

Partitioned and Overhead-Aware Scheduling of Mixed-Criticality Real-Time Systems

Yuanbin Zhou¹, Soheil Samii^{1,2}, Petru Eles¹, Zebo Peng¹

¹ESLAB, Linköping University, Sweden

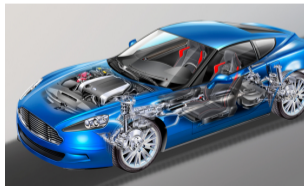
²General Motors R&D, USA

Overview

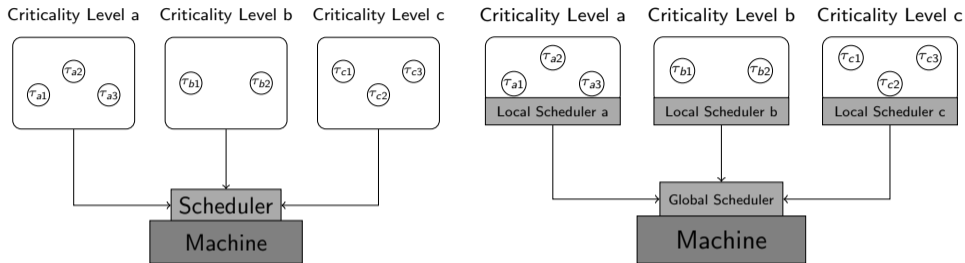
- 1 Introduction & System Model
- 2 Motivation
- 3 Problem Formulation
- 4 Proposed Approach
- 5 Experimental Results

Mixed-Criticality Systems (MCS)

- Tasks with different criticalities share computation resources
- Criticality used in functional safety, e.g., automotive
- Industrial safety standards
 - ISO 26262 – road vehicles
 - DO 178C – avionics software
 - IEC 61508 – generic standard
- Core concept for MCS is sufficient independence



Partitioned Scheduling (Hierarchical Scheduling)

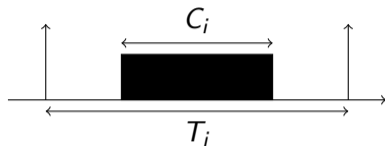


(a) Integrated Architecture

(b) Partitioned Architecture

- **Global Scheduler** assign system resources to Local Scheduler
- Tasks scheduled by **Local Scheduler**
- Misbehaviors do not affect tasks with different criticality levels
- Online local scheduler (flexible), Offline global scheduler (predictable)

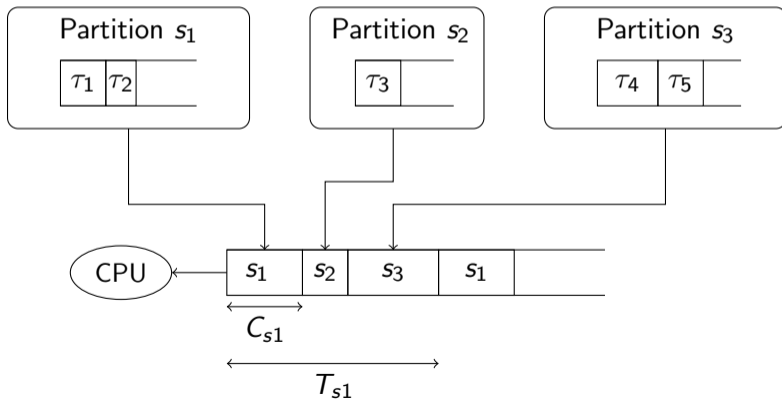
Task Model



- Single-core platform
- Timing parameters for task τ_i
 - Worst-case Execution Time (WCET) C_i
 - Period T_i
 - Relative Deadline D_i ($D_i \leq T_i$)
 - Fixed Priority P_i
- Criticality level SIL_i

Partition Model

- Periodic partition:
 - Period T_s
 - Deadline D_s ($D_s = T_s$)
 - Capacity C_s



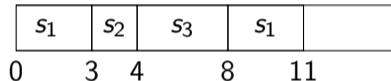
Design of Partitions

- Need to be determined
 - Allocation tasks to partitions
 - Period : T_s , Capacity : C_s
- (C_s, T_s) pairs of each partition obtained¹
 - Cost function of each partition (e.g., Utilization) defined
- Tasks within partitions are guaranteed schedulable

¹Almeida L, Pedreiras P. Scheduling within temporal partitions: response-time analysis and server design[C]//Emsoft. 2004: 95-103.

