

Sense Leh

Tsinghua University



FEI: Fusion Processing of Sensing Energy and Information for Self-Sustainable Infrared Smart Vision System

Haijin Su, Xin Hong, Maimaiti Nazhamaiti, Ce Zhang, Li Luo, Qi Wei, Zheyu Liu, Wenjie Deng, Yongzhe Zhang, Fei Qiao

Asia South Pacific Design Automation Conference 2025 (ASP-DAC2025) Innovative Techniques for Energy-Efficient and Reliable Hardware Systems Session





Outline

- Background
- **FEI:** Fusion processing of sensing Energy and Information
- The IPC² System
- IPC_p: Information Power Coupler
- IPC_{trl}: Intelligent Power Controller
- Simulation Results
- Conclusion

Background

- Infrared smart vision systems are increasingly prevalent in the era of the Internet of Things.
 - Widely deployed on the edge
 - Always-on working
 - Sense the ambient environment
 - Perform low-complexity but frequent tasks



Security Monitoring^[1]





Unmanned Aerial Vehicle Navigation^[2]

Human Behavior Target Tracking^[3]

- Significant power consumption.
- Power-limited batteries bring huge cost to device maintenance.

Background

 Advanced low power processing architectures



 Efficient energy harvesting methods to eliminate batteries



Ultra-low-power always-on face detector^[4]

Energy-Autonomous Sensor System^[5]

Energy and Information are processed Separately

- Lower power consumption
- Higher energy efficiency
- Deeper integration

Fusion

Background

Energy and information are deeply entwined, mutually constraining and complementing each other.



FEI: Fusion processing of sensing Energy and Information

- Exploit the natural merit.
- Energy-efficient and self-sustainable.
- Enables energy harvesting and information processing on the same focal plane.

FEI: Fusion processing of sensing Energy and Information



- Simultaneous energy harvesting and low power in-pixel-computing.
- Schedule the harvested energy to complete low power NN inference.

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 Software-hardware co-design strategy to exploit the layer-wise characteristic of the computation process and circuit topology.

The IPC² System

IPC² System

Fusion processing of sensing energy and information

IPC_p

- Information-Power-Coupler
- Utilizes in-situ coupled energy to process the containing information on the same focal plane

IPC_{trl}

- Intelligent-Power-Controller
- Scheduling the harvested energy self-adaptively



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- Zero-biased PD for energy harvesting and information processing in the analog domain.
- EH pixel: Sensing and energy harvesting.
- IPC pixel: In-pixel-computing circuit.
- 1st layer of NN inference on focal plane.





- Initial stage: No target is in sight.
- EHD mode: Energy Harvesting and Detection.
- EH pixels start working, IPC pixels are off.
- Energy is accumulated to the off-chip capacitor.
- IPC_{trl}: Cold start.



- A target appears in the view.
- Stronger energy on the focal plane.
- Useful information has been detected.
- EHC mode is triggered: Energy Harvesting and Compute.
- EH pixels are working, IPC pixels are still off.



- V_{RCP} reaches V_{tar.1} : Low power in-pixel compute begins.
- EH pixels are working, IPC pixels are working.
- Harvested energy as a complementary to the storage capacitor.
- The in-pixel compute is powered by harvested energy.
- Fusion processing of sensing energy and information. 12

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- The adaptive design flow:
 - Step1: Determine the neural network layer-wise target operation voltage. $\longrightarrow V_{RCP_{tar},i}$
 - Step2: Adjust the reconfigurable main charge pump's topology.
 Stage number N
 - Step3: Improve the energy efficiency by matching impedance of interfaces.

Capacitance of each stage C_{stage}

- Step1: Determine the neural network layer-wise target operation voltage.
 - The inference energy consumption E_{Layer} for each NN layer

$$E_{Layer} = \frac{V_{Layer}^2}{R_{Load}} t_{op}$$

• The required operation voltage $V_{RCP_{tar},i}$ for each neural network layer

$$V_{RCP_{tar},i} = V_{min} + \frac{OP_{max} - OP_{current}}{OP_{max} - OP_{min}} \left(V_{max} - V_{min} \right)$$

- Lower operation voltage for layers with more operation numbers
- More energy consumption reduction
- Executed self-powered NN inference with less delay

*For more detail : reference [6]

- Step2: Adjust the reconfigurable main charge pump's topology.
- The equivalent model of two stages capacitive charge pump.
 - Driven by non-overlap oscillator.
 - Parasitic capacitors and current load are considered.

Notations	Definition	Vin	CLK1	CLK2	2 CLK1	l Vout	Load_
V _{EH}	The converted voltage from harvested energy.		0 o C ₁ _	+ Ξ + Ξ	$C_2 + \frac{1}{\overline{z}} \beta C_2$	N stages	
V _{in}	The input voltage for each stage.		αC _{1_+}	α	C₂_+	C _{storage}	
T _{RCPtar}	The required output voltage for each layer.		جَا ۲	لے م			
C _{storage}	The capacitance for energy storage.		v _{in}	Ţ	V_{in}		÷
C _{stage}	The capacitance in each stage.				(a))	
α	The parasitic parameter of the top plate of capacitor.		V _{in} ,αC₁		V_{out}		$\beta C_1 + \alpha C_2$
β	The parasitic parameter of the bottom plate of capacitor.]		
t _{oscillator}	The period of the oscillator.						γ_βC
Ν	The stage number of the charge pump.			(b)	Ŧ	•	^(c) 16

