ML for Computational Lithography: Practical Recipes

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Chip Manufacturing

- Mask synthesis: layout to masks
- Lithography: <u>pattern transfer from</u> <u>mask to wafer</u> (through exposure to light)
- Wafer processing: etch, ion implantation, etc
- Packaging

Computational lithography:

mathematical and algorithmic approaches to improve the resolution attainable with lithography







ML for Lithography

- Has been popular since ~2010
 - Why: (1) ML provides "higher" modeling capability, (2) many applications are "image recognition" or "image conversion"
 - Some ML solutions are already being provided through vendor products (e.g. Synopsys, Mentor, Brion)

Motivations

- ML (for chip design and manufacturing) has its own limitations
 - Lack of benchmark and common data set
 - Difficult to analyze and debug
 - Data belongs to users; Model provided by vendors
- This talk
 - Which lithography applications are more promising with ML?
 - When training samples are sparse, do we still use ML?

ML for Lithography

- Promising applications
 - Test pattern classification
 - Etch bias model
 - OPC and ILT
- ML may not be an ideal solution in
 - Optical model
 - Hotspot
 - Assist features

Lithography Test Patterns

- Parametric patterns
 - Represented by a few geometrical parameters (e.g. width, space)
 - Easy to build and analyze
 - Cannot cover complex patterns
- Actual patterns
 - Extracted from sample layouts; can cover more complex shapes
 - Should be well classified









Test Pattern Classification

- Representation of sample patterns in parameter space → Clustering → Selection of representative patterns
- Representation parameters are important
 - Hanan grid (or Squish pattern)
 - Image parameter space (IPS): I_{max}, I_{min}, I_{slp}
 - ML features





Etch Bias Model

- Etch bias
 - Amount of under-etch (positive bias) or over-etch (negative bias)
 - Etch bias model is a key for EPC (etch proximity correction) or Retargeting



Etch Bias Model

- Current RB- or MB-models are crude and inaccurate
 - Etch process is difficult and complex to model, accurately



ML Etch Bias Model

- Even a simple MLP provides pretty good accuracy
 - Choice of MLP input parameters (e.g. local pattern densities, optical kernel signals) are important
 - Choice of regression network (for weak etch process) or classification network (for strong etch process)



Standard (Model-Based) OPC

- Runtime increases year after year
 - More masks to process
 - More polygons to correct
 - Higher resolution requested

• Given: layout patterns



• Derive: mask patterns



| Technology Node | 28nm | 22nm | 14nm | 10nm | 7nm | 5nm |
|---|------|------|------|------|------|-------|
| Production start | 2011 | 2013 | 2014 | 2016 | 2017 | 2019 |
| Average transistor density (billion/cm ²) | 1.17 | 1.63 | 2.34 | 3.75 | 6.25 | 10.71 |
| Number of critical layer masks | 18 | 24 | 33 | 37 | 47 | 66 |
| Normalized OPC runtime per layer per unit area | 1 | 1.4 | 2 | 2.7 | 4 | 5.6 |

OPC with ML

Mask bias

- Trained ML model for "Quick guess of mask bias"
 - No iterations, no simulations: extremely fast
 - But quality is not high enough
 - Practical application: ML output as initial OPC solution, provided to standard OPC: still quite fast (3 ~ 6 times)

- Challenges

- Choice of ML model (MLP, BRNN, GCN, CNN)
- Feature engineering (pattern densities, optical kernel signals)
- ML optimization & training (as usual)



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Lithography Simulation

 Uses a compact model to simulate the response of PR to <u>exposure</u> and <u>development</u>



- Optical model
 - Captures exposure

$$I(x,y) = \sum \lambda_i |\phi_i \otimes M(x,y)|^2$$

 Often uses SOCS (sum of coherent systems) approximation: already efficient (accuracy and computation time)

Resist model

Captures PEB (post-exposure bake) & development

Hotspot

- Patterns that may cause pinching (critical width), bridging (critical spacing), line end shortening, etc
 - 1. <u>Pattern matching</u> (using hotspot library) to choose candidate regions
 - "Lithography simulations" to confirm hotspot patterns through <u>PVB</u> (process variation band)





