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#### Beyond Time-Quantum: A Basic-Block FDA Approach for Accurate System Computing Performance Estimation

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#### Program Phase – A Sequence of Executions with Similar Behavior

 Most applications have repetitive execution phases which alternatively occur in each execution run.



## Highly Correlated to the Program Code Structure

- Application behaviors follow closely with the code functions executed.
- Basic block, loop, and function are common code structures, which usually exhibit stable behavior in repeated executions.



### A Few Well-Known Approaches

- Time-quantum-based approach [1][2][3]
  - Divide a program execution into fixed-length intervals, with each interval representing a phase segment that is to be merged into a phase.
- Program-structure-based approach [4]
  - Use the basic structures such as loops or functions to determine program phases.

[1] Phase tracking and prediction, 2003, ISCA

[2] Transition phase classification and prediction, 2005, HPCA

[3] Improving dynamic prediction accuracy through multi-level phase analysis, 2012, LCTES

[4] Selecting Software Phase Markers with Code Structure Analysis, 2006, CGO

#### Basic Block Vector Time-Quantum Approach

- Record basic block trace from the execution
- Group time quantum with similar basic block compositions (signatures) into a phase



#### **Transition Phase Issue**

 A quanta often runs across program phase boundaries



#### **Multi-level Phase Structures**

- Phases should be of a hierarchical structure
- Coarse-grain to fine-grain phases.



### **Time-Quantum-Based Approach**

- Pros:
  - Convenient for metric evaluation and processing.
- Cons:
  - Cannot precisely capture actual program phases.
  - No insights into the dynamic nature of real program phases.

#### Program-Structure-Based Approach

 Lau. et. al. used a Hierarchical Call-Loop Graph analysis technique to identify program phases from loops or functions (procedures).



#### Program-Structure-Based Approach

#### • Pros:

- Better understanding of program phases.
- Stronger associations between each program phase and its characteristics.

#### • Cons:

• Difficult to calculate a precise performance value (e.g. CPI) due to the variations of different execution runs.

#### Motivation: Human Intuition in Identifying Program Phases

- Simply view the waveform.
- Need a method to systematically and automatically identify these patterns



#### From Time-domain Waveform to Frequency-domain Spectrum

- The major phase generally dominates the performance waveform.
- Can identify major phase identification through the low-frequency spectrum.



#### **Identify the Main Program Phase**

- D the total length of the execution length
- X the occurrence number of the main spectrum
- L the length of the main program phase

$$L = D / X$$



#### **Continue Next Level Analysis Until the Major Phase's Occurrence is One**

- No Repeated Pattern
- Check the performance gap to identify the highlow phases.



## Stop if Dominant Frequency = Zero

- The time-domain waveform is almost flat
- Only one single phase.



#### **BBFDA Algorithm Summary**

- 1. Profile the target program (by execution or simulation).
- 2. Apply frequency-domain analysis on the timedomain waveform to generate the frequency spectrum.
- 3. Calculate the phase length by the main spectrum.
- 4. Scan the profiling trace to find basic blocks that match the phase length.
- 5. Check if there are minor phases in this major phase.
- 6. If yes, go to step 2 and work on the identified major phase; otherwise, the process is completed.

#### Note: Program Phases Can Be Fully Decomposed into Basic Blocks

- The transition point between any two program phases is always a branch instruction.
- There are no branch instructions within a basic block.
  - The number and types of instructions are fixed, resulting in consistent performance measures.



### For System Optimization: Identify Phase Starting Basic Block

- Follow branch instructions during program execution to identify basic blocks.
- For each program phase detected, identify the phase starting basic block.



# 1. Hierarchical Phase Information Table

 Record the phase's starting basic block, length, and performance value.



# 2. Use a Special Instruction for Hierarchical Phase Information

- Embedded in basic blocks
- Functions like an NOP
- Contains the associated phase information



#### Validation

- SPEC CPU2017
- SimpleScalar
- Comparisons

BBFDA	the proposed approach
TQ-100M	the time-quantum-based approach with 100 million instructions quanta size
TQ-1B	the time-quantum-based approach with 1 billion instructions quanta size

## Profile the Performance Value $p_b$ of a Basic Block *b* from Time Quantum

• Compute the weighted average from the performance value  $v_q$  of the time quanta q where the basic block b occurs  $n_q$  times.



- The estimation matches well with real value.
- Can be further improved using the identified phases.

## Estimate the Performance Value $p_p$ of a Program Phase *p* from Basic Blocks

• Compute the weighted average from the performance value  $p_b$  of the basic block *b* that occurs  $n_b$  times in the phase.

$$p_p = \left(\sum_b n_b p_b\right) / \left(\sum_b n_b\right)$$



#### **Estimation Error Rate**



#### **Compare Time Waveform Predictions**



#### **Test Sensitivity to Input Data**



#### **Robust to Input Data**

Error Cross Dataset 25% 20% 15% 10% 5% 0% 401.15/1102 403.9CC 10.1010 416.9010es 429.10C1 433.1011C 10.00C5 431.1811e31e30 450.501et 456.1010et 464.12641e1 464.12641e1

■Baseline ■Set1 ■Set2 ■Set3 ■Set4 ■Set5 ■Set6 ■Set7 ■Set8

### Conclusions

- Efficient Program Phase Identification: The BBFDA method effectively discerns program phases and precisely estimates performance waveforms.
- Robust Input Handling: Our approach remains resilient in the face of varying input data.
- **Time-Quantum Granularity Resolution**: Skillful avoidance of the time-quantum granularity issue.
- Comprehensive Hierarchical Phase Information: Detailed hierarchical phase information is supplied for optimal runtime adjustments.