Motivation – Offline Partition Scheduling

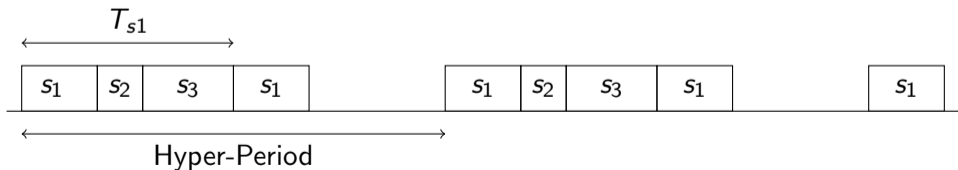
- Offline scheduling
 - Schedule table determined before system runs
 - Schedule table size affect : **Synthesis time, Memory usage**



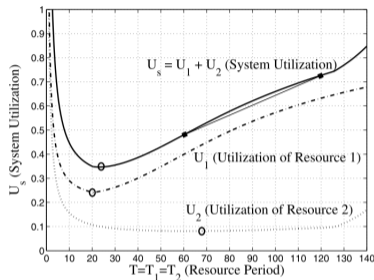
Partition	Start Time	End Time
S_1	0	3
S_2	3	4
S_3	4	8
S_1	8	11

Motivation – Hyper-Period

- Hyper-Period
 - Schedule is same cross Hyper-Period (HP)
 - Least Common Multiple of periods
- Very long Hyper-Period
 - Example 1: $HP\{15, 16, 31, 32, 33\} = 163680$
- Harmonic relations
 - $\frac{T_{i+1}}{T_i} \in \mathbb{N}^+$
 - Example 2: $HP\{16, 16, 32, 32, 32\} = 32$



Motivation – Period vs Utilization

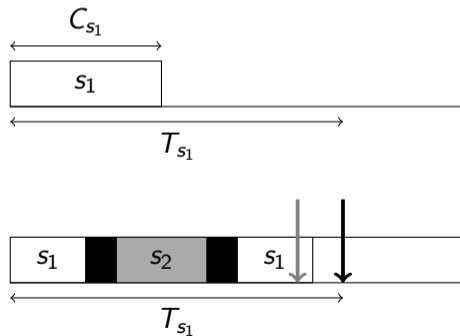


- Partitions' utilization increased by setting different periods²
 - e.g., harmonic periods
- Research problem: to **trade-off** hyper-period length and system schedulability

²Yoon M K et al. Holistic design parameter optimization of multiple periodic resources in hierarchical scheduling[C]//DATE,2013: 1313-1318.

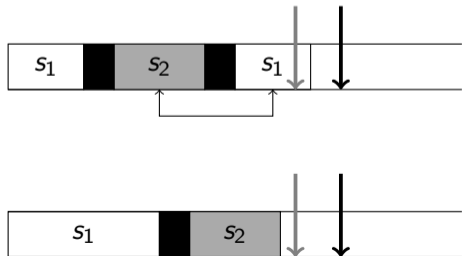
Motivation – Overhead between Partitions

- Construct **offline** schedule table
 - Preemptive EDF to simulate within hyper-period
 - Utilization $\leq 1 \rightarrow$ schedulable
 - Several partition slices due to preemption
 - Scheduling overhead between partition slices



Motivation – Overhead between Partitions (Cont.)

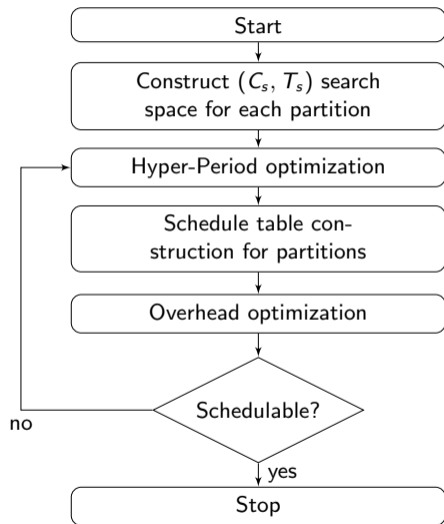
- Too many partition slices \rightarrow too much scheduling overhead \rightarrow impact schedulability
- EDF is not optimal when overhead considered
- Combine partition slices \rightarrow reduce utilization \rightarrow improve schedulability
 - Deadline and release constraints not violated
 - Possible due to offline scheduling



