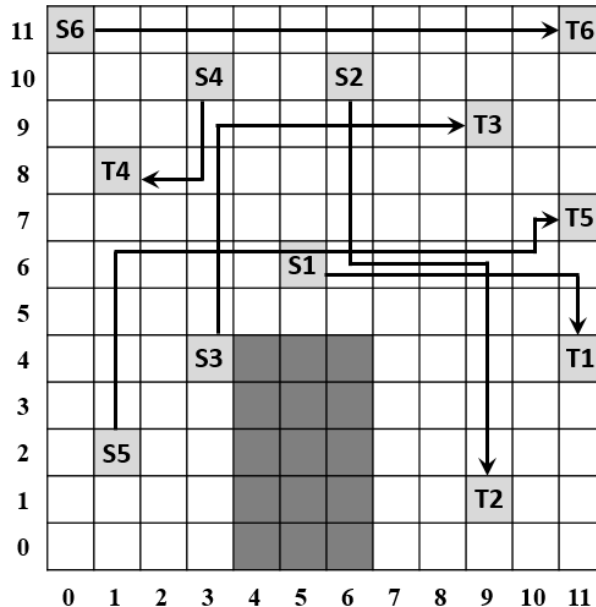
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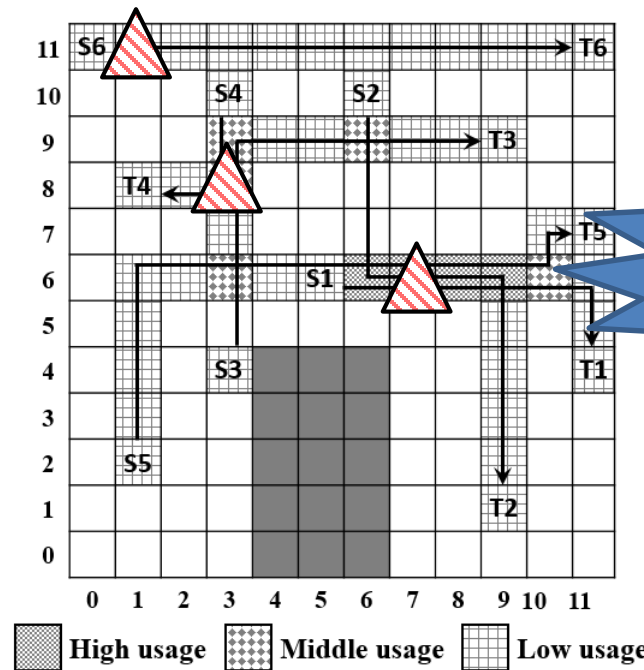


Checkpoint Minimization

- Intuitively, we might assign highly used cells to be checkpoints.