Contact/via layout

PVB

Hotspot Detection

- Hotspot detection using CNN
 - Training is difficult: sample hotspots are sparse, augmentation of samples (mirroring, flipping, etc) might help
 - Detection should be perfect; miss prediction is not allowed



Assist Features (AF)

 Extra patterns added to the mask, <u>not intended to be printed</u>, which help nearby main patterns for better printing through constructive light interference



AF Applications with ML

- CNN to predict AF map for AF insertion
 - AF insertion runtime is reduced to 1/7 (in standard OPC flow); ILT runtime is reduced by 34%
- MLP for AF printability check
- AFs are "small" features; high accuracy of AF applications with ML is not easy
- AFs are becoming integral part of ILT



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Example: Re-Fragmentation

- OPC relies on fragmentation
 - Simple rules (e.g. nominal segment length) are usually applied



- Motivation
 - Only a few (critical) segments will cause many OPC iterations
 - Discover critical segments (with ML model) → they are further divided

Re-Fragmentation with ML

• ML model: random forest classifier (RFC)

- Actual re-fragmentation
 - Each decision tree predicts 0 (non-split) or 1 (split)
 - Voting: split segment in half if sum of 1s > threshold
- Assessment
 - − RB1: nominal length = $30nm \rightarrow 7k$ segments
 - − RB2: nominal length = 15nm → 13.8k segments
 - Proposed: RB1 + re-fragmentation → 7k + 93 segments



Depth

Rule-Based Re-Fragmentation

- Same amount of data (28k segments) is used to set up a few rules
 - σ for length and 2σ for |initial EPE|

| Segment type | Length | Initial EPE |
|------------------------------|--------|-------------|
| Line-end | >25nm | >31.9nm |
| Convex | >42nm | >7.4nm |
| Concave | >40nm | >11.8nm |
| Run (adjacent to corner) | >38nm | >8.8nm |
| Run (not adjacent to corner) | >44nm | >5.6nm |



 Rule-based is worse (in max EPE) than RFC when data volume is enough

| Refragmentation | Max. EPE [nm] | #Segments |
|------------------|---------------|-----------|
| No | 3.83 | 7,000 |
| RFC (big data) | 2.42 | 7,096 |
| Rules (big data) | 3.07 | 7,163 |

RFC vs Rule-Based (in Small Data Volume)

- Sample segments are reduced: $28k \rightarrow 1.4k$
- RFC model is re-trained; rules are set up again
- Rule-based is better than RFC, this time
 - RFC is over fitted
 - Rules are less sensitive to the amount of data
 - Carefully crafted "complex rules" (with hints from RFC) can be very good

| Segment type | Length | $\begin{array}{l} \text{Initial EPE} \\ \text{if } \phi_1 \leq 0.73 \end{array}$ | $\begin{array}{l} \text{Initial EPE} \\ \text{if } \phi_1 > 0.73 \end{array}$ |
|------------------------------|--------|--|---|
| Line-end | >25nm | >29.4nm | >26.5nm |
| Convex | >42nm | >7.8nm | >7.0nm |
| Concave | >40nm | >10.2nm | >9.2nm |
| Run (adjacent to corner) | >37nm | >9.7nm | >8.7nm |
| Run (not adjacent to corner) | >44nm | >5.9nm | >5.3nm |

| Refragmentation | Max. EPE [nm] | #Segments |
|-------------------------------|---------------|-----------|
| No | 3.83 | 7,000 |
| RFC (big data) | 2.42 | 7,096 |
| Rules (big data) | 3.07 | 7,163 |
| RFC (small data) | 3.41 | 7,165 |
| Rules (small data) | 3.13 | 7,177 |
| Revised rules (small data) | 2.59 | 7,168 |

Summary

- ML is not always an ideal solution
- Rule-based (= heuristic) may be better than ML in small data volume