Security Coverage Metrics for Information Flow at the System Level

Ece Nur Demirhan Coskun**

Sallar Ahmadi-Pour[⊎]

Muhammad Hassan[⊎]*

Rolf Drechsler[⊎]*

*Cyber-Physical Systems, DFKI GmbH Institute of Computer Science, University of Bremen *ece.coskun@dfki.de

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Overview of Presentation Content

Motivation

Security aspect of modern System-on-Chip (SOC) designs, Vulnerabilities

Preliminaries

Information Flow Tracking (IFT), Completeness Driven Development, Virtual Prototypes
 Threat Model

Aim

Security Coverage Metrics for System Level Information Flow

Methodology

Metrics Definition, Metrics Implementation: SiMiT (Static + Dynamic IFT) Tool

Experimental Results

≻Car Engine Immobilizer with open source available RISC-V VP

Conclusion

Motivation

 Modern SOC desings are everywhere.

IOT Devices, combining SW, HW, microcontrollers, microprocessors, and IPs.

Seamless integration for mission critical applications. Security of modern SOC desings are becoming increasingly important.

>One bug ≈ Disastrous consequences.

Real-time requirements, susceptible to attacks!

 An Example: DoS Attacks on Roadside Units (RSU):

Disrupting communication between vehicles and/or RSUs.

- ≻Shut down the network.
- NO road status information in time!

Security Validation Technique: Information Flow Tracking

- IFT helps mitigate security vulnerabilities.
 - Information Flow Policies
 - Security Properties:
 - ➢Confidentiality
 - ≻Integrity
 - ≻Availabilitiy

- Effectiveness of IFT?
 - Accurate security property definition!
 - Ensure vulnerability detection for the targeted threat model!
- Benefits:
 - >Assist verification engineers:
 - ➢Better intuition to assess weaknesses,
 - >Understand vulnerabilities,
 - >Derive appropriate security properties.

- How can we measure?
 - Security Coverage Metrics
 - ➢Qualitatively
 - ➢Quantitatively

Virtual Prototypes (VPs)

★Golden reference ★Abstract SW models of HW ★SystemC/ AMS





1. <u>https://armkeil.blob.core.windows.net/developer/Files/pdf/white-paper/virtual-prototyping-soc-design.pdf</u>

Completeness Driven Development (CDD)

Security aspect

Ensure competeness: ____

- verify the complete behavior of the design at each level of abstraction.
- Formerly used for functional correctness^[2].



Security aware CDD concept.

[2] R. Drechsler, M. Diepenbeck, D. Große, U. Kühne, H. M. Le, J. Seiter, M. Soeken, and R. Wille, "Completeness-driven development," in International Conference on Graph Transformations, 2012, pp. 38–50.

Threat Model

Motivating Example

Availability:

- Availability: The timely access of shared resources.
- Availability issues: IPs overusing shared resources, making them inaccessible to other IPs.
- Improperly configured access control system!
- Detecting such relation is challenging without <u>automated IFT tools</u>!



A simplified SystemC model of Keyless Entry System.

Security Coverage Metrics

>Sytem level Information Flow.

≻Availability Threat Model.

- 1. Direct Signal Connectivity
- 2. Indirect Signal Connectivity
- 3. Partial Path Activation
- 4. Full Path Activation
- 5. Information Flow Rate



Security aware CDD concept.

Direct Signal Connectivity (DSC)

DSC metric determines whether a signal A and a signal B are directly, i.e. explicitly connected.



```
BUS
    . . .
   grant bt = false;
   grant nfc = false;
   if (bt request == true) {
     grant bt = true;
     write mem.write(1);
   else if (nfc request == true) {
8
9
     grant nfc = true;
10
     write mem.write(1);
11
12 else {
13
     write mem.write(0);
14 }
15 if (grant bt == true) {
     data bus out.write(bt data in);
16
17 }
18 else if (grant nfc == true) {
19
     data bus out.write(nfc data in);
20 ...
```

Code excerpt of Bus IP.

Indirect Signal Connectivity (ISC)

- ISC metric determines whether a signal A and a signal B are indirectly connected.
- Implicit Information Flow (IIF), more subtle compared to the EIF, could result in the unavailability of the IPs.

➤The IIF might occur between two modules, where one belongs to the trusted zone and the other to the untrusted zone, sharing memory.



A simplified SystemC model of Keyless Entry System.

Partial Path Activation (PPA)

- A definite flow: beyond mere connectivity; activation of paths!
- Activation of a path: signal A successfully propagates to signal B in a simulation for a given time interval.



Full Path Activation (FPA)

FPA quantifies the total path activation for the whole execution time.



Information Flow Rate (IFR)

IFR quantifies the occurrence of an information flow from a signal A to a signal B within a given time frame.



 <u>Security Properties (SPs)</u>: guarantees outputs are Always Available (AA) when needed.