Routing solution



Usage map

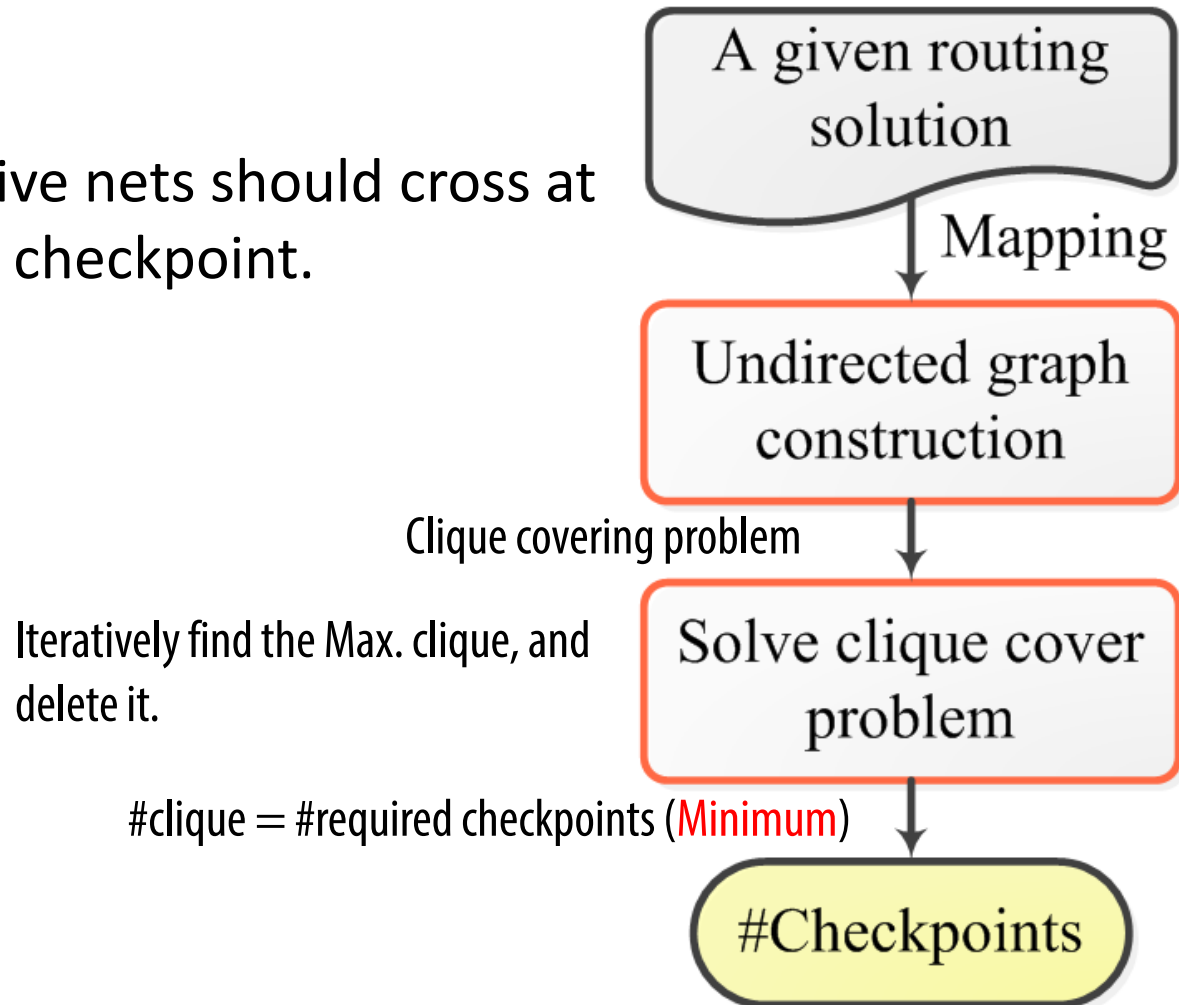
HOW?

checkpoint?

Proposed Minimization Flow

● Constraint:

- All sensitive nets should cross at least one checkpoint.

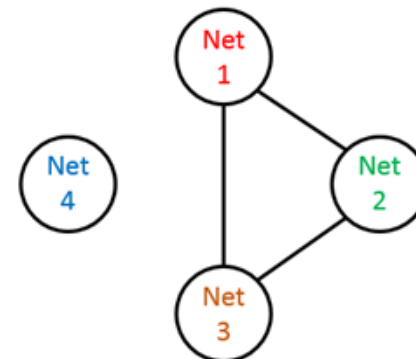
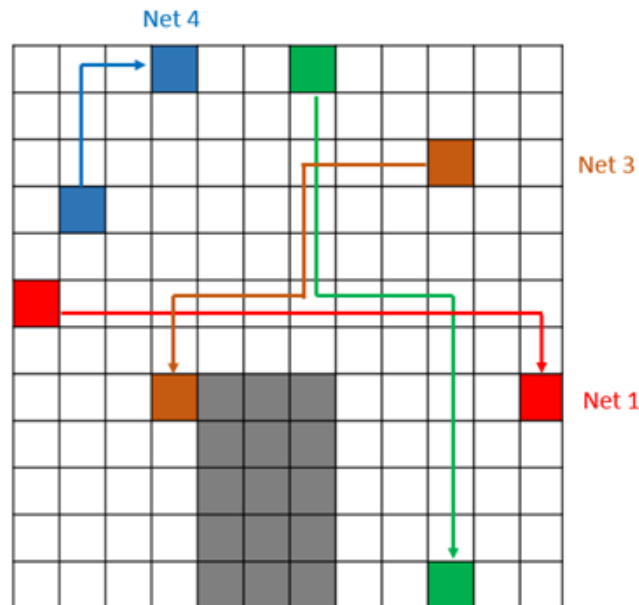


Iteratively find the Max. clique, and delete it.