- Algorithm for transient analysis.
- Initialize and definition
 - Initial stage number:
 - $\bullet N = 0$
 - Start with CLK1 phase:
 - CLK = 0
 - Begin charge transfer:
 - $Q_{CLK2} = 0$
 - $V_{in} = V_{CLK2} = V_{EH}$ • $V_{out} = 0$

- Charge consumption by the load:
- $Q_{Load} = V_{out}C_{storage} I_{out}t_{oscillator}$
- Total capacitance at CLK1 phase:

•
$$C_{CLK1} = (\alpha + 1)C_{stage}$$

Total capacitance at CLK2 phase:

•
$$C_{CLK2} = \left(\frac{\alpha}{\alpha+\beta} + \alpha + 1\right) C_{stage}$$

Transient analysis of charge pump to get N.

while
$$V_{RCP_{tar}} < V_{RCP_{act}}$$
 do
if $CLK = 0$ then
 $Q_{in} = Q_{CLK2}$
 $V_{in} = Q_{in}C_{CLK1}$
 $V_{out} = V_{out}$
 $Q_{out} = V_{out} \left(\frac{\alpha}{\alpha+1} + \beta\right)C_{stage}$
 $V_{RCP_{act}} = V_{out} - Q_{Load}C_{storage}$
 $N + +$

else

$$Q_{CLK2} = Q_{out} + V_{in} \left(\frac{\beta}{\beta+1} + \alpha\right) C_{stage}$$

$$V_{CLK2} = Q_{CLK2} C_{CLK2}$$

$$V_{out} = V_{CLK2}$$

$$Q_{CLK2} = V_{CLK2} \left(\frac{\alpha}{\alpha+1} + \beta\right) C_{stage}$$

$$N + +$$

$$CLK = 1$$
end if
end while

CLK = 1





The topology at CLK1 / CLK2 phase.

- Step3: Improve the energy efficiency by matching impedance of interfaces.
 - The inversely proportional relationship:

$$R_{IPC_{trl},input} \propto \frac{t_{oscillator}}{NC_{stage}}$$

By adjusting $t_{oscillator}$ or C_{stage} , a proper $R_{IPC_{trl},input}$ can be achieved.

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Simulation Results

- The proposed architecture and design strategy are simulated with TSMC 180nm technology.
- The entire pixel array
 - 128×128 PDs for sensing
 - 32×32 PDs for IPC -> 1st layer of BNN inference
 - 15,360 PDs for energy harvesting
- The Compute In Memory (CIM) structure^[7]
 - Complete the computation of subsequent BNN layers
- Intelligent-power-controller (IPC_{trl})
 - Energy efficiency power management

Simulation Results

The implement of IPC_{trl}:

- Conv2 takes the highest power reduction ratio(30.57%).
- Total energy consumption of conducting a BNN in IPC² system is only 147.62nJ.
- Eliminate 25% energy consumption.



Two datasets from the OTCBVS Benchmark Dataset Collection^[8]

	Conv2	Conv2	FC1	FC2
Operation Number	4,515,840	2,654,208	276,480	960
Operation Voltage (V)	1.000	1.082	1.188	1.200
Energy / Option (fJ)	17.24	20.18	24.33	24.83
Energy @ IPC _{trl} (nJ)	77.853	53.562	6.727	0.024
Energy @ 1.2V (nJ)	112.128	65.904	6.865	0.024
Energy Reduction Ratio (%)	30.57	18.73	2.01	1

Simulation Results

	This Work	ISSCC 2023[9]	TCAS-I 2017[10]	JSSC 2020[11]
Process	180 nm	180 nm	130 nm	180 nm
Supply Voltage	1 – 1.2 V	0.9 – 1.2 V	1.2 V	1.2 V / 0.8 V
Power	350.07 nW ª	3.6 µW @ 1 fps	13.9 µW @ 230 fps	2.36 μW
Energy Efficiency	9.23 pJ / pixel / frame	55 pJ / pixel / frame	1130 pJ / pixel / frame	11.4 pJ / pixel / frame
Self-powered Frame Rate	4 fps ^b	1 fps	230 fps	15 fps
Function	Target Detection & NN Inference	Image & ND + ED ^c	Moving Object Detection	Image & MS + OS ^d
Accuracy	Self-powered NN Inference: 99.4 %	Positive ND: 85.2 % Negative ND: 86.2 %	N/A	N/A
Energy Harvesting	YES	YES	YES	NO
Energy Conversion	93.38 %	N/A	Boost: 76 % Buck: 54 %	N/A
Intelligent Power Control	YES	NO	NO	NO

^a Power consumption of IPC.

^c ND: Novelty Detection; ED: Edge Detection.

^b Self-powered frame rate for the complete neural network. ^d MS: Motion Sensing; OS: Object Segmentation. 23

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Conclusion

- A Fusion processing strategy (FEI) of sensing Energy and Information for infrared smart vision system is detailed.
 - Simultaneous energy harvesting and low power in-pixel computing
 - Utilizing in-situ coupled energy to process the containing information on the same focal plane.
- An IPC² system combines low power information-powercoupler (IPC_p) with intelligent-power-controller (IPC_{trl}) is presented.
 - The architecture demonstrates a scheduling method for deeply fused energy and information circumstances.

• A software-hardware co-design strategy is proposed.

 Considering power consumption characteristics of the computing process to determine the topology and parameters IPC_{trl}.



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Thanks for listening! Q&A

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> **Reporter : Haijin Su** Email: qiaofei@tsinghua.edu.cn

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