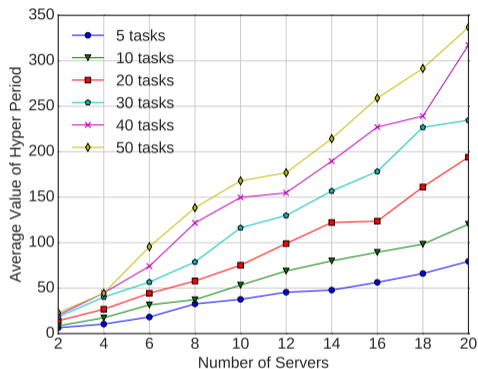
Problem Formulation

- Input:
 - Task Parameters (including WCET, Deadline, Period, Criticality Level)
- Output:
 - Offline schedule table for partitions
- Constraints:
 - System is schedulable
 - Reduce partition schedule length

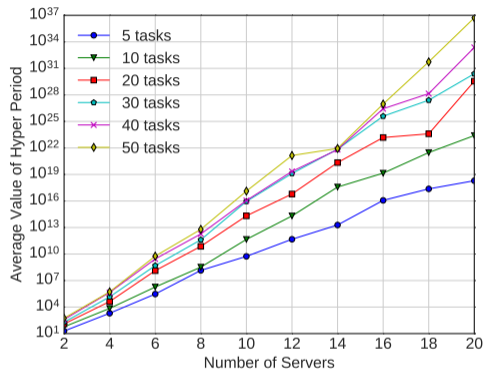
Overall Approach



Experimental Results (Hyper-Period Value)



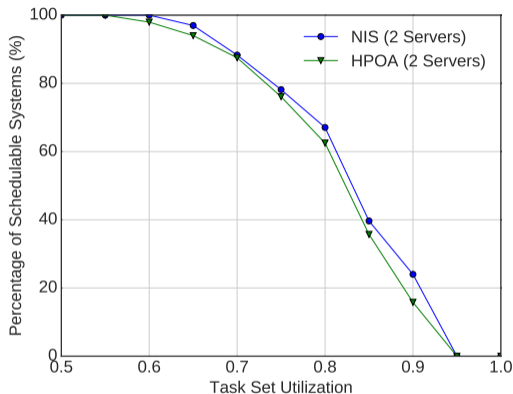
(a) Proposed Approach



(b) Straight-forward Approach

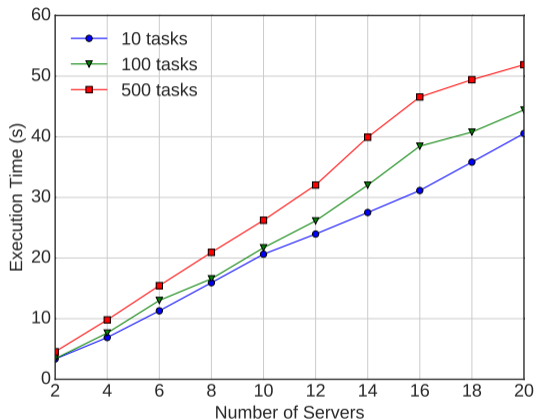
- Proposed approach is within several hundreds
- Straight-forward approach (NIS): rounded into nearest integer
 - from several hundreds to 10^{37}

Experimental Results (System Schedulability)



- HPOA : proposed approach, NIS : straight-forward approach
- Differences in schedulability are smaller than 10%
- Large reduction in hyper-period, small sacrifice on schedulability

Experimental Results (Scalability)



- Synthesis is done within scalable time

Conclusions

- Partitioned and overhead-aware scheduling **framework** for mixed-criticality systems
- Synthesis schedule table for partitions with **reduced schedule length** and **preserved system schedulability**
- **Re-scheduling algorithm** to reduce runtime overhead between partitions