#clique = #required checkpoints (Minimum)

Compatibility Graph Construction

- Construct compatibility graph, where
 - A node represents a net
 - An edge represents the paths of two nets are overlapping



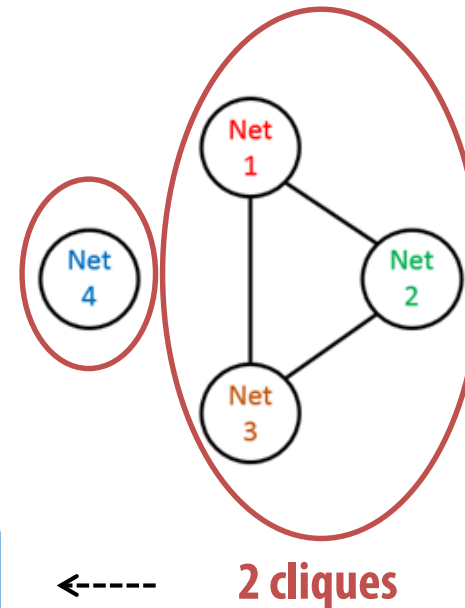
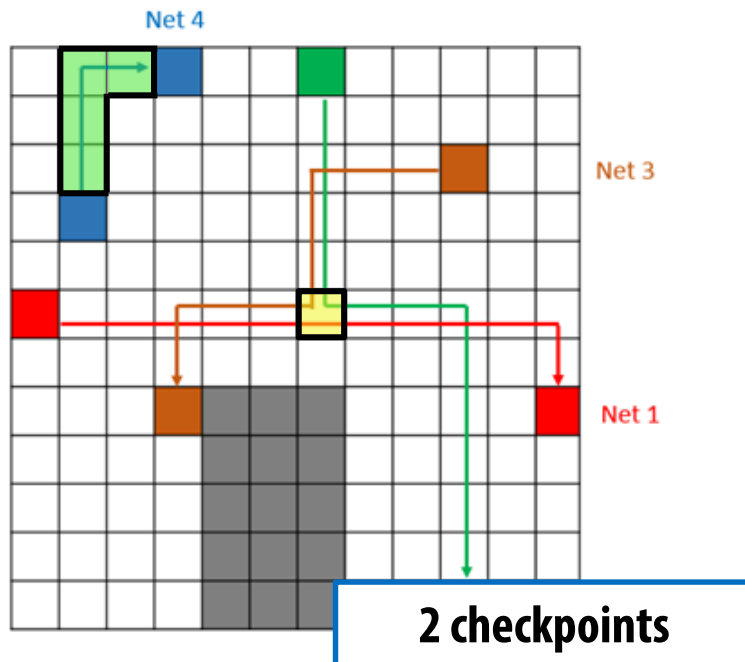
After the graph has been constructed

original minimization problem

-----> **clique cover problem**

Clique Cover Problem

- Find a minimal number of non-overlapping cliques which cover all nodes in graph.

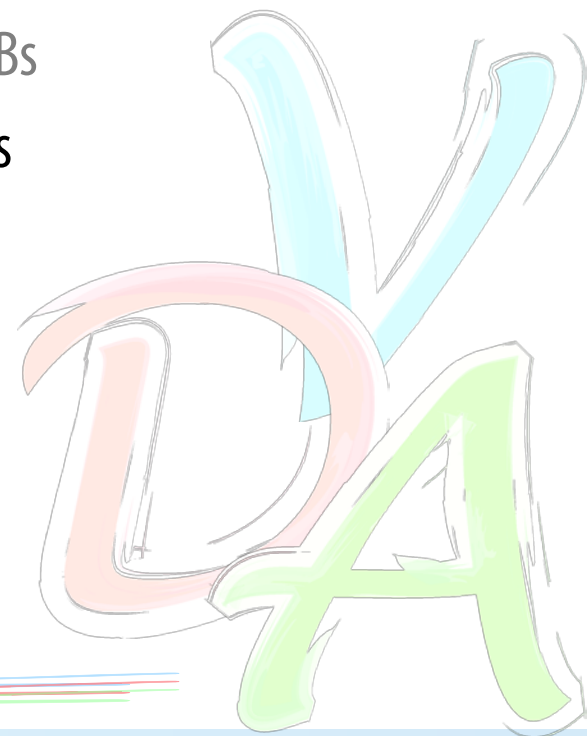


-  Possible locations of the first checkpoint
-  Possible locations of the second checkpoint



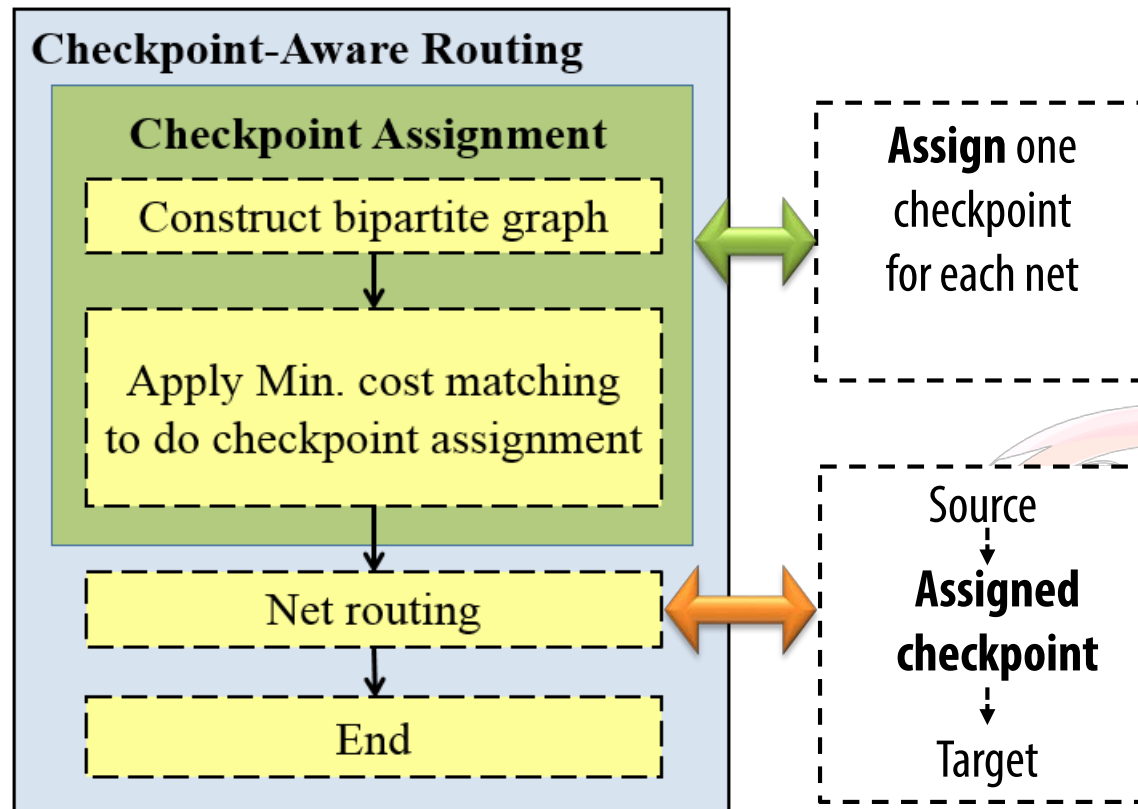
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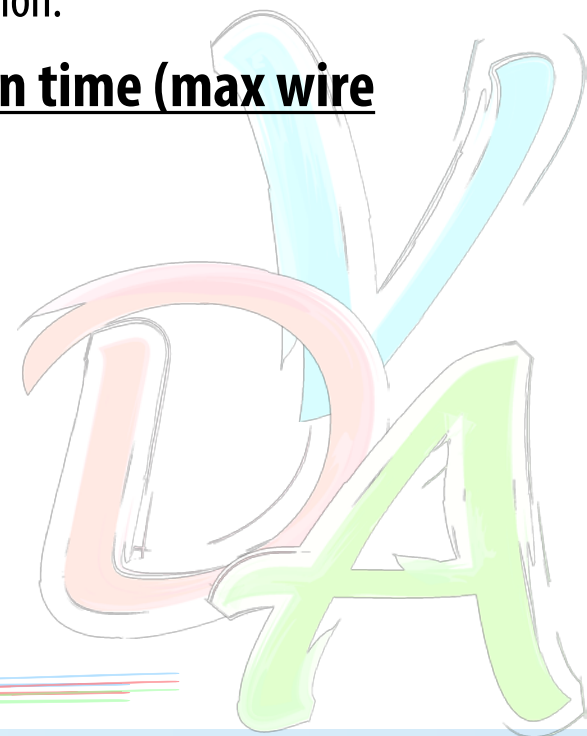
Checkpoint-Aware Routing

- Constraint: All sensitive nets should cross at least one checkpoint.



Checkpoint Assignment

- We construct the bi-partite graph to balance two goals:
 - **Reducing (eliminating) checkpoint congestion**,
(there are several droplets trying to use the same checkpoint at the same time)
 - ◆ Some droplets needs to be stalled when checkpoint congestion.
 - **Minimizing the maximum droplet transportation time (max wire length)**.

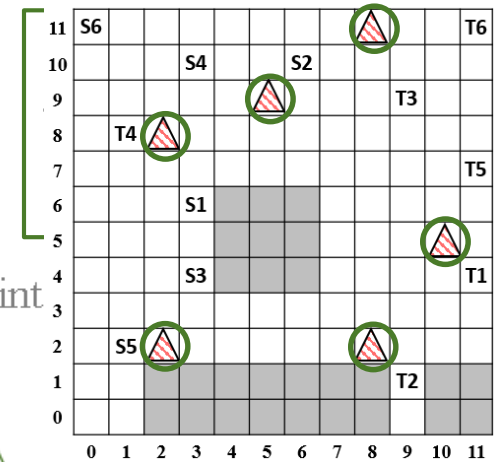
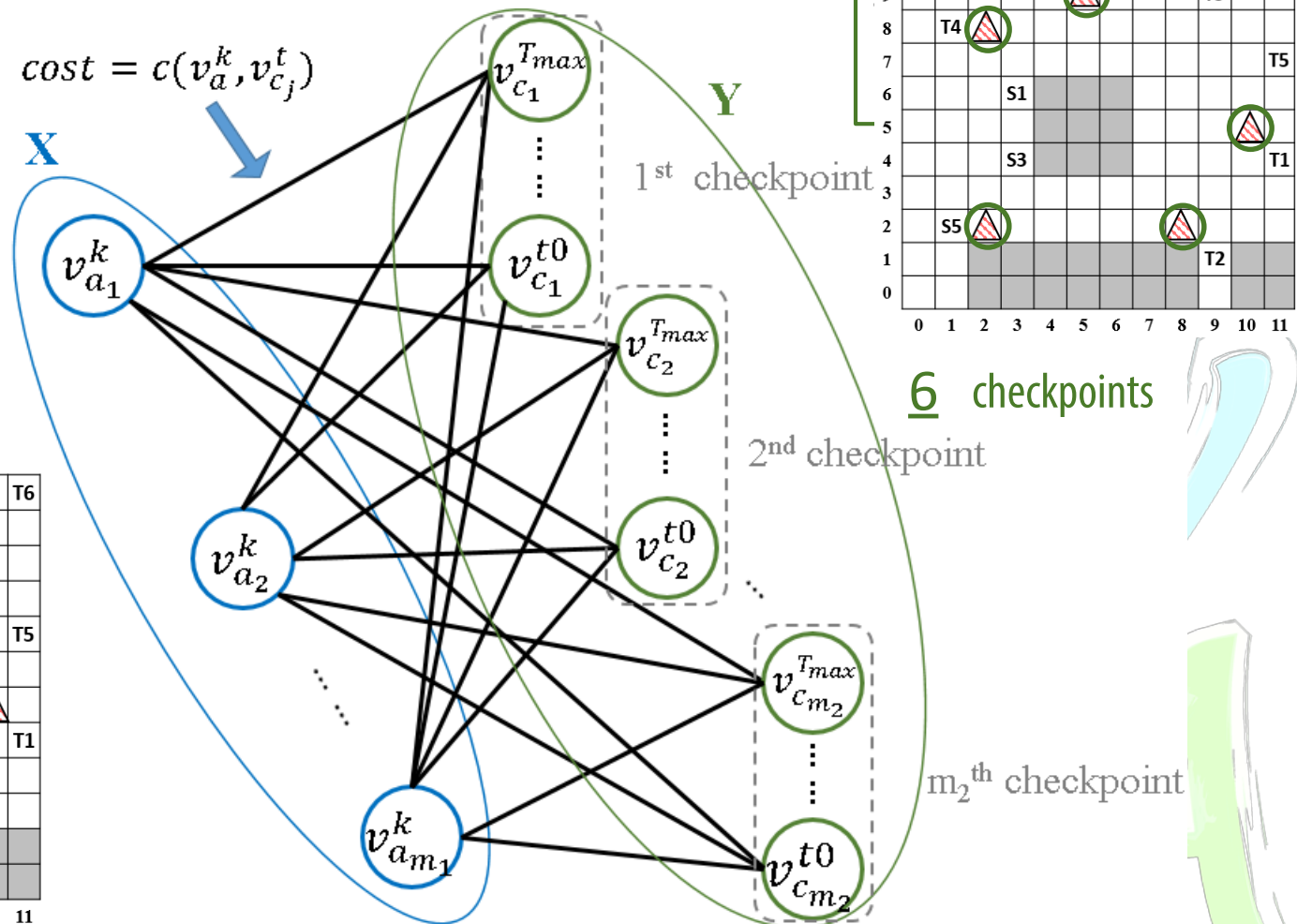
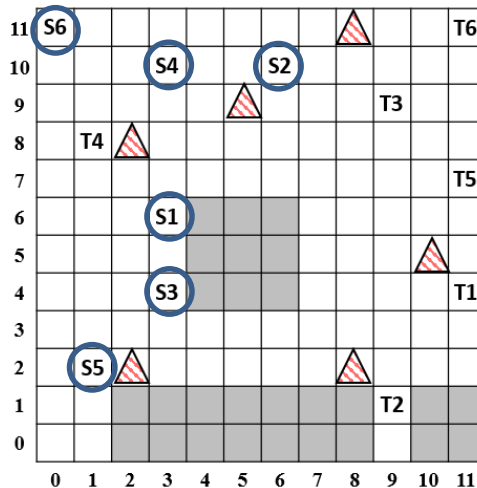


Bipartite Graph Construction

Cost = model (net length, congestion penalty)

$$\text{cost} = c(v_a^k, v_{c_j}^t)$$

6 droplets



6 checkpoints

Cost in Bipartite Graph

- The cost is defined as:

wire length estimation **timing penalty for checkpoint congestion**

$$c(v_a^k, v_{c_j}^t) = \begin{cases} WL_{a,k}^j + (t - T_{shorstest}^{a,k,j}), & \text{if } t \geq T_{shorstest}^{a,k,j} \\ \infty, & \text{if } t < T_{shorstest}^{a,k,j} \end{cases}$$

where $WL_{a,k}^j$ is the sum of the distance from source to checkpoint and the distance from checkpoint to target, and $T_{shorstest}^{a,k,j}$ is the minimum distance from source to target.

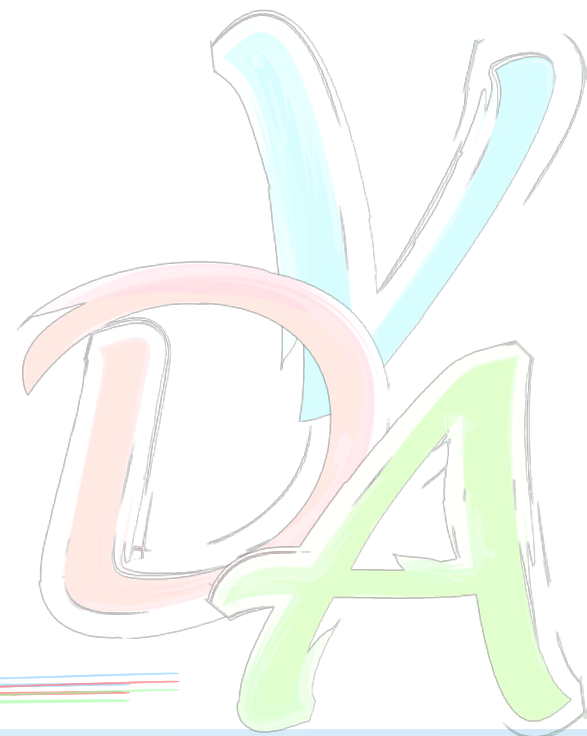
- We use **Hungarian** method [1] to derive the matching in a bipartite graph.

[1]: Harold W. Kuhn, "The Hungarian Method for the assignment problem", Naval Research Logistics Quarterly, 2: 83–97, 1955. Kuhn's original publication.



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Setting on Checkpoint Minimization

- We choose state-of-the-art routing engine to derive the routing solution [2] as input.
- Assume all droplets are highly sensitive.
 - That is, all droplets need to cross at least one checkpoint.
- **Baseline algorithm** determines the number of required checkpoints in an exhaustive manner.
 - That is, #net is equal to #checkpoint

[2]: O. Keszocze, R. Wille, T.-Y. Ho, and R. Drechsler, “Exact one-pass synthesis of digital microfluidic biochips,” in Design Automation Conference, pp. 1–6, 2014.

Result on Checkpoint Minimization

- On average, the proposed minimization algorithm reduces the number of required checkpoint by 17%.

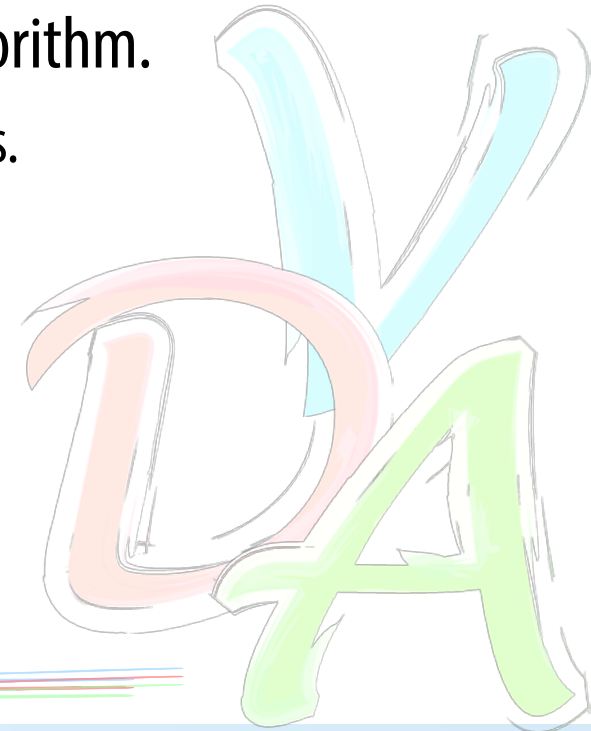
	Exhaustive ¹	Proposed
Name	#Checkpoint	#Checkpoint
in_vitro_1	28	25
in_vitro_2	35	29
protein_1	181	150
protein_2	178	146
Avg.	1.00x	0.83x

#checkpoint: Total number of required checkpoints among

The proposed algorithm can **globally select the most efficient candidates (cells)** as checkpoints. → Less #checkpoint are needed

Setting on Checkpoint-Aware Routing

- Assume the locations of checkpoints are evenly distributed.
- Assume all droplets are highly sensitive.
 - That is, all droplets need to cross at least one checkpoint.
- **Baseline algorithm** is the nearest-neighbor algorithm.
 - All droplets will choose the nearest checkpoint to cross.



Result on Checkpoint-Aware Routing

- The proposed routing algorithm achieves
 - 100% routing completion for all test cases.
 - On average, 10% less average latest-arrival-time and 15% less maximum latest-arrival-time.

Name	Nearest ¹		Proposed	
	Max. T_{la}	Avg. T_{la}	Max. T_{la}	Avg. T_{la}
in_vitro_1	21 (fail)	12	18	12
in_vitro_2	20	12	16	10
protein_1	24 (fail)	17	20	16
protein_2	20	9	18	7
Avg.	1.00x	1.00x	0.85x	0.90x

The proposed algorithm can **globally assign the checkpoints to nets.** → Less checkpoint congestions are occurred.

Conclusion

- We introduced the checkpoint problems in the two design flows.
- We proposed
 - The **first checkpoint minimization algorithm** in application-specific DMFBs
 - The **first checkpoint-aware routing algorithm** in general-purpose DMFBs.
- The experimental results on a set of real-life applications demonstrated that the proposed algorithms are effective.

Thank You