 $SP=\{(SI,SO)|SI \in \{in1=HS,..\}, SO \in \{out1=AA,..\}\}$

- <u>Binding Information</u>: connects modules.
- <u>Call-Graph</u>: coordinates analysis.
- <u>Control Flow Graph(CFG)</u>: helps understanding the relationship between various statements.



- <u>Trace</u>: A log file records "visited nodes" incl. file names and line numbers (L) for each time step.
- <u>Control Flow List (CFL)</u>: added traversed nodes from the CFG's node.





- <u>Data Flow Analysis (DFA)</u>: constructs defuse, use_dep pairs.
- <u>def-use</u>: "for each defined variable, which uses may potentially utilize its values."
- <u>use-dep</u>: dependence for variables in the conditional statements of CFG blocks, where definitions in the possible succesors to the conditional statements are stored.
- <u>Data Dependency Graph (DDG)</u>: maps the relationships among variables, incl. signals, ports, variables.



- <u>Data Flow Analysis (DFA)</u>: constructs defuse, use_dep pairs.
- <u>def-use</u>: "for each defined variable, which uses may potentially utilize its values."
- <u>use-dep</u>: "for each variable in conditional statements, which variables are assigned in the succesors to the condition."
- <u>Data Dependency Graph (DDG)</u>: maps the relationships among variables, incl. signals, ports, variables.



• <u>Observed Data Dependency Graph</u>: formed using the relevant CFLs for each time steps, rather than the CFG.





 Static Taint Analysis: generates the Observed Dependency List (ODL). It begins with a tainted source and incrementally includes variables by executing a Depth First Search (DFS) that utilizes dependence data from each ODDG.



 $SP = (\{bt_enable_in = HS\}, \{grant_nfc = AA\})$

1. Direct Signal Connectivity:

- Identify EIF; find variables influenced by Secure Inputs (SI).
- Secure List of SI (SLSI): Employ forward tracing from SI node to a Secure Output (SO) node.
- Identify sensitive control variables in SLSI.
- For all child nodes of the conditional nodes with sensitive control variables, if any left-hand side variable is in SO, there is EIF.



 $SP = (\{bt_enable_in = HS\}, \{grant_nfc = AA\})$

2. Indirect Signal Connectivity:

- Identify IIF:
 - Secure List of SO: Employ backward tracing to extract assignment statements explicitly linked to AA outputs.
 - For all child nodes of the conditional nodes with sensitive control variables, if any left-hand side variable is in SLSO, there is IIF.



SP = ({bt_enable_in = HS}, {grant_nfc = AA})

3. Partial Path Activation:

ODDG is used to find activated paths for each time step.

$$FPA(HS, AA, t_1, t_2) = \frac{n_{PPA}(HS, AA, t_1, t_2)}{n_P(HS, AA)} \xrightarrow{1} 1$$

4. Full Path Activation :

Quantify the total path activation for the whole execution time of the testbench.

$$FPA(HS, AA) = \frac{n_{FPA}(HS, AA)}{n_P(HS, AA)} \xrightarrow{1}_{1}$$



 $SP = (\{bt_enable_in = HS\}, \{grant_nfc = AA\})$

5. Information Flow Rate:

ODL is scrutinized to calculate the percentage of IFR:



It happens 2 times in 10 ms : 2%



Experimental Results

Car Engine Immobilizer with open source available RISC-V VP:

- SystemC with TLM 2.0 Modeling.
- Misprioritizing the UART over the CAN ~
 - CPU delays, hindering communication with peripherals using critical tasks.
 - Usually does not impact normal use due to limited access to the ECU's debug interface.
 - However, CAN interrupt handling must be distinct from UART tasks to avoid signal interference.



The RISC-V VP model of a Car Engine Immobilizer

Experimental Results

 $SP = ({plic_uart = HS}, {SO_s = AA})$

No.	AA-tagged SOs	DSC	ISC	РРА	FPA	IFR (%)
SP_1	interrupt_can	FALSE	TRUE	1	1	$3 \cdot 10^{-4}$
SP ₂	hart_config	FALSE	TRUE	1	1	$7.79 \cdot 10^{-3}$
SP ₃	c.m.f.m	FALSE	TRUE	1	1	$7.78 \cdot 10^{-3}$

- 15 ms trace observed 196,313 samples to assess this effect.
- SiMiT identified multiple SPs influenced by UART signals, highlighting a potential impact on CAN message availability.
- For example, SP_1 failed:
 - interrupt_can; implicitly dependent through 6 paths to plic_uart via controlling variables.
 - SiMiT observed 6 of these 6 paths from plic_uart to interrupt_can were activated.
 - interrupt_can was reached by plic_uart in 6 of the observed samples.

Conclusion

Definition of Security Coverage Metrics for System Level Information Flow

- Static and Dynamic Information Flow Techniques of SiMiT
- Implementation of Security Coverage Metrics in SiMiT

>Demonstration using experiments on an open source RISC-V Case study